PLAXIS

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Material Models Manual



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Table of Contents

Chapter 1: Introduction 7

1.1 On the use of different models 7
1.2 Limitations 10

Chapter 2: Preliminaries on material modelling 15

2.1 General definitions of stress 15
2.2 General definitions of strain 17
2.3 Elastic strains 18
2.4 Undrained effective stress analysis (effective stiffness parameters) 20
2.4.1 Skempton B-parameter 23
2.4.2 Biot pore pressure coefficient αBiot 24
2.5 Undrained effective stress analysis with effective strength parameters (Undrained A) 25
2.6 Undrained effective stress analysis with undrained strength parameters (Undrained B) 26
2.7 Undrained total stress analysis with undrained parameters (Undrained C) 27
2.8 The initial pre-consolidation stress in advanced models 28
2.9 On the initial stresses 30

Chapter 3: Linear Elastic Perfectly Plastic Model (Mohr-Coulomb Model) 32

3.1 Linear Elastic Perfectly - Plastic behaviour 32
3.2 Formulation of the Mohr-Coulomb model 33
3.3 Basic parameters of the Mohr-Coulomb model 35
3.4 Advanced parameters of the Mohr-Coulomb model 40
3.5 On the use of the Mohr-Coulomb model in dynamic calculations 42

Chapter 4: The Hoek-Brown model (rock behaviour) 43

4.1 Formulation of the Hoek-Brown model 43
4.2 Conversion of Hoek-Brown to Mohr-Coulomb 46
4.3 Parameters of the Hoek-Brown model 46
4.4 On the use of the Hoek-Brown model in dynamic calculations 53

Chapter 5: The Joined Rock model (anisotropy) 55

5.1 Anisotropic elastic material stiffness matrix 56
5.2 Plastic behaviour in three directions 58
5.3 Parameters of the Joined Rock model 60
5.4 On the use of the Joined Rock model in dynamic calculations 66

Chapter 6: The Hardening Soil model (Isotropic hardening) 67

6.1 Hyperbolic relationship for standard drained triaxial test 68
6.2 Approximation of hyperbola by the Hardening Soil model 69
6.3 Plastic volumetric strain for triaxial states of stress 71
6.4 Parameters of the Hardening Soil Model 72
6.5 On the cap yield surface in the Hardening Soil model 79
6.6 State parameters in the Hardening Soil model 81
6.7 On the use of the Hardening Soil model in dynamic calculations 82

Chapter 7: The Hardening Soil model with small-strain stiffness (HSsmall) 83

7.1 Describing small-strain stiffness with a Simple Hyperbolic Law 84
7.2 Applying the Hardin-Drnevich relationship in the HS Model 85
7.3 Virgin (initial) loading vs unloading/reloading 87
7.4 Model Parameters 88
7.5 On the parameters G0 and γ0.7 91
7.6 Model Initialization 92
7.7 State parameters in the Hardening Soil model with small-strain stiffness 93
7.8 On the use of the Hardening Soil model with small-strain stiffness in dynamic calculations 93
7.9 Other differences with the Hardening Soil model 94

Chapter 8: The UBC3D-PLM model 96

8.1 Elasto-plastic behaviour and hardening rule 97
8.2 Flow rule 99
8.3 Load state during liquefaction 100
8.4 Post-liquefaction rule and cyclic mobility 102
8.5 Parameters of the UBC3D-PLM model 103
8.6 State parameters in the UBC3D-PLM model 107
8.7 On the use of the UBC3D-PLM model in dynamic calculations 109

Chapter 9: The Soft soil model 110

9.1 Isotropic states of stress and strain (σ'1 = σ'2 = σ'3) 111
9.2 Yield function 112
9.3 Parameters of the Soft Soil model 114
9.4 State parameters in the Soft Soil model 118
9.5 On the use of the Soft Soil model in dynamic calculations 118

Chapter 10: Soft Soil Creep model (time dependent behaviour) 119

10.1 Introduction 119
10.2 Basics of one-dimensional creep 120
10.3 On the variables τc and εc 121
10.4 Differential law for 1D-creep 123
10.5 Three-dimensional-model 124
10.6 Formulation of elastic 3D-strains 127
10.7 Formulation of failure condition 128
10.8 Parameters of the Soft Soil Creep model 128
10.9 State parameters in the Soft Soil Creep model 132
10.10 On the use of the Soft Soil Creep model in dynamic calculations 132
10.11 On the use of the Soft Soil Creep model in practical applications 132

Chapter 11: Modified Cam-Clay model 134

11.1 Formulation of the Modified Cam-Clay model 134
11.2 Parameters of the Modified Cam-Clay model 135
11.3 State parameters in the Modified Cam-Clay model 136
11.4 On the use of the Modified Cam-Clay model in dynamic calculations 137
11.5 Warning 137

Chapter 12: The Sekiguchi-Ohta model 138

12.1 Formulation of the Sekiguchi-Ohta model 138
12.1.1 Isotropic states of stress and strain (σ'1 = σ'2 = σ'3) 138
12.1.2 Inviscid (time-independent) formulation 139

12.1.3 Viscid (time-dependent) formulation 140
12.2 Parameters of the Sekiguchi-Ohta model 140
12.2.1 Model parameters of the inviscid model 140
12.2.2 Model parameters of the viscid model 143
12.3 State parameters in the Sekiguchi-Ohta model 144

Chapter 13: The NGI-ADP model (anisotropic undrained shear strength) 145

13.1 Formulation of the NGI-ADP model 145
13.1.1 1D model presentation 145
13.1.2 The NGI-ADP model in plane strain 146
13.1.3 The NGI-ADP model in 3D stress space 147
13.1.4 The NGI-ADP model traction criterion for interfaces in 2D 150
13.2 Parameters of the NGI-ADP model 151
13.2.1 Ratio unloading / reloading shear modulus over plane strain active shear strength (Gur/SuA) 151
13.2.2 Shear strain at failure in triaxial compression (γfC) 152
13.2.3 Shear strain at failure in triaxial extension (γfE) 152
13.2.4 Shear strain at failure in direct simple shear (γfDSS) 152
13.2.5 Reference active shear strength (su,refA) 152
13.2.6 Ratio triaxial compressive shear strength over active shear strength (suC,TX/suA) 153
13.2.7 Reference depth (yref) 153
13.2.8 Increase of shear strength with depth (su,incA) 153
13.2.9 Ratio of passive shear strength over active shear strength (sup/suA) 153
13.2.10 Ratio of direct simple shear strength over active shear strength (suDSS/suA) 153
13.2.11 Initial mobilization (T0/suA) 154
13.2.12 Poisson's ratio (ν') 155
13.3 State parameters in the NGI-ADP model 155

Chapter 14: The UDCAM-S model 157

14.1 Parameters of the UDCAM-S model 159
14.1.1 Ratio of the initial shear modulus to the degraded TXC shear strength (Gmax/τC) ..160
14.1.2 Shear strain at failure in triaxial compression (γfC) 160
14.1.3 Shear strain at failure in triaxial extension (γfE) 160
14.1.4 Shear strain at failure in direct simple shear (γfDSS) 160
14.1.5 Reference degraded TXC shear strength (τrefC) 160
14.1.6 Reference depth (yref) 161
14.1.7 Increase of degraded TXC shear strength with depth (τincC) 161
14.1.8 Ratio of the degraded TXE shear strength to the undrained TXC shear strength (τE/τC) 161
14.1.9 Ratio of the degraded DSS shear strength to the undrained TXC shear strength (τDSS/τc) 161
14.1.10 Initial mobilization (τ0/τC) 161
14.1.11 Poisson's ratio (ν') 162
14.2 State parameters in the UDCAM-S model 162
14.3 On the use of the UDCAM-S model in dynamic calculations 163

Chapter 15: The Concrete model 164

15.1 Formulation of the Concrete model 165
15.2 Strain hardening and softening 166
15.2.1 Compression 166
15.2.2 Tension 167

15.3 Time-dependency of the Concrete model ... 168
15.3.1 Strength and Stiffness ... 168
15.3.2 Plastic Deformability ... 169
15.3.3 Fracture energy ... 170
15.3.4 Viscoelastic Creep ... 171
15.3.5 Shrinkage ... 171
15.4 Parameters of the Concrete model ... 172
15.4.1 Recommended values for the parameters of the Concrete model ... 173
15.4.2 Summary of recommended parameters for Concrete model ... 176
15.5 State parameters in the Concrete model ... 178
15.6 On the use of the Concrete model in dynamic calculations ... 179
15.7 Warning ... 180

Chapter 16: Application of advanced soil models (PLAXIS 2D) ... 181

16.1 Hardening Soil model: Response in drained and undrained triaxial tests ... 181
16.2 Application of the Hardening Soil model on real soil tests ... 185
16.2.1 Triaxial Test ... 186
16.2.2 Oedometer test ... 188
16.2.3 Pressiometer test ... 190
16.2.4 Conclusions of the Application of the Hardening Soil model on real soil tests ... 193
16.3 Application of the Hardening Soil model with small-strain stiffness on real soil tests ... 194
16.4 Soft Soil Creep model : Undrained triaxial tests at different loading rates ... 197
16.5 Soft Soil Creep model: Response in one-dimensional compression test ... 201
16.6 Soft Soil model: Response in isotropic compression test ... 207
16.7 Hardening Soil model and Hardening Soil model with small-strain stiffness: Excavation in Berlin sand ... 209

Chapter 17: User-defined soil models ... 213

17.1 Introduction ... 213
17.2 Implementation of User Defined (UD) soil Models in calculations program ... 213
17.2.1 Main Functionalities UD Models ... 213
17.2.2 Using predefined subroutines from the source code ... 219
17.2.3 Definition of user-interface functions ... 219
17.2.4 Compiling the user subroutine ... 221
17.2.5 Debugging possibilities ... 222
17.3 Input of UD model parameters via user-interface ... 222

Chapter 18: Structural Behaviour ... 226

18.1 Anchors ... 226
18.2 3D Beams ... 226
18.3 2D Geogrids ... 228
18.4 3D Geogrids ... 229
18.5 2D plates ... 230
18.6 3D Plates ... 233
18.7 2D Embedded beam row ... 239
18.8 3D Embedded beam (PLAXIS 3D) ... 242

Chapter 19: Hydraulic Models ... 245

19.1 Van Genuchten model ... 245
19.2 Approximate Van Genuchten model ... 248

Chapter 20: References ... 251

Appendices 256

Appendix A: Symbols 257
Appendix B: Applicability of the material model 262
Appendix C: Modelling of embedded structures 267
Appendix D: Fortran subroutines for User-defined soil models 269

1 Introduction

The mechanical behaviour of soils and rocks may be modelled at various degrees of accuracy. Hooke's law of linear, isotropic elasticity, for example, may be thought of as the simplest available stress-strain relationship. As it involves only two input parameters, i.e. Young's modulus, E, and Poisson's ratio,ν, it is generally too crude to capture essential features of soil and rock behaviour. The linear elastic perfectly plastic model (Mohr-Coulomb) may be considered as a first order approximation of soil or rock behaviour. However, PLAXIS includes more advanced material models involving specific features such as stress-dependency of stiffness, strain-hardening / softening, memory of pre-consolidation, critical state, anisotropy, creep, swelling and shrinkage. Users are encouraged to employ the advanced models in an attempt to simulate the behaviour of soils and rocks more realistically, thereby obtaining more accurate results from their PLAXIS calculations. The use of the *SoilTest* facility may help in calibrating the corresponding model parameters. An overview of the applicability of the material models is given in Applicability of the material model (on page 262).

1.1 On the use of different models

1.1.1 *Linear Elastic model (LE)*

The Linear Elastic model is based on Hooke's law of isotropic elasticity. It involves two basic elastic parameters, i.e. Young's modulus E and Poisson's ratio ν. Although the Linear Elastic model is not suitable to model soil, it may be used to model stiff volumes in the soil, like concrete walls, or intact rock formations.

1.1.2 *Mohr-Coulomb model (MC)*

The linear elastic perfectly-plastic Mohr-Coulomb model involves five input parameters, i.e. E and ν for soil elasticity; φ and c for soil plasticity and ψ as an angle of dilatancy. This Mohr-Coulomb model represents a 'first-order' approximation of soil or rock behaviour. It is recommended to use this model for a first analysis of the problem considered. For each layer one estimates a constant average stiffness or a stiffness that increases linearly with depth. Due to this constant stiffness, computations tend to be relatively fast and one obtains a first estimate of deformations.

1.1.3 *Hardening Soil model (HS)*

The Hardening Soil model is an advanced model for the simulation of soil behaviour. As for the Mohr-Coulomb model, limiting states of stress are described by means of the friction angle, φ, the cohesion, c, and the dilatancy

angle, ψ. However, soil stiffness is described much more accurately by using three different input stiffnesses: the triaxial loading stiffness, E_{50}, the triaxial unloading stiffness, E_{ur}, and the oedometer loading stiffness, E_{oed}. As average values for various soil types, $E_{ur} \approx 3E_{50}$ and $E_{oed} \approx E_{50}$ are suggested as default settings, but both very soft and very stiff soils tend to give other ratios of E_{oed} / E_{50}, which can be entered by the user.

In contrast to the Mohr-Coulomb model, the Hardening Soil model also accounts for stress-dependency of stiffness moduli. This means that all stiffnesses increase with pressure. Hence, all three input stiffnesses relate to a reference stress, usually taken as 100 kPa (1 bar).

Besides the model parameters mentioned above, initial soil conditions, such as pre-consolidation, play an essential role in most soil deformation problems. This can be taken into account in the initial stress generation.

1.1.4 *Hardening Soil model with small-strain stiffness (HSsmall)*

The Hardening Soil model with small-strain stiffness (HSsmall) is a modification of the above Hardening Soil model that accounts for the increased stiffness of soils at small strains. At low strain levels most soils exhibit a higher stiffness than at engineering strain levels, and this stiffness varies non-linearly with strain. This behaviour is described in the HSsmall model using an additional strain-history parameter and two additional material parameters, i.e. G_0^{ref} and $\gamma_{0.7}$. G_0^{ref} is the small-strain shear modulus and $\gamma_{0.7}$ is the strain level at which the shear modulus has reduced to about 70% of the small-strain shear modulus. The advanced features of the HSsmall model are most apparent in working load conditions. Here, the model gives more reliable displacements than the HS model. When used in dynamic applications, the Hardening Soil model with small-strain stiffness also introduces hysteretic material damping.

1.1.5 *Soft Soil model (SS)*

The Soft Soil model is a Cam-Clay type model especially meant for primary compression of near normally-consolidated clay-type soils. Although the modelling capabilities of this model are generally superseded by the Hardening Soil model, the Soft Soil model is better capable to model the compression behaviour of very soft soils.

1.1.6 *Soft Soil Creep model (SSC)*

The Hardening Soil model is generally suitable for all soils, but it does not account for viscous effects, i.e. creep and stress relaxation. In fact, all soils exhibit some creep and primary compression is thus followed by a certain amount of secondary compression.

The latter is most dominant in soft soils, i.e. normally consolidated clays, silts and peat, and PLAXIS thus implemented a model under the name Soft Soil Creep model. The Soft Soil Creep model has been developed primarily for application to settlement problems of foundations, embankments, etc. For unloading problems, as normally encountered in tunnelling and other excavation problems, the Soft Soil Creep model hardly supersedes the simple Mohr-Coulomb model. As for the Hardening Soil model, proper initial soil conditions are also essential when using the Soft Soil Creep model. This also includes data on the pre-consolidation stress, as the model accounts for the effect of overconsolidation. Note that the initial overconsolidation ratio also determines the initial creep rate.

1.1.7 *Joined Rock model (JR)*

The Joined Rock model is an anisotropic elastic-plastic model, especially meant to simulate the behaviour of rock layers involving stratification and particular fault directions. Plasticity can only occur in a maximum of three shear directions (shear planes). Each plane has its own strength parameters φ and c. The intact rock is considered to behave fully elastic with constant stiffness properties E and ν. Reduced elastic properties may be defined for the stratification direction.

1.1.8 *Modified Cam-Clay model (MCC)*

The Modified Cam-Clay model is a well known model from international soil modelling literature; see for example Muir Wood (1990) (on page 254). It is meant primarily for the modelling of near normally-consolidated clay-type soils. This model has been added to PLAXIS to allow for a comparison with other codes.

1.1.9 *NGI-ADP model* GSE

The NGI-ADP model is an anisotropic undrained shear strength model. The soil shear strength is defined by means of S_u values for active, passive and direct simple shear stress states. The model may be used for onshore and offshore applications in undrained clays and silts.

1.1.10 *UDCAM-S model* GSE

The Simplified UnDrained Cyclic Accumulation Model (UDCAM-S) is an advanced model to deal with undrained soil behaviour and degradation of the strength and stiffness in cyclic loading of clay or very low permeable silty soils. The UDCAM-S model is derived from the complex UDCAM model by NGI (Andersen & Jostad, 2009 (on page 251)) with simplifications in order to be more suitable for engineering practice. The material model is based on the NGI-ADP model for the undrained behaviour of clays, implementing a pre-processing procedure called cyclic accumulation tool (See the Reference Manual - *Chapter 6 - Cyclic accumulation and optimisation tool*) to obtain the degraded parameter set based on the type of analysis the user has to perform.

1.1.11 *Sekiguchi-Ohta model* GSE

The Sekiguchi-Ohta model is a Cam-Clay type of model with anisotropic yield contour defined by K_{nc}^{0}. Two versions of the model exist: The inviscid model is a time independent model which has similarities with the Soft Soil model. The viscid model is time-dependent and has similarities with the Soft Soil Creep model. Both models have been developed in Japan. These models were previously available as user-defined models, but have become standard models in PLAXIS nowadays.

1.1.12 *Hoek-Brown model (HB)* GSE

The Hoek-Brown model is an isotropic elastic perfectly-plastic model for weathered rock based on the 2002 edition of the Hoek-Brown failure criterion. This non-linear stress-dependent criterion describes shear failure

and tensile failure by a continuous function, and is familiar to most geologists and rock engineers. Besides the elastic parameters (E and ν), the model involves practical rock parameters such as the uni-axial compressive strength of the intact rock (σ_{ci}), the Geological Strength Index (GSI), and the disturbance factor (D).

1.1.13 *UBC3D-PLM model* GSE

The UBC3D-PLM model is an advanced model for the simulation of liquefaction behaviour in dynamic applications. The UBC3D-PLM model employs two yield surfaces to guarantee a smooth transition near the mobilised friction angle. The UBC3D-PLM model uses the Mohr-Coulomb yield condition with an hardening law similar to the Hardening Soil model. For the secondary state, the UBC3D-PLM model incorporates a densification law through a second yield surface with a kinematic hardening rule based on the number of loading cycles. This correlation improves the precision of the evolution of the excess pore pressure.

The dynamic applications require a deep and extended investigation of the soil deposit. However, the UBC3D-PLM model implements a specific formulation with input parameters based on the most common tests: drained triaxial tests (CD TxC) or standard penetration tests (SPT).

1.1.14 *Concrete model* GSE

The Concrete model is an advanced elastoplastic model for concrete and shotcrete structures. It simulates the time-dependent strength and stiffness of concrete, strain hardening-softening in compression and tension as well as creep and shrinkage. The failure criterion involves a Mohr-Coulomb yield surface for deviatoric loading, which is combined with a Rankine yield surface in the tensile regime. The Concrete model employs 25 input parameters, but most of them can be derived from standard uniaxial tensile and compression tests and are generally familiar to structural engineers.

1.1.15 *Calibration of model parameters using the SoilTest facility*

The *SoilTest* facility may be used to check the performance of material models and the chosen model parameters in well defined soil lab test conditions as well as in arbitrary stress-strain conditions. In this way, users can compare the model response with real lab test data and get a feel for the accuracy at which real soil behaviour is approximated by the model. Even if a perfect match is obtained, it is good to realise that using calibrated material models in practical applications (where conditions are different than in the lab) may still lead to differences between the finite element model and reality. Nevertheless, the use of the *SoilTest* facility can help in understanding the capabilities and limitations of the material model and the influence of the model parameters.

1.2 Limitations

The PLAXIS code and its soil models have been developed to perform calculations of realistic geotechnical problems. In this respect PLAXIS can be considered as a geotechnical simulation tool. The soil models can be regarded as a qualitative representation of soil behaviour whereas the model parameters are used to quantify the soil characteristics. Although much care has been taken for the development of the PLAXIS code and its soil models, the simulation of reality remains an approximation, which implicitly involves some inevitable numerical and modelling errors. Moreover, the accuracy at which reality is approximated depends highly on the expertise

of the user regarding the modelling of the problem, the understanding of the soil models and their limitations, the selection of model parameters, and the ability to judge the reliability of the computational results.

Some of the limitations in the currently available models are listed below:

1.2.1 *Linear Elastic model*

Linear Elastic model Soil behaviour is highly non-linear and irreversible. The linear elastic model is insufficient to capture the essential features of soil. The use of the linear elastic model may, however, be considered to model strong massive structures in the soil or bedrock layers. Stress states in the linear elastic model are not limited in any way, which means that the model shows infinite strength. Be careful using this model for materials that are loaded up to their material strength.

1.2.2 *Mohr-Coulomb model*

The linear elastic perfectly-plastic Mohr-Coulomb model is a first order model that includes only a limited number of features that soil behaviour shows in reality. Although the increase of stiffness with depth can be taken into account, the Mohr-Coulomb model does neither include stress-dependency nor stress-path dependency nor strain dependency of stiffness or anisotropic stiffness. In general, effective stress states at failure are quite well described using the Mohr-Coulomb failure criterion with effective strength parameters φ' and c'. For undrained materials, the Mohr-Coulomb model may be used with the friction angle φ set to 0° and the cohesion c set to $c_u(S_u)$, to enable a direct control of undrained shear strength. In that case note that the model does not automatically include the increase of shear strength with consolidation.

1.2.3 *Hardening Soil model*

Although the Hardening Soil model can be regarded as an advanced soil model, there are a number of features of real soil behaviour the model does not include. It is a hardening model that does not account for softening due to soil dilatancy and de-bonding effects. In fact, it is an isotropic hardening model so that it models neither hysteretic and cyclic loading nor cyclic mobility. Moreover, the model does not distinguish between large stiffness at small strains and reduced stiffness at engineering strain levels. The user has to select the stiffness parameters in accordance with the dominant strain levels in the application. Last but not least, the use of the Hardening Soil model generally results in longer calculation times, since the material stiffness matrix is formed and decomposed in each calculation step.

1.2.4 *Hardening Soil model with small-strain stiffness*

As the Hardening Soil model with small-strain stiffness (HSsmall) incorporates the loading history of the soil and a strain-dependent stiffness, it can, to some extent, be used to model cyclic loading. However, it does not incorporate a gradual softening during cyclic loading, so is not suitable for cyclic loading problems in which softening plays a role. In fact, just as in the Hardening Soil model, softening due to soil dilatancy and debonding effects are not taken into account. Moreover, the HSsmall does not incorporate the accumulation of irreversible volumetric straining nor liquefaction behaviour with cyclic loading. The use of the HSsmall will generally result in calculation times that are even longer than those of the Hardening Soil model.

1.2.5 *Soft Soil model*

The same limitations (including the ones for the Soft Soil Creep model) hold in the Soft Soil model. The utilization of the Soft Soil model should be limited to the situations that are dominated by compression. It is not recommended for use in excavation problems, since the model hardly supercedes the Mohr-Coulomb model in unloading problems.

1.2.6 *Soft Soil Creep model*

All above limitations also hold true for the Soft Soil Creep model. In addition this model tends to over-predict the range of elastic soil behaviour. This is especially the case for excavation problems, including tunnelling. Care must also be taken with the generation of initial stresses for normally consolidated soils. Although it would seem logical to use OCR = 1.0 for normally consolidated soils, such use would generally lead to an over-prediction of deformations in problems where the stress level is dominated by the initial self-weight stresses. Therefore, for such problems it is recommended to use a slightly increased OCR-value to generate the initial stress state. In fact, in reality most soils tend to show a slightly increased pre-consolidation stress in comparison with the initial effective stress. Before starting an analysis with external loading it is suggested to perform a single calculation phase with a short time interval and without loading to verify the surface settlement rate based on common practice.

1.2.7 *Joined Rock model*

The Joined Rock model is a first order anisotropic model that includes a limited number of features that rock behaviour shows in reality. Plasticity can only occur in a maximum of three shear directions (shear planes). Each plane has its own shear strength parameters φ_i and c_i and tensile strengtht_i. Hence, the maximum shear stress is linearly dependent on the normal stress, and not curved as in reality. The intact rock is considered to behave fully elastic with constant stiffness properties E and νReduced elastic properties may be defined for the stratification direction. Note that failure is limited to the predefined shear plane directions. It is possible that realistic potential failure mechanisms are not captured by the model because of the elastic behaviour in any other direction than the three shear planes.

1.2.8 *Modified Cam-Clay model*

The same limitations (including those in the Soft Soil Creep model) hold in the Modified Cam-Clay model. Moreover, the Modified Cam-Clay model may allow for unrealistically high shear stresses. This is particularly the case for overconsolidated stress states where the stress path crosses the critical state line. Furthermore, the Modified Cam-Clay model may give softening behaviour for such stress paths. Without special regularization techniques, softening behaviour may lead to mesh dependency and convergence problems of iterative procedures. Moreover, the Modified Cam-Clay model cannot be used in combination with *Safety* analysis by means of phi-c reduction.

1.2.9 *NGI-ADP model* GSE

The NGI-ADP model is an undrained shear strength model particularly meant to model undrained clays and silts. It can be used in a drained or effective stress analysis, but note that the shear strength is not automatically updated with changes of effective stress. Also note that the NGI-ADP model does not include a tension cut-off.

1.2.10 *UDCAM-S model* GSE

The UDCAM-S model is an undrained shear strength model particularly meant to model undrained clays and silts under design storms. It can be used in a drained or effective stress analysis, but note that the shear strength is not automatically updated with changes of effective stress. Also note that the NGI-ADP model does not include a tension cut-off.

1.2.11 *Hoek-Brown model* GSE

The Hoek-Brown model is an isotropic continuum model particularly meant to model weathered rock. Hence, the model is not suitable for stratified or jointed rock sections with a significant anisotropic stiffness or with one or more dominant sliding directions. For such behaviour, the Joined Rock model is available.

1.2.12 *UBC3D-PLM model* GSE

The UBC3D-PLM model is designed to evaluate liquefaction in sandy soils and it implements correlations based on experimental data for this purpose. Hence, it's not advisable for static analysis. The use of UBC3D-PLM model in other dynamic applications involving sandy soils could be affected by an overdamping due to use of G_{max} in elastic unloading. This limitation can be overcome by using the Hardening Soil model with small-strain stiffnessmall.

1.2.13 *Concrete model* GSE

The Concrete model is an elastoplastic time-dependent model particularly meant to model shotcrete or concrete structures. The design approach is separately implemented in the model through two safety factor parameters in order to avoid inconsistency between the different aspects computed by the Concrete model. The user should be careful in dynamic analysis because of the time interval difference between dynamic input and shotcrete hardening. The model is not suitable for failure involving low fracture energy.

1.2.14 *Interfaces*

Interface elements are generally modelled by means of the bi-linear Mohr-Coulomb model. When a more advanced model is used for the corresponding cluster material data set, the interface element will only pick up the relevant data (c, φ, ψ, E, ν) for the Mohr-Coulomb model, as described in the Reference Manual. In such cases the interface stiffness is set equal to the elastic soil stiffness. Hence, $E = E_{ur}$where E_{ur} is stress level dependent, following a power law with E_{ur} proportional to σ_m. For the Soft Soil model, Soft Soil Creep model

and Modified Cam-Clay model the power *m* is equal to 1 and E_{ur} is largely determined by the swelling constant κ^*.

1.2.15 *Undrained behaviour*

In general, care must be taken in undrained conditions, since the effective stress path that is followed in any of the models may deviate significantly from reality. Although PLAXIS has options to deal with undrained behaviour in an effective stress analysis, the use of undrained shear strength (c_u or Su) may be preferred over the use of effective strength properties (φ' and c') in such cases. Please note that direct input on undrained shear strength does not automatically include the increase of shear strength with consolidation. If, for any reason, the user decides to use effective strength properties in undrained conditions, it is strongly recommended to check the resulting *mobilised shear strength* using the corresponding option in the PLAXIS Output program.

2 Preliminaries on material modelling

A material model is described by a set of mathematical equations that give a relationship between stress and strain. Material models are often expressed in a form in which infinitesimal increments of stress (or 'stress rates') are related to infinitesimal increments of strain (or 'strain rates'). All material models implemented in PLAXIS are based on a relationship between the effective stress rates, $\dot{\sigma}'$, and the strain rates, $\dot{\epsilon}'$. In the following section it is described how stresses and strains are defined in PLAXIS. In subsequent sections the basic stress-strain relationship is formulated and the influence of pore pressures in undrained materials is described. Later sections focus on initial conditions for advanced material models.

This Material Models Manual is a general manual for all PLAXIS programs and uses the coordinate system as used in most programs (Figure 1 (on page 15)). Please note that the PLAXIS 3D uses a different coordinate system where *z* is the vertical axis. Users should realize this when reading this manual.

2.1 General definitions of stress

Stress is a tensor which can be represented by a matrix in Cartesian coordinates:

$$\boldsymbol{\sigma} = \begin{bmatrix} \sigma_{xx} & \sigma_{xx} & \sigma_{xz} \\ \sigma_{yx} & \sigma_{yy} & \sigma_{yz} \\ \sigma_{zx} & \sigma_{zy} & \sigma_{zz} \end{bmatrix} \qquad \textit{Eq. [1]}$$

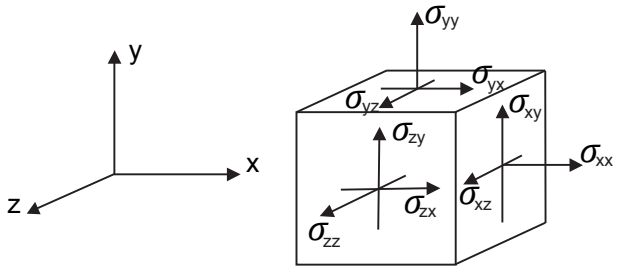


Figure 1: General three-dimensional coordinate system and sign convention for stresses

In the standard deformation theory, the stress tensor is symmetric such that $\sigma_{xy} = \sigma_{yx}$, $\sigma_{yz} = \sigma_{zy}$ and $\sigma_{zx} = \sigma_{xz}$. In this situation, stresses are often written in vector notation, which involve only six different components:

$$\underline{\sigma} = (\sigma_{xx} \;\; \sigma_{yy} \;\; \sigma_{zz} \;\; \sigma_{xy} \;\; \sigma_{yz} \;\; \sigma_{zx})^T \qquad \textit{Eq. [2]}$$

According to Terzaghi's principle, stresses in the soil are divided into effective stresses, $\underline{\sigma}'$, and pore pressures, $\underline{\sigma}_w$:

$$\underline{\sigma} = \underline{\sigma}' + \underline{\sigma}_w \qquad Eq.\ [3]$$

Pore pressures are generally provided by water in the pores. Water is considered not to sustain any shear stresses. As a result, effective shear stresses are equal to total shear stresses. Positive normal stress components are considered to represent tension, whereas negative normal stress components indicate pressure (or compression). Moreover, water is considered to be fully isotropic, so all pore pressure components are equal. Hence, pore pressure can be represented by a single value, p_w:

$$\underline{\sigma}_w = (p_w \;\; p_w \;\; p_w \;\; 0 \;\; 0 \;\; 0)^T \qquad Eq.\ [4]$$

Material models for soil and rock are generally expressed as a relationship between infinitesimal increments of effective stress and infinitesimal increments of strain. In such a relationship, infinitesimal increments of effective stress are represented by stress rates (with a dot above the stress symbol):

$$\dot{\underline{\sigma}}' = (\dot{\sigma}'_{xx} \;\; \dot{\sigma}'_{yy} \;\; \dot{\sigma}'_{zz} \;\; \dot{\sigma}_{xy} \;\; \dot{\sigma}_{yz} \;\; \dot{\sigma}_{zx})^T \qquad Eq.\ [5]$$

It is often useful to apply principal stresses rather than Cartesian stress components when formulating material models. Principal stresses are the stresses in such a coordinate system direction that all shear stress components are zero. Principal stresses are, in fact, the eigenvalues of the stress tensor. Principal effective stresses can be determined in the following way:

$$\det(\boldsymbol{\sigma} - \boldsymbol{\sigma}\mathbf{I}) = 0 \qquad Eq.\ [6]$$

where $\mathbf{I}$ is the identity matrix. This equation gives three solutions for σ', i.e. the principal effective stresses (σ'_1, σ'_2, σ'_3). In PLAXIS the principal effective stresses are arranged in algebraic order:

$$\sigma'_1 \le \sigma'_2 \le \sigma'_3 \qquad Eq.\ [7]$$

Hence, σ'_1 is the largest compressive principal stress and σ'_3 is the smallest compressive principal stress. In this manual, models are often presented with reference to the principal stress space, as indicated in Figure 2 (on page 16).

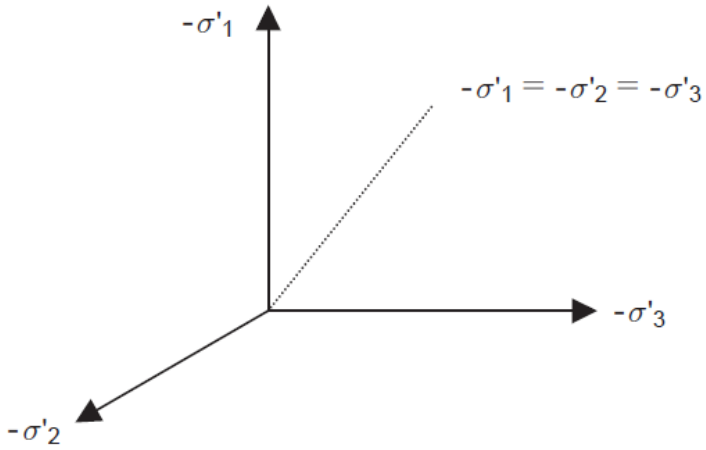


Figure 2: Principal stress space

In addition to principal stresses it is also useful to define invariants of stress, which are stress measures that are independent of the orientation of the coordinate system. Two useful stress invariants are:

$$p' = \frac{1}{3}(\sigma'_{xx} + \sigma'_{yy} + \sigma'_{zz}) \qquad Eq.\ [8]$$

$$q = \sqrt{\frac{1}{2}((\sigma'_{xx} - \sigma'_{yy})^2 + (\sigma'_{yy} - \sigma'_{zz})^2 + (\sigma'_{zz} - \sigma'_{xx})^2 + 6(\sigma^2_{xy} + \sigma^2_{yz} + \sigma^2_{zx}))} \qquad \textit{Eq. [9]}$$

where

p' = Isotropic effective stress, or mean effective stress.

q = Equivalent shear stress. It has the important property that it reduces to $q = \left| \sigma'_1 - \sigma'_3 \right|$ for triaxial stress states with $\sigma'_2 = \sigma'_3$.

Principal effective stresses can be written in terms of the invariants:

$$\sigma'_1 = p' + \frac{2}{3}q\sin(\theta - \frac{2}{3}\pi) \qquad \textit{Eq. [10]}$$

$$\sigma'_2 = p' + \frac{2}{3}q\sin(\theta) \qquad \textit{Eq. [11]}$$

$$\sigma'_3 = p' + \frac{2}{3}q\sin(\theta + \frac{2}{3}\pi) \qquad \textit{Eq. [12]}$$

in which θ is referred to as Lode 's angle (a third invariant), which is defined as:

$$\theta = \frac{1}{3}\arcsin(\frac{27}{2}\frac{J_3}{q^3}) \qquad \textit{Eq. [13]}$$

with

$$J_3 = (\sigma'_{xx} - p')(\sigma'_{yy} - p')(\sigma'_{zz} - p') - (\sigma'_{yy} - p')\sigma^2_{zx} - (\sigma'_{xx} - p')\sigma^2_{yz} - (\sigma'_{zz} - p')\sigma^2_{xy} + 2\sigma_{xy}\sigma_{yz}\sigma_{zx} \qquad \textit{Eq. [14]}$$

2.2 General definitions of strain

Strain is a tensor which can be represented by a matrix with Cartesian coordinates as:

$$\boldsymbol{\varepsilon} = \begin{bmatrix} \varepsilon_{xx} & \varepsilon_{xx} & \varepsilon_{xz} \\ \varepsilon_{yx} & \varepsilon_{yy} & \varepsilon_{yz} \\ \varepsilon_{zx} & \varepsilon_{zy} & \varepsilon_{zz} \end{bmatrix} \qquad \textit{Eq. [15]}$$

Strains are the derivatives of the displacement components, i.e. $\varepsilon_{ij} = \frac{1}{2}\left(\frac{\partial u_i}{\partial j} + \frac{\partial u_j}{\partial i}\right)$, where i and j are either x, y or z. According to the small deformation theory, only the sum of complementing Cartesian shear strain components ε_{ij} and ε_{ji} result in shear stress. This sum is denoted as the shear strain γ. Hence, instead of ε_{xy}, ε_{yx}, ε_{yz}, ε_{zy}, ε_{zx} and ε_{xz} the shear strain components γ_{xy}, γ_{yz} and γ_{zx} are used respectively. Under the above conditions, strains are often written in vector notation, which involve only six different components:

$$\underline{\varepsilon} = (\varepsilon_{xx}\ \varepsilon_{yy}\ \varepsilon_{zz}\ \gamma_{xy}\ \gamma_{yz}\ \gamma_{zx})^T \qquad \textit{Eq. [16]}$$

$$\varepsilon_{xx} = \frac{\partial}{\partial x}u_x \qquad \textit{Eq. [17]}$$

$$\varepsilon_{yy} = \frac{\partial}{\partial y}u_y \qquad \textit{Eq. [18]}$$

$$\varepsilon_{zz} = \frac{\partial}{\partial z}u_z \qquad \textit{Eq. [19]}$$

$$\gamma_{xy} = \varepsilon_{xy} + \varepsilon_{yx} = \frac{\partial}{\partial y} u_x + \frac{\partial}{\partial x} u_y \qquad \textit{Eq. [20]}$$

$$\gamma_{yz} = \varepsilon_{yz} + \varepsilon_{zy} = \frac{\partial}{\partial z} u_y + \frac{\partial}{\partial y} u_z \qquad \textit{Eq. [21]}$$

$$\gamma_{zx} = \varepsilon_{zx} + \varepsilon_{xz} = \frac{\partial}{\partial x} u_z + \frac{\partial}{\partial z} u_x \qquad \textit{Eq. [22]}$$

Similarly as for stresses, positive normal strain components refer to extension, whereas negative normal strain components indicate compression.

In the formulation of material models, where infinitesimal increments of strain are considered, these increments are represented by strain rates (with a dot above the strain symbol). notation

$$\dot{\underline{\varepsilon}} = (\dot{\varepsilon}_{xx}\ \dot{\varepsilon}_{yy}\ \dot{\varepsilon}_{zz}\ \dot{\gamma}_{xy}\ \dot{\gamma}_{yz}\ \dot{\gamma}_{zx})^T \qquad \textit{Eq. [23]}$$

In analogy to the invariants of stress, it is also useful to define invariants of strain. A strain invariant that is often used is the volumetric strain, ε_v, which is defined as the sum of all normal strain components in a standard calculation according to small deformation theory:

$$\varepsilon_v = \varepsilon_{xx} + \varepsilon_{yy} + \varepsilon_{zz} = \varepsilon_1 + \varepsilon_2 + \varepsilon_3 \qquad \textit{Eq. [24]}$$

In *Updated mesh* calculations the volumetric strain is calculated as:

$$\varepsilon_v = \varepsilon_{xx} + \varepsilon_{yy} + \varepsilon_{zz} + \varepsilon_{xx}\varepsilon_{yy} + \varepsilon_{xx}\varepsilon_{zz} + \varepsilon_{yy}\varepsilon_{zz} + \varepsilon_{xx}\varepsilon_{zz}\varepsilon_{yy}\varepsilon_{zz} \qquad \textit{Eq. [25]}$$

The volumetric strain is defined as negative for compaction and as positive for dilatancy.

Another invariant is the deviatoric strain *(ε_q)*, which is calculated as:

$$\varepsilon_q = \sqrt{\frac{2}{9}\left[(\varepsilon_{xx} - \varepsilon_{yy})^2 + (\varepsilon_{yy} - \varepsilon_{zz})^2 + (\varepsilon_{zz} - \varepsilon_{xx})^2 + \frac{1}{3}(\gamma^2_{xy} + \gamma^2_{yz} + \gamma^2_{zx})\right]} \qquad \textit{Eq. [26]}$$

For triaxial conditions i.e. $\varepsilon_2 = \varepsilon_3$ the deviatoric strain, reduces to:

$$\varepsilon_q = \frac{2}{3} \mid \varepsilon_1 - \varepsilon_3 \mid \qquad \textit{Eq. [27]}$$

where ε_1 and ε_3 are the major and minor principal strains components respectively. Furthermore, when volumetric strains are negligible ($\varepsilon_v = 0$), then $\varepsilon_3 = -1 / 2\varepsilon_1$, so $\varepsilon_q = \mid \varepsilon_1 \mid$

For elastoplastic models, as used in PLAXIS, strains are decomposed into elastic and plastic components:

$$\underline{\varepsilon} = \varepsilon^e + \varepsilon^p \qquad \textit{Eq. [28]}$$

Throughout this manual, the superscript *e* will be used to denote elastic strains and the superscript *p* will be used to denote plastic strains.

2.3 Elastic strains

Material models for soil and rock are generally expressed as a relationship between infinitesimal increments of effective stress ('effective stress rates') and infinitesimal increments of strain ('strain rates'). This relationship may be expressed in the form:

$$\dot{\underline{\sigma}}' = \mathbf{M}\dot{\varepsilon} \qquad \textit{Eq. [29]}$$

where **M** is a material stiffness matrix. Note that in this type of approach, pore-pressures are explicitly excluded from the stress-strain relationship.

The simplest material model in PLAXIS is based on Hooke's law for isotropic linear elastic behaviour. This model is available under the name Linear Elastic model, but it is also the basis of other models. Hooke's law can be given by the equation:

$$\begin{bmatrix} \dot{\sigma}_{xx}' \\ \dot{\sigma}_{yy}' \\ \dot{\sigma}_{zz}' \\ \dot{\sigma}_{xy}' \\ \dot{\sigma}_{yz}' \\ \dot{\sigma}_{zx}' \end{bmatrix} = \frac{E'}{(1-2\nu')(1+\nu')} \begin{bmatrix} 1-\nu' & \nu' & \nu' & 0 & 0 & 0 \\ \nu' & 1-\nu' & \nu' & 0 & 0 & 0 \\ \nu' & \nu' & 1-\nu' & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{2}-\nu' & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{1}{2}-\nu' & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{1}{2}-\nu' \end{bmatrix} \begin{bmatrix} \dot{\varepsilon}_{xx}' \\ \dot{\varepsilon}_{yy}' \\ \dot{\varepsilon}_{zz}' \\ \dot{\varepsilon}_{xy}' \\ \dot{\varepsilon}_{yz}' \\ \dot{\varepsilon}_{zx}' \end{bmatrix} \qquad \textit{Eq. [30]}$$

The elastic material stiffness matrix is often denoted as $\mathbf{D}^e$. Two parameters are used in this model, the effective Young's modulus, E', and the effective Poisson's ratio, ν'. In the remaining part of this manual effective parameters are denoted without dash ('), unless a different meaning is explicitly stated. The symbols E and ν are sometimes used in this manual in combination with the subscript *ur* to emphasize that the parameter is explicitly meant for unloading and reloading. A stiffness modulus may also be indicated with the subscript *ref* to emphasize that it refers to a particular reference level (y_{ref})

According to Hooke's law, the relationship between Young's modulus E and other stiffness moduli, such as the shear modulus G, the bulk modulus K, and the oedometer modulus E_{oed}, is given by:

$$G = \frac{E}{2(1+\nu)} \qquad a)$$

$$K = \frac{E}{3(1-2\nu)} \qquad b) \qquad \textit{Eq. [31]}$$

$$E_{oed} = \frac{(1-\nu)E}{(1-2\nu)(1+\nu)} \qquad c)$$

Using these auxiliary stiffness parameters, Hooke's law can be presented in an alternative form as:

$$\begin{bmatrix} \dot{p}' \\ \dot{q} \end{bmatrix} = \begin{bmatrix} K & 0 \\ 0 & 3G \end{bmatrix} \begin{bmatrix} \dot{\varepsilon}_v \\ \dot{\varepsilon}_q \end{bmatrix} \qquad \textit{Eq. [32]}$$

During the input of material parameters for the Linear Elastic model or the Mohr-Coulomb model the values of G and E_{oed} are presented as auxiliary parameters (alternatives), calculated from Eq. [31]. Note that the alternatives are influenced by the input values of E and ν. Entering a particular value for one of the alternatives G or E_{oed} results in a change of the E modulus, while ν remains the same.

It is possible for the Linear Elastic model and the Mohr-Coulomb model to specify a stiffness that varies linearly with depth. This can be done by entering a value for E_{inc} which is the increment of stiffness per unit of depth, as indicated in Eq. [33]

Together with the input of E_{inc} the input of y_{ref} becomes relevant. Above y_{ref} the stiffness is equal to E_{ref}. Below the stiffness is given by:

$$E(y) = E_{ref} + (y_{ref} - y)E_{inc} \qquad y < y_{ref} \qquad \textit{Eq. [33]}$$

Note:

The Linear Elastic model is usually inappropriate to model the highly non-linear behaviour of soil, but it is of interest to simulate structural behaviour, such as thick concrete walls or plates, for which strength properties are usually very high compared with those of soil. For these applications, the Linear Elastic model will often be selected together with *Non-porous* drainage type in order to exclude pore pressures from these structural elements.

2.4 Undrained effective stress analysis (effective stiffness parameters)

In PLAXIS it is possible to specify undrained behaviour in an effective stress analysis using effective model parameters. This is achieved by identifying the type of material behaviour (*Drainage type*) of a soil layer as *Undrained (A)* or *Undrained (B)* (Undrained effective stress analysis with effective strength parameters (Undrained A) (on page 25) and Undrained effective stress analysis with undrained strength parameters (Undrained B) (on page 26)). In this section, it is explained how PLAXIS deals with this special option.

The presence of pore pressures in a soil body, usually caused by water, contributes to the total stress level. According to Terzaghi's principle, total stresses vector notationσ can be divided into effective stresses $\underline{\sigma}'$, active pore pressure p_{active} and pore water pressures p_w (see also Eq. [3]). However, water is supposed not to sustain any shear stress, and therefore the effective shear stresses are equal to the total shear stresses:

$$\underline{\sigma} = \underline{\sigma}' p_{active} \qquad \textit{Eq. [34]}$$

where,

$$m = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \text{ and } p_{active} = \alpha_{Biot} S_{eff} p_w \qquad \textit{Eq. [35]}$$

$$\sigma_{xx} = \sigma'_{xx} + \alpha_{Biot} S_{eff} p_w \qquad \textit{Eq. [36]}$$

$$\sigma_{yy} = \sigma'_{yy} + \alpha_{Biot} S_{eff} p_w \qquad \textit{Eq. [37]}$$

$$\sigma_{zz} = \sigma'_{zz} + \alpha_{Biot} S_{eff} p_w \qquad \textit{Eq. [38]}$$

$$\sigma_{xy} = \sigma'_{xy}$$
$$\sigma_{yz} = \sigma'_{yz} \qquad \textit{Eq. [39]}$$
$$\sigma_{zx} = \sigma'_{zx}$$

where

α_{Biot} = Biot's pore pressure coefficient.
S_{eff} = Effective degree of saturation.

Considering incompressible grains, Biot's coefficient α_{Biot} is equal to unity ($\alpha_{Biot} = 1$). The situation of compressible grains or compressible solid material ($\alpha_{Biot} < 1$) is explained in more detail at the end of this section.

Note that, similar to the total and the effective stress components, p_w is considered negative for pressure.

The product $\alpha_{Biot} S_{eff} p_w$ is termed 'Active pore pressure', p_{active} in PLAXIS. A further distinction is made between steady state pore stress, p_{steady}, and excess pore stress, p_{excess}:

$$p_w = p_{setady} + p_{excess} \qquad \textit{Eq. [40]}$$

Steady state pore pressures are considered to be input data, i.e. generated on the basis of phreatic levels or by means of a groundwater flow calculation. Excess pore pressures are generated during plastic calculations for the case of undrained (A) or (B) material behaviour or during a consolidation analysis. Undrained material behaviour and the corresponding calculation of excess pore pressures are described below.

Since the time derivative of the steady state component equals zero, it follows:

$$\dot{p}_w = \dot{p}_{excess} \qquad \textit{Eq. [41]}$$

Hooke's law can be inverted to obtain:

$$\begin{bmatrix} \dot{\varepsilon}^e_{xx} \\ \dot{\varepsilon}^e_{yy} \\ \dot{\varepsilon}^e_{zz} \\ \dot{\gamma}^e_{xy} \\ \dot{\gamma}^e_{yz} \\ \dot{\gamma}^e_{zx} \end{bmatrix} = \frac{1}{E'} \begin{bmatrix} 1 & -\upsilon' & -\upsilon' & 0 & 0 & 0 \\ -\upsilon' & 1 & -\upsilon' & 0 & 0 & 0 \\ -\upsilon' & -\upsilon' & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2+2\upsilon' & 0 & 0 \\ 0 & 0 & 0 & 0 & 2+2\upsilon' & 0 \\ 0 & 0 & 0 & 0 & 0 & 2+2\upsilon' \end{bmatrix} \begin{bmatrix} \dot{\sigma}'_{xx} \\ \dot{\sigma}'_{yy} \\ \dot{\sigma}'_{zz} \\ \dot{\sigma}'_{xy} \\ \dot{\sigma}'_{yz} \\ \dot{\sigma}'_{zx} \end{bmatrix} \qquad \textit{Eq. [42]}$$

Substituting Eq. [39] gives:

$$\begin{bmatrix} \dot{\varepsilon}^e_{xx} \\ \dot{\varepsilon}^e_{yy} \\ \dot{\varepsilon}^e_{zz} \\ \dot{\gamma}^e_{xy} \\ \dot{\gamma}^e_{yz} \\ \dot{\gamma}^e_{zx} \end{bmatrix} = \frac{1}{E'} \begin{bmatrix} 1 & -\upsilon' & -\upsilon' & 0 & 0 & 0 \\ -\upsilon' & 1 & -\upsilon' & 0 & 0 & 0 \\ -\upsilon' & -\upsilon' & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2+2\upsilon' & 0 & 0 \\ 0 & 0 & 0 & 0 & 2+2\upsilon' & 0 \\ 0 & 0 & 0 & 0 & 0 & 2+2\upsilon' \end{bmatrix} \begin{bmatrix} \dot{\sigma}_{xx} - \alpha_{Biot}\dot{p}_w \\ \dot{\sigma}_{yy} - \alpha_{Biot}\dot{p}_w \\ \dot{\sigma}_{zz} - \alpha_{Biot}\dot{p}_w \\ \dot{\sigma}'_{xy} \\ \dot{\sigma}'_{yz} \\ \dot{\sigma}'_{zx} \end{bmatrix} \qquad \textit{Eq. [43]}$$

Considering slightly compressible water, the rate of excess pore pressure is written as:

$$\dot{p}_{excess} = \frac{a_{biot}\dot{\varepsilon}_v}{nC_w + (a_{biot} - n)C_s} \qquad \textit{Eq. [44]}$$

$$C_w = \frac{1}{k_w} \qquad \textit{Eq. [45]}$$

$$C_s = \frac{1}{k_s} \qquad \textit{Eq. [46]}$$

in which K_w is the bulk modulus of the water, K_s is the bulk modulus of the solid material, C_w is the compressibility of the water, C_s is the compressibility of the solid material and n is the soil porosity.

$$n = \frac{e_0}{1 - e_0} \qquad \textit{Eq. [47]}$$

where e_0 is the initial void ratio as specified in the general soil properties.

The inverted form of Hooke's law may be written in terms of the total stress rates and the undrained parameters E_u and ν_u:

$$\begin{bmatrix} \dot{\varepsilon}^e_{xx} \\ \dot{\varepsilon}^e_{yy} \\ \dot{\varepsilon}^e_{zz} \\ \dot{\gamma}^e_{xy} \\ \dot{\gamma}^e_{yz} \\ \dot{\gamma}^e_{zx} \end{bmatrix} = \frac{1}{E_u} \begin{bmatrix} 1 & -\upsilon_u & -\upsilon_u & 0 & 0 & 0 \\ -\upsilon_u & 1 & -\upsilon_u & 0 & 0 & 0 \\ -\upsilon_u & -\upsilon_u & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2+2\upsilon_u & 0 & 0 \\ 0 & 0 & 0 & 0 & 2+2\upsilon_u & 0 \\ 0 & 0 & 0 & 0 & 0 & 2+2\upsilon_u \end{bmatrix} \begin{bmatrix} \dot{\sigma}'_{xx} \\ \dot{\sigma}'_{yy} \\ \dot{\sigma}'_{zz} \\ \dot{\sigma}'_{xy} \\ \dot{\sigma}'_{yz} \\ \dot{\sigma}'_{zx} \end{bmatrix} \qquad \textit{Eq. [48]}$$

where:

$$E_u = 2G(1+\upsilon_u);$$
$$\upsilon_u = \frac{3\upsilon' + \alpha_{Biot} B(1-2\upsilon')}{3 - \alpha_{Biot} B(1-2\upsilon')} \qquad \textit{Eq. [49]}$$
$$B = \frac{\alpha_{Biot}}{\alpha_{Biot} + n\left(\frac{K'}{K_w} + \alpha_{Biot} - 1\right)}$$

where B is Skempton's B-parameter.

Hence, the special option for undrained behaviour in PLAXIS (*Undrained (A)* or *Undrained (B)*) is such that the effective parameters G and ν' are transformed into undrained parameters E_u and ν_u according to Eq. [49] . Note that the index u is used to indicate auxiliary parameters for undrained soil. Hence, E_u and ν_u should not be confused with E_{ur} and ν_{ur} as used to denote unloading / reloading.

Fully incompressible behaviour is obtained for $\nu_u = 0.5$. However, taking $\nu_u = 0.5$ leads to singularity of the stiffness matrix. In fact, water is not fully incompressible, but a realistic bulk modulus for water is very large. In order to avoid numerical problems caused by an extremely low compressibility, ν_u is, by default, taken as 0.495, which makes the undrained soil body slightly compressible. In order to ensure realistic computational results, the bulk modulus of the water must be high compared with the bulk modulus of the soil skeleton, i.e. $K_w >> n\,K'$. This condition is sufficiently ensured by requiring $\nu' \leq 0.35$.

Consequently, for material behaviour *Undrained (A)* or *Undrained (B)*, a bulk modulus for water is automatically added to the stiffness matrix. The bulk modulus of water is obtained in three ways: automatically from Eq. [50] (*Standard*), automatically but by specifying the Skempton's B-parameter (*Manual - Stiffness dependent K_w*) and manually by directly specifying K_w and α_{Biot} (*Manual - Constant K_w*).

$$\frac{K_w}{n} = \frac{3(\upsilon_u - \upsilon')}{(1-2\upsilon_u)(1+\upsilon')} \quad K' = \frac{0.495 - \upsilon'}{1+\upsilon'} 300K' \geq 30K' \,(\textit{For}\ \alpha_{Biot} = 1) \qquad \textit{Eq. [50]}$$

Note: In the UBC3D-PLM model, the implicit Poisson's ratio (ν') is defined based on the elastic bulk modulus K and the elastic shear modulus G at the current stress state, $\nu' = (3K - 2G)/(6K + 2G)$. For this reason, the value follows the evolution of the stiffnesses and it is not constant.

Hence, K_w / n is larger than $30K'$, at least for $\nu' \leq 0.35$ and $\alpha_{Biot} = 1$. The bulk stiffness of water K_w, calculated in this way, is a numerical value related to the soil stiffness. It is lower than or equal to the real bulk stiffness of pure water, K_w^0 ($2 \cdot 10^6$ kN/m^2). In retrospect it is worth mentioning here a review about the Skempton B-parameter.

2.4.1 *Skempton B-parameter*

When the *Drainage type* is set to *Undrained (A)* or *Undrained (B)*, PLAXIS automatically assumes an implicit undrained bulk modulus, K_u, for the soil as a whole (soil skeleton + water) and distinguishes between total stress rates, effective stress rates and rates of excess pore pressure:

$$Total\ stress: \qquad \dot{p} = K_u \dot{\varepsilon}_v \qquad Eq.\ [51]$$

$$Excess\ pore\ pressure: \qquad \dot{p}_{excess} = B\dot{p} = \frac{\alpha_{biot}\dot{\varepsilon}_v}{nC_w + (\alpha_{biot} - n)C_s} \qquad Eq.\ [52]$$

$$Effective\ stress: \qquad \dot{p}' = (1 - \alpha_{Biot} B)\dot{p} = K'\dot{\varepsilon}_v \qquad Eq.\ [53]$$

Note that for *Undrained (A)* or *Undrained (B)* effective stiffness parameters should be entered in the material data set, i.e. E' and ν' and not E_u and ν_u, or the respective stiffness parameters in advanced models; the latter should be done for *Undrained (C)* behaviour in a total stress analysis (Undrained total stress analysis with undrained parameters (Undrained C) (on page 27)). The undrained bulk modulus is automatically calculated by PLAXIS using Hooke's law of elasticity:

$$K_u = \frac{2G(1 + \nu_u)}{3(1 - 2\nu_u)} \quad where \quad G = \frac{E'}{2(1 + \nu')} \qquad Eq.\ [54]$$

When using the *Standard* option, $\nu_u = 0.495$ and $\alpha_{Biot} = 1$, whereas when using the *Manual* option with input of Skempton's B-parameter (*Manual - Stiffness dependent* K_w) or Biot's pore pressure coefficient (*Manual - Constant* K_w), ν_u is calculated as:

$$\nu_u = \frac{3\nu' + \alpha_{Biot} B(1 - 2\nu')}{3 - \alpha_{Biot} B(1 - 2\nu')} \qquad Eq.\ [55]$$

If the soil is only partially saturated, the pores contain both air and water and the equivalent bulk modulus of the pore fluid K_w^{unsat} is expected to be much smaller compared to that of pure water, in the case of fully saturated soil K_w. PLAXIS assumes a constant gas pressure i.e. air is always drained, the drainage type of soil only relates to the drainage type of liquid water. Excess pore pressure change will therefore depend on the bulk modulus of liquid water and the surface tension (capillary effect). This assumption allows to establish the following rigorous relationship for the unsaturated bulk modulus of the pore fluid:

$$K_w^{unsat} = \frac{K_w}{1 + \frac{K_w}{S_w}\left(-\frac{\partial S_w}{\partial p_w}\right)} \qquad Eq.\ [56]$$

where is the derivative of saturation w.r.t. pore water pressure (suction), i.e. the slope of water retention curve

The value of Skempton's B-parameter is calculated from the ratio of the bulk stiffnesses of the soil skeleton and the pore fluid, as already defined in Eq. [50]:

$$B = \frac{\alpha_{Biot}}{\alpha_{Biot} + n\left(\frac{K'}{K_w} + \alpha_{Biot} - 1\right)} \qquad Eq.\ [57]$$

The rate of excess pore pressure is calculated from the (small) volumetric strain rate, according to:

$$\dot{p}_{excess} = \frac{\alpha_{Biot}\dot{\varepsilon}_v}{nC_w + (\alpha_{Biot} - n)C_s} \qquad Eq.\ [58]$$

The types of elements used in PLAXIS are sufficiently adequate to avoid mesh locking effects for nearly incompressible materials.

This special option to model undrained material behaviour on the basis of effective model parameters is available for most material models in PLAXIS. This enables undrained calculations to be executed with effective stiffness parameters, with explicit distinction between effective stresses and (excess) pore pressures. However, shear induced (excess) pore pressure may not be sufficiently included.

Such an analysis requires effective soil parameters and is therefore highly convenient when such parameters are available. For soft soil projects, accurate data on effective parameters may not always be available. Instead, in situ tests and laboratory tests may have been performed to obtain undrained soil parameters. In such situations measured undrained Young's moduli can be easily converted into effective Young's moduli based on Hooke's law:

For advanced models there is no such direct conversion possible. In that case it is recommended to estimate the required effective stiffness parameter from the measured undrained stiffness parameter, then perform a simple undrained test to check the resulting undrained stiffness and adapt the effective stiffness if needed. The *Soil test* facility (Reference Manual) may be used as a convenient tool to perform such test.

2.4.2 *Biot pore pressure coefficient α_{Biot}*

In general, for geotechnical applications, the compressibility of the soil skeleton is much higher than the compressibility of the individual grains, so deformations of the grains themselves can be ignored. However, in the case of very deep soil layers at very high pressures, the stiffness of the soil or rock matrix comes close to the stiffness of the solid material of which the soil grains or the rock is composed of, and, therefore, the compressibility of the solid material cannot be ignored. This has consequences for the division of total stress into effective stress and pore pressure. Considering compressible solid material, Terzaghi's effective stress definition changes into:

$$\underline{\sigma}' = \underline{\sigma} - \alpha_{biot} S_{eff}\, \underline{m}\, p_w \qquad Eq.\ [59]$$

Where α_{Biot} is Biot's pore pressure coefficient, S_{eff} is the effective degree of saturation, $\underline{m}$ is a vector with unity values (1) for the normal components and 0-values for the shear components, and p_w is the pore water pressure. The alpha coefficient is defined as:

$$\alpha_{biot} = 1 - \frac{K'}{K_s} \qquad Eq.\ [60]$$

Where K' is the effective bulk modulus of the soil matrix and K_s is the bulk modulus of the solid material. Indeed, for incompressible solid material ($K_s = \infty$) Terzaghi's original stress definition is retained. A lower value of α_{Biot}

implies that for a given value of total stress and pore water pressure, the resulting effective stress is higher than when considering incompressible solid material (α_{Biot} *=1*).

In the case of undrained soil behaviour (*Undrained A* or *B* in), Biot's pore pressure coefficient also affects the undrained Poisson's ratio ν_u that is automatically calculated by based on a manual input of K_w parameter (see Eq. Eq. [49]).

The default value of Biot's pore pressure coefficient is 1.0 (*Standard* and *Manual - Stiffness dependent* K_w option), but users may change this value in the range of [0.001, 1.0] for the *Manual - Constant* K_w option.

2.5 Undrained effective stress analysis with effective strength parameters (*Undrained A*)

In principle, undrained effective stress analysis as described in Undrained effective stress analysis (effective stiffness parameters) (on page 20) can be used in combination with effective strength parameters φ' and c' to model the material's undrained shear strength (*Undrained (A)*). In this case, the development of the pore pressure plays a crucial role in providing the right effective stress path that leads to failure at a realistic value of undrained shear strength (c_u or s_u). However, note that most soil models are not capable of providing the right effective stress path in undrained loading. As a result, they will produce the wrong undrained shear strength if the material strength has been specified on the basis of effective strength parameters. Another problem is that for undrained materials effective strength parameters are usually not available from soil investigation data. In order to overcome these problems, some models allow for a direct input of undrained shear strength. This approach is described in Undrained effective stress analysis with undrained strength parameters (Undrained B) (on page 26).

If the user wants to model the material strength of undrained materials using the effective strength parameters φ' and c', this can be done in PLAXIS in the same way as for drained materials. However, in this case the *Drainage type* must be set to *Undrained (A)*. As a result, PLAXIS will automatically add the stiffness of water to the stiffness matrix (see Undrained effective stress analysis (effective stiffness parameters) (on page 20)) in order to distinguish between effective stresses and (excess) pore pressures (= effective stress analysis). The advantage of using effective strength parameters in undrained loading conditions is that after consolidation a qualitatively increased shear strength is obtained, although this increased shear strength could also be quantitatively wrong, for the same reason as explained before.

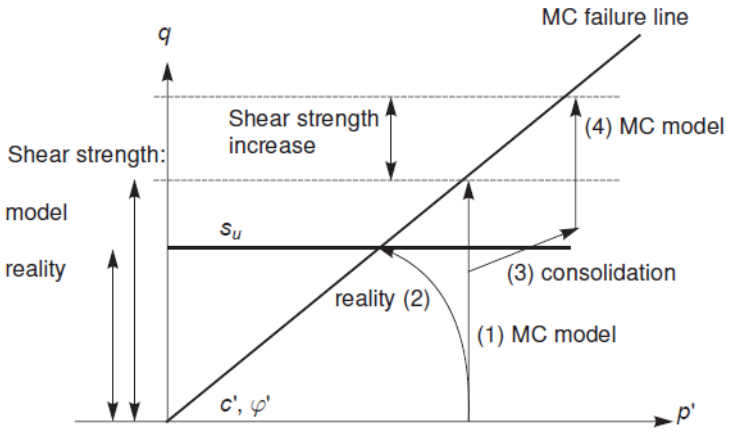


Figure 3: Illustration of stress paths; reality vs Mohr-Coulomb model

Undrained effective stress analysis (effective stiffness parameters) (on page 20) illustrates an example using the Mohr-Coulomb model. When the *Drainage type* is set to *Undrained (A)*, the model will follow an effective stress path where the mean effective stress, *p'*, remains constant all the way up to failure (1). It is known that especially soft soils, like normally consolidated clays and peat, will follow an effective stress path in undrained loading where *p'* reduces significantly as a result of shear induced pore pressure (2). As a result, the maximum deviatoric stress that can be reached in the model is over-estimated in the Mohr-Coulomb model. In other words, the mobilised shear strength in the model supersedes the available undrained shear strength.

If, at some stress state, the soil is consolidated, the mean effective stress will increase (3). Upon further undrained loading with the Mohr-Coulomb model, the observed shear strength will be increased (4) compared to the previous shear strength, but this increased shear strength may again be unrealistic, especially for soft soils.

On the other hand, advanced models do include, to some extent, the reduction of mean effective stress in undrained loading, but even when using advanced models it is generally advised to check the mobilised shear strength in the Output program against the available (undrained) shear strength when this approach is followed.

Note that whenever the *Drainage type* parameter is set to *Undrained (A)*, effective values must be entered for the stiffness parameters (Young's modulus E' and Poisson ratio ν' in case of the Mohr-Coulomb model or the respective stiffness parameters in the advanced models).

Care must be taken when using *Undrained (A)* together with a non-zero dilatancy angle ψ. The use of a positive dilatancy angle may lead to unrealistically large tensile pore stresses and, as a result, an unrealistically large shear strength. The use of a negative dilatancy angle may lead to unrealistically high pore pressure and unrealistic liquefaction type of behaviour. Hence, for *Undrained (A)* it is recommended to use $\psi = 0$.

2.6 Undrained effective stress analysis with undrained strength parameters (*Undrained B*)

For undrained soil layers with a known undrained shear strength profile, PLAXIS offers for some models the possibility of an undrained effective stress analysis, as described in Undrained effective stress analysis (effective stiffness parameters) (on page 20), with direct input of the undrained shear strength, i.e. setting the friction

angle to zero and the cohesion equal to the undrained shear strength ($\varphi = \varphi_u = 0°$; $c = s_u$) (*Drainage type* = *Undrained (B)*). Also in this case, distinction is made between pore pressures and effective stresses. Although the pore pressures and effective stress path may not be fully correct, the resulting undrained shear strength is not affected, since it is directly specified as an input parameter.

The option to perform an undrained effective stress analysis with undrained strength properties is only available for the Mohr-Coulomb model, the Hardening Soil model, the Hardening Soil model with small-strain stiffnessmall and the NGI-ADP model. Since most soils show an increasing shear strength with depth, it is possible to specify the increase per unit of depth in PLAXIS in the **Advanced** subtree in the **Parameters** tabsheet of the **Soil** window.

Note that if the Hardening Soil model or the Hardening Soil model with small-strain stiffnessmall is used with $\varphi = 0°$, the stiffness moduli in the model are no longer stress-dependent and the model exhibits no compression hardening, although the model retains its separate unloading-reloading modulus and shear hardening. Also note that a direct input of undrained shear strength does not automatically give the increase of shear strength with consolidation.

Further note that whenever the *Drainage type* parameter is set to *Undrained (B)*, effective values must be entered for the stiffness parameters (Young's modulus E' and Poisson ratio ν' in case of the Mohr-Coulomb model or the respective stiffness parameters in the advanced models).

2.7 Undrained total stress analysis with undrained parameters (*Undrained C*)

If, for any reason, it is desired not to use the *Undrained (A)* or *Undrained (B)* options in PLAXIS to perform an undrained effective stress analysis, one may simulate undrained behaviour using a conventional total stress analysis with all parameters specified as undrained. In that case, stiffness is modelled using an undrained Young's modulus E_u and an undrained Poisson ratio ν_u, and strength is modelled using an undrained shear strength s_u and $\varphi = \varphi_u = 0°$. Typically, for the undrained Poisson ratio a value close to 0.5 is selected (between 0.495 and 0.499). A value of 0.5 exactly is not possible, since this would lead to singularity of the stiffness matrix.

In PLAXIS it is possible to perform a total stress analysis with undrained parameters if the Mohr-Coulomb model or the NGI-ADP model is used. In this case, one should select *Undrained (C)* as the *Drainage type*. The disadvantage of the undrained total stress analysis is that no distinction is made between effective stresses and pore pressures. Hence, all output referring to effective stresses should now be interpreted as total stresses and all pore pressures are equal to zero.

Note that a direct input of undrained shear strength does not automatically give the increase of shear strength with consolidation. In fact, it does not make sense to perform a consolidation analysis since there are no pore pressures to consolidate. Also note that the K_0-value to generate initial stresses refers to total stresses rather than effective stresses in this case. This type of approach is not possible for most advanced models.

2.7.1 Overview of models and allowable drainage types

Material model	Drainage type
Linear Elastic model	Drained, Undrained(A), Undrained(C), Non-porous

Material model	Drainage type
Mohr-Coulomb model	Drained, Undrained(A), Undrained(B), Undrained(C), Non-porous
Hardening Soil model	Drained, Undrained(A), Undrained(B)
Hardening Soil model with small-strain stiffness	Drained, Undrained(A), Undrained(B)
UBC3D-PLM model	Drained, Undrained(A)
Soft Soil model	Drained, Undrained(A)
Soft Soil Creep model	Drained, Undrained(A)
Joined Rock model	Drained, Non-porous
Modified Cam-Clay model	Drained, Undrained(A)
NGI-ADP model	Drained, Undrained(C)
UDCAM-S model	Undrained(C)
Hoek-Brown model	Drained, Non-porous
Sekiguchi-Ohta model	Drained, Undrained(A)
Concrete model	Drained, Non-porous
User-defined soil models	Drained, Undrained(A), Non-porous

2.8 The initial pre-consolidation stress in advanced models

When using advanced models in PLAXIS an initial pre-consolidation stress has to be determined. In the engineering practice it is common to use a vertical pre-consolidation stress, σ_p, but PLAXIS needs an equivalent isotropic pre-consolidation stress, p_p^{eq} to determine the initial position of a cap-type yield surface. If a material is overconsolidated, information is required about the overconsolidation Ratio (OCR), i.e. the ratio of the greatest effective vertical stress previously reached, σ_p (see Figure 4 (on page 29)), and the in-situ effective vertical stress, σ'^{0}_{yy} (note that in PLAXIS 3D the vertical (effective) stress is σ'^{0}_{zz}).

$$OCR = \frac{\sigma_p}{\sigma'^{0}_{yy}} \qquad Eq.\ [61]$$

The two ways of specifying the vertical pre-consolidation stress are illustrated in Figure 4 (on page 29).

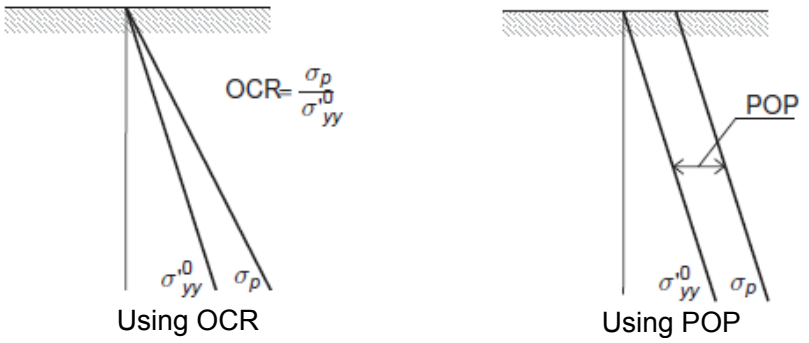


Figure 4: Illustration of vertical pre-consolidation stress in relation to the in-situ vertical stress

It is also possible to specify the initial stress state using the Pre-Overburden Pressure (POP) as an alternative to prescribing the overconsolidation ratio. The Pre-Overburden Pressure is defined by:

$$POP = \left| \sigma_p - \sigma_{yy}^{'0} \right| \qquad Eq.\ [62]$$

The pre-consolidation stress σ_p is used to compute the equivalent pre-consolidation pressure p_p^{eq} which determines the initial position of a cap-type yield surface in the advanced soil models. The calculation of p_p^{eq} is based on the principal stress history ($\sigma'_{1,max}$, σ'_2, σ'_3). The actual determination of p_p^{eq} depends on the constitutive model being used. The principal stress history is initialised in the *Initial phase (K0-procedure or Gravity loading)* based on the *Cartesian effective stress* components and the *pre-overburden pressure (POP)* or *overconsolidation ratio (OCR)* defined in the boreholes or data set. From this, Cartesian pre-consolidation stress levels are calculated based on the following equations:

$$\begin{aligned} \sigma_{xx,c}^{'} &= K_0^{nc}\, OCR\ \sigma_{yy}^{'} \\ \sigma_{xx,c}^{'} &= OCR\ \sigma_{yy}^{'} \\ \sigma_{zz,c}^{'} &= K_0^{nc}\, OCR \sigma_{yy}^{'} \\ \sigma_{xy,c} &= \sigma_{xy} \end{aligned} \qquad Eq.\ [63]$$

where

K_0^{nc} = K_0-value associated with normally consolidated states of stress.

Note:

- K_0^{nc} is a model parameter in advanced constitutive models and estimated in simple models (K_0^{nc}= *1-sinφ*).
- Models that do not have *φ* as input parameter use K_0^{nc} =0.5 (*φ=30°*).

For the Modified Cam-Clay model, K_0^{nc} is automatically determined based on the parameter *M* as entered by the user. The exact relationship between *M* and K_0^{nc} can be formulated as (Bringreve, 1994) (on page 252):

$$M = 3\sqrt{\frac{\left(1 - K_0^{nc}\right)^2}{\left(1 + 2K_0^{nc}\right)^2} + \frac{\left(1 - K_0^{nc}\right)\left(1 - 2\upsilon_{ur}\right)\left(\lambda^* / k^* - 1\right)}{\left(1 + 2K_0^{nc}\right)\left(1 - 2\upsilon_{ur}\right)\lambda^* / k - \left(1 - K_0^{nc}\right)\left(1 + \upsilon_{ur}\right)}} \qquad Eq.\ [64]$$

For more details see Modified Cam-Clay model (on page 134).

The Cartesian stress components ($\sigma'_{xx,c}$, $\sigma'_{yy,c}$, $\sigma'_{zz,c}$, $\sigma'_{xy,c}$) are transformed to principal stress components ($\sigma'_{1,max}$, σ'_2, σ'_3) and the maximum major principal stress, $\sigma'_{1,max}$, is kept as a general state parameter which is

available for succeeding phases. In subsequent phases, $\sigma'_{1,max}$ is updated if the major principal stress is larger than the current one.

If, in later calculation phases, the soil behaviour is changed to an(other) advanced material model, the equivalent pre-consolidation pressure p_p^{eq} is initialised according to the current (updated) principal stress history ($\sigma'_{1,max}$, σ'_2, σ'_3).

The stress state at pre-consolidation stress level is expressed in (p, q):

$$p' = -\frac{1}{3}(1 + 2K_0^{nc})\sigma_p \quad \text{and} \quad q=(1- K_0^{nc})\,\sigma_p \qquad \textit{Eq. [65]}$$

The equivalent isotropic pre-consolidation stress is calculated depending on the model used.

Note that *OCR* and *POP* are only taken into account in the K_0-procedure (initial calculation phase). Gravity loading does not consider *OCR* or *POP*, and always gives a normally-consolidated stress state. If an advanced soil model (involving pre-consolidation stress) is activated in a later calculation phase, i.e.

- The corresponding soil cluster is activated for the first time, or
- The material data of a soil is changed from a 'simple'soil model without pre-consolidation stress to an 'advanced'soil model with the pre-consolidation stress as a state parameter

then the stress state at the beginning of that phase is assumed to be normally-consolidated, i.e. the pre-consolidation stress is initiated in accordance with the current stress state. If, in such a case, an overconsolidated stress state is to be modelled, the overconsolidation has to be simulated by applying and removing an overburden load.

2.9 On the initial stresses

In overconsolidated soils the coefficient of lateral earth pressure for the initial stress state is larger than for normally consolidated soils. This effect is automatically taken into account for advanced soil models when generating the initial stresses using the K_0-procedure. The procedure that is followed here is described below. The procedure is described for the lateral stress in x-direction (σ'_{xx} based on $K_{0,x}$), but a similar procedure is followed for the lateral stress in z-direction (σ'_{zz} based on $K_{0,z}$).

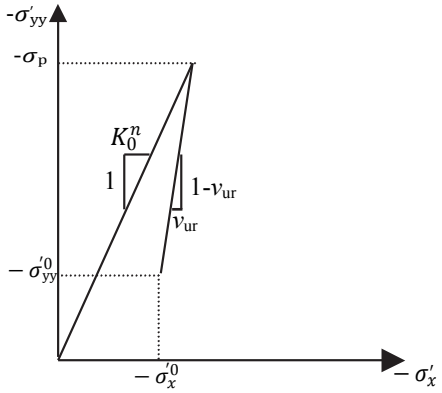


Figure 5: Overconsolidated stress state obtained from primary loading and subsequent unloading

Consider a one-dimensional compression test, preloaded to $\sigma'_{yy} = \sigma_p$ and subsequently unloaded to $\sigma'_{yy} = \sigma'^{0}_{yy}$. During unloading the sample behaves elastically and the incremental stress ratio is, according to Hooke's law, given by (see Figure 5 (on page 30)):

$$\frac{\Delta\sigma_{xx}'}{\Delta\sigma_{yy}'} = \frac{K_0^{nc}\sigma_p - \sigma_{xx}'^0}{\sigma_p - \sigma_{yy}'^0} = \frac{K_0^{nc}OCR\sigma_{yy}'^0 - \sigma_{xx}'^0}{(OCR-1)\sigma_{yy}'^0} = \frac{\upsilon_{ur}}{1-\upsilon_{ur}} \qquad \textit{Eq. [66]}$$

where K_0^{nc} is the stress ratio in the normally consolidated state. Hence, the default stress ratio of the overconsolidated soil sample is given by:

$$K_{0,x} = \frac{\sigma_{xx}'^0}{\sigma_{yy}'^0} = K_0^{nc}OCR - \frac{\upsilon_{ur}}{1-\upsilon_{ur}}(OCR-1) \qquad \textit{Eq. [67]}$$

When using POP as an alternative way to define overconsolidation, the default initial horizontal stress is defined by:

$$\sigma_{xx}'^0 = K_0^{nc}\sigma_p - \frac{\upsilon_{ur}}{1-\upsilon_{ur}}\,POP \qquad \textit{Eq. [68]}$$

The use of a small Poisson's ratio will lead to a relatively large ratio of lateral stress and vertical stress, as generally observed in overconsolidated soils. Note that Eq. [67]and Eq. [68] are only valid in the elastic domain, because the formulas are derived from Hooke's law of elasticity. If a soil sample is unloaded by a large amount, resulting in a high degree of overconsolidation, the stress ratio will be limited by the Mohr-Coulomb failure condition.

Note that the above initial stress ratio's are only suggested (default) values, and may be overruled by the user if more precise data are available or if other values seem more appropriate.

3 Linear Elastic Perfectly Plastic Model (Mohr-Coulomb Model)

Soils behave rather non-linear when subjected to changes of stress or strain. In reality, the stiffness of soil depends at least on the stress level, the stress path and the strain level. Some such features are included in the advanced soil models in PLAXIS. The Mohr-Coulomb model, however, is a simple and well-known linear elastic perfectly plastic model, which can be used as a first approximation of soil behaviour. The linear elastic part of the Mohr-Coulomb model is based on Hooke's law of isotropic elasticity (Linear Elastic Perfectly - Plastic behaviour (on page 32)). The perfectly plastic part is based on the Mohr-Coulomb failure criterion, formulated in a non-associated plasticity framework.

Plasticity involves the development of irreversible strains. In order to evaluate whether or not plasticity occurs in a calculation, a yield function, f, is introduced as a function of stress and strain. Plastic yielding is related with the condition $f = 0$. This condition can often be presented as a surface in principal stress space. A perfectly-plastic model is a constitutive model with a fixed yield surface, i.e. a yield surface that is fully defined by model parameters and not affected by (plastic) straining. For stress states represented by points within the yield surface, the behaviour is purely elastic and all strains are reversible.

3.1 Linear Elastic Perfectly - Plastic behaviour

The basic principle of elastoplasticity is that strains and strain rates are decomposed into an elastic part and a plastic part:

$$\underline{\varepsilon} = \underline{\varepsilon}^e + \underline{\varepsilon}^p \qquad \dot{\underline{\varepsilon}} = \dot{\underline{\varepsilon}}^e + \dot{\underline{\varepsilon}}^p \qquad \textit{Eq. [69]}$$

Hooke's law is used to relate the stress rates to the elastic strain rates. Substitution of Eq. [69] into Hooke's law Eq. [30] leads to:

$$\dot{\underline{\sigma}}' = \mathbf{D}^e \dot{\underline{\varepsilon}}^e = \mathbf{D}^e(\dot{\underline{\varepsilon}} - \dot{\underline{\varepsilon}}^p) \qquad \textit{Eq. [70]}$$

According to the classical theory of plasticity , plastic strain rates are proportional to the derivative of the yield function with respect to the stresses. This means that the plastic strain rates can be represented as vectors perpendicular to the yield surface. This classical form of the theory is referred to as associated plasticity. However, for Mohr-Coulomb type yield functions, the theory of associated plasticity overestimates dilatancy. Therefore, in addition to the yield function, a plastic potential function g is introduced. The case $g \neq f$ is denoted as non-associated plasticity. In general, the plastic strain rates are written as:

$$\dot{\underline{\varepsilon}}^p = \lambda \frac{\partial g}{\partial \underline{\sigma}'} \qquad \textit{Eq. [71]}$$

in which λ is the plastic multiplier. For purely elastic behaviour λ is zero, whereas in the case of plastic behaviour λ is positive:

$$\lambda = 0 \quad for: \quad f < 0 \quad or: \quad \frac{\partial f}{\partial \underline{\sigma}'}^T \mathbf{D}^e \dot{\underline{\varepsilon}} \leq 0 \qquad (Elasticity) \qquad Eq.\ [72]$$

$$\lambda > 0 \quad for: \quad f = 0 \quad and: \quad \frac{\partial f}{\partial \underline{\sigma}'}^T \mathbf{D}^e \dot{\underline{\varepsilon}} > 0 \qquad (Plasticity) \qquad Eq.\ [73]$$

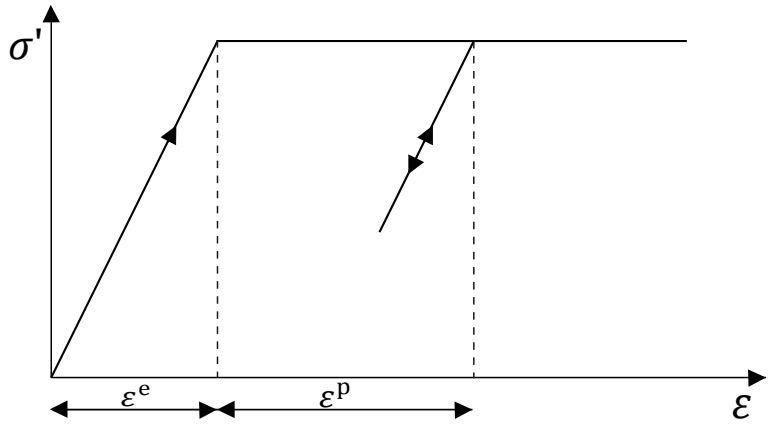


Figure 6: Basic idea of an elastic perfectly plastic model

These equations may be used to obtain the following relationship between the effective stress rates and strain rates for elastic perfectly-plastic behaviour (Smith & Griffiths [1982] (on page 255); Vermeer & Borst [1984] (on page 255)):

$$\dot{\underline{\sigma}}' = \left(\mathbf{D}^e - \frac{\alpha}{d} \mathbf{D}^e \frac{\partial g}{\partial \underline{\sigma}'} \frac{\partial f}{\partial \underline{\sigma}'}^T \mathbf{D}^e \right) \dot{\underline{\varepsilon}} \qquad Eq.\ [74]$$

where:

$$d = \left(\frac{\partial f}{\partial \underline{\sigma}'}^T \mathbf{D}^e \frac{\partial g}{\partial \underline{\sigma}'} \right) \qquad Eq.\ [75]$$

The parameter α is used as a switch. If the material behaviour is elastic, as defined by Eq. [72], the value of α is equal to zero, whilst for plasticity, as defined by Eq. [73], the value of α is equal to unity.

The above theory of plasticity is restricted to smooth yield surfaces and does not cover a multi surface yield contour as present in the full Mohr-Coulomb model. For such a yield surface the theory of plasticity has been extended by Koiter (1960) (on page 253) and others to account for flow vertices involving two or more plastic potential functions:

$$\dot{\underline{\varepsilon}}^p = \lambda_1 \frac{\partial g_1}{\partial \underline{\sigma}'} + \lambda_2 \frac{\partial g_2}{\partial \underline{\sigma}'} + \ldots \qquad Eq.\ [76]$$

Similarly, several quasi independent yield functions ($f_1, f_2, \ldots$) are used to determine the magnitude of the multipliers ($\lambda_1, \lambda_2, \ldots$).

3.2 Formulation of the Mohr-Coulomb model

The Mohr-Coulomb yield condition is an extension of Coulomb's friction law to general states of stress. In fact, this condition ensures that Coulomb's friction law is obeyed in any plane within a material element.

The full Mohr-Coulomb yield condition consists of six yield functions when formulated in terms of principal stresses (see for instance Smith & Griffiths, 1982 (on page 255)):

$$
\begin{aligned}
f_{1a} &= \tfrac{1}{2}\left(\sigma'_2 - \sigma'_3\right) + \tfrac{1}{2}\left(\sigma'_2 + \sigma'_3\right)\sin(\phi) - c\cos(\phi) \le 0 \qquad a)\\
f_{2a} &= \tfrac{1}{2}\left(\sigma'_3 - \sigma'_2\right) + \tfrac{1}{2}\left(\sigma'_3 + \sigma'_2\right)\sin(\phi) - c\cos(\phi) \le 0 \qquad b)\\
f_{2a} &= \tfrac{1}{2}\left(\sigma'_3 - \sigma'_1\right) + \tfrac{1}{2}\left(\sigma'_3 + \sigma'_1\right)\sin(\phi) - c\cos(\phi) \le 0 \qquad c)\\
f_{2b} &= \tfrac{1}{2}\left(\sigma'_1 - \sigma'_3\right) + \tfrac{1}{2}\left(\sigma'_1 + \sigma'_3\right)\sin(\phi) - c\cos(\phi) \le 0 \qquad d)\\
f_{3a} &= \tfrac{1}{2}\left(\sigma'_1 - \sigma'_2\right) + \tfrac{1}{2}\left(\sigma'_1 + \sigma'_2\right)\sin(\phi) - c\cos(\phi) \le 0 \qquad e)\\
f_{3b} &= \tfrac{1}{2}\left(\sigma'_2 - \sigma'_1\right) + \tfrac{1}{2}\left(\sigma'_2 + \sigma'_1\right)\sin(\phi) - c\cos(\phi) \le 0 \qquad f)
\end{aligned}
\qquad \textit{Eq. [77]}
$$

The two plastic model parameters appearing in the yield functions are the well-known friction angle φ and the cohesion c. The condition $f_i = 0$ for all yield functions together (where f_i is used to denote each individual yield function) represents a fixed hexagonal cone in principal stress space as shown in Figure 7 (on page 34).

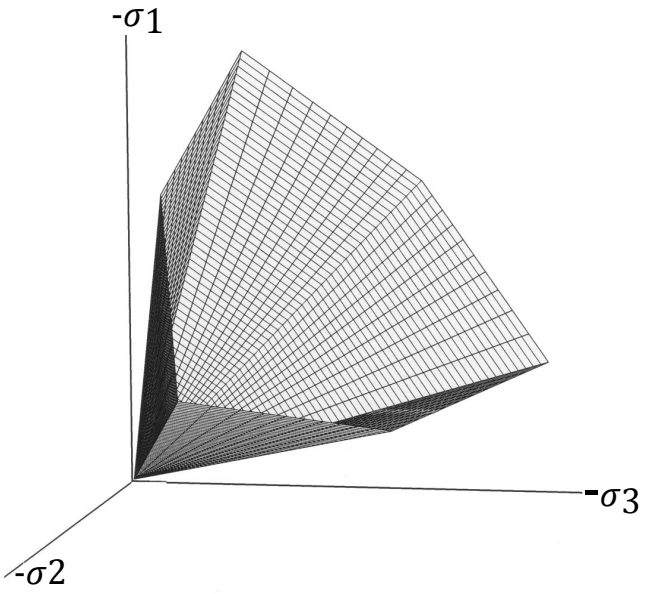


Figure 7: The Mohr-Coulomb yield surface in principal stress space (c = 0)

In addition to the yield functions, six plastic potential functions are defined for the Mohr-Coulomb model:

$$
\begin{aligned}
g_{1a} &= \tfrac{1}{2}\left(\sigma'_2 - \sigma'_3\right) + \tfrac{1}{2}\left(\sigma'_2 + \sigma'_3\right)\sin(\psi) \le 0 \qquad a)\\
g_{1b} &= \tfrac{1}{2}\left(\sigma'_3 - \sigma'_2\right) + \tfrac{1}{2}\left(\sigma'_3 + \sigma'_2\right)\sin(\psi) \le 0 \qquad b)\\
g_{2a} &= \tfrac{1}{2}\left(\sigma'_3 - \sigma'_1\right) + \tfrac{1}{2}\left(\sigma'_3 + \sigma'_1\right)\sin(\psi) \le 0 \qquad c)\\
g_{2b} &= \tfrac{1}{2}\left(\sigma'_1 - \sigma'_3\right) + \tfrac{1}{2}\left(\sigma'_1 + \sigma'_3\right)\sin(\psi) \le 0 \qquad d)\\
g_{3a} &= \tfrac{1}{2}\left(\sigma'_1 - \sigma'_2\right) + \tfrac{1}{2}\left(\sigma'_1 + \sigma'_2\right)\sin(\psi) \le 0 \qquad e)\\
g_{3b} &= \tfrac{1}{2}\left(\sigma'_2 - \sigma'_1\right) + \tfrac{1}{2}\left(\sigma'_2 + \sigma'_1\right)\sin(\psi) \le 0 \qquad f)
\end{aligned}
\qquad \textit{Eq. [78]}
$$

The plastic potential functions contain a third plasticity parameter, the dilatancy angle ψ. This parameter is required to model positive plastic volumetric strain increments (dilatancy) as actually observed for dense soils. A discussion of all of the model parameters used in the Mohr-Coulomb model is given in the next section.

When implementing the Mohr-Coulomb model for general stress states, special treatment is required for the intersection of two yield surfaces. Some programs use a smooth transition from one yield surface to another, i.e. the rounding-off of the corners (see for example Smith & Griffiths, 1982 (on page 255)). In PLAXIS, however, the exact form of the full Mohr-Coulomb model is implemented, using a sharp transition from one yield surface to another. For a detailed description of the corner treatment the reader is referred to the literature (Koiter, 1960 (on page 253); van Langen & Vermeer, 1990 (on page 255)).

For $c > 0$, the standard Mohr-Coulomb criterion allows for tension. In fact, allowable tensile stresses increase with cohesion. In reality, soil can sustain none or only very small tensile stresses. This behaviour can be included in a PLAXIS analysis by specifying a tension cut-off. In this case, Mohr circles with positive principal stresses are not allowed. The tension cut-off introduces three additional yield functions, defined as:

$$
\begin{aligned}
f_4 &= \sigma'_1 - \sigma_t \le 0 \qquad a)\\
f_5 &= \sigma'_2 - \sigma_t \le 0 \qquad b)\\
f_6 &= \sigma'_3 - \sigma_t \le 0 \qquad c)
\end{aligned}
\qquad \textit{Eq. [79]}
$$

When this tension cut-off procedure is used, the allowable tensile stress, σ_t, is, by default, taken equal to zero, but this value can be changed by the user. For these three yield functions an associated flow rule is adopted.

For stress states within the yield surface, the behaviour is elastic and obeys Hooke's law for isotropic linear elasticity, as discussed in . Hence, besides the plasticity parameters c, φ, and ψ, input is required on the elastic Young's modulus E and Poisson's ratio ν. The model described here is officially called the linear elastic perfectly plastic model with Mohr-Coulomb failure criterion. For simplicity, this model is called the Mohr-Coulomb model in PLAXIS.

3.3 Basic parameters of the Mohr-Coulomb model

The linear elastic perfectly-plastic Mohr-Coulomb model requires a total of five parameters, which are generally familiar to most geotechnical engineers and which can be obtained from basic tests on soil samples. These parameters with their standard units are listed below:

E	Young's modulus	[kN/m^2]

ν	Poisson's ratio	[-]
c	Cohesion	[kN/m^2]
φ	Friction angle	[°]
ψ	Dilatancy angle	[°]
σ_t	Tension cut-off and tensile strength	[kN/m^2]

Instead of using the Young's modulus as a stiffness parameter, alternative stiffness parameters can be entered. These parameters with their standard units are listed below:

G	Shear modulus	[kN/m^2]
E_{oed}	Oedometer modulus	[kN/m^2]

Parameters can either be effective parameters (indicated by a prime sign (')) or undrained parameters (indicated by a subscript u), depending on the selected drainage type.

DYN In the case of dynamic applications, alternative and/or additional parameters may be used to define stiffness based on wave velocities. These parameters are listed below:

V_P	Compression wave velocity	[m/s]
V_S	Shear wave velocity	[m/s]

3.3.1 Young's modulus (E)

PLAXIS uses the Young's modulus as the basic stiffness modulus in the elastic model and the Mohr-Coulomb model, but some alternative stiffness moduli are displayed as well. A stiffness modulus has the dimension of stress. The values of the stiffness parameter adopted in a calculation require special attention as many geomaterials show a non-linear behaviour from the very beginning of loading. In triaxial testing of soil samples the initial slope of the stress-strain curve (tangent modulus) is usually indicated as E_0 and the secant modulus at 50% strength is denoted as E_{50} (see Figure 8 (on page 37)). For materials with a large linear elastic range it is realistic to use E_0, but for loading of soils one generally uses E_{50}. Considering unloading problems, as in the case of tunnelling and excavations, one needs an unload-reload modulus (E_{ur}) instead of E_{50}.

For soils, both the unloading modulus, E_{ur}, and the first loading modulus, E_{50}, tend to increase with the confining pressure. Hence, deep soil layers tend to have greater stiffness than shallow layers. Moreover, the observed stiffness depends on the stress path that is followed. The stiffness is much higher for unloading and reloading than for primary loading. Also, the observed soil stiffness in terms of a Young's modulus may be lower for (drained) compression than for shearing. Hence, when using a constant stiffness modulus to represent soil behaviour one should choose a value that is consistent with the stress level and the stress path development. Note that some stress-dependency of soil behaviour is taken into account in the advanced models in PLAXIS which are described in subsequent chapters. For the Mohr-Coulomb model, PLAXIS offers a special option for the input of a stiffness increasing with depth (see Advanced parameters of the Mohr-Coulomb model (on page 40)). Note that for material data sets where the drainage type is set to *Undrained (A)* or *Undrained (B)*, Young's modulus has the meaning of an effective Young's modulus, whilst PLAXIS automatically takes care of the incompressibility (Undrained effective stress analysis (effective stiffness parameters) (on page 20)).

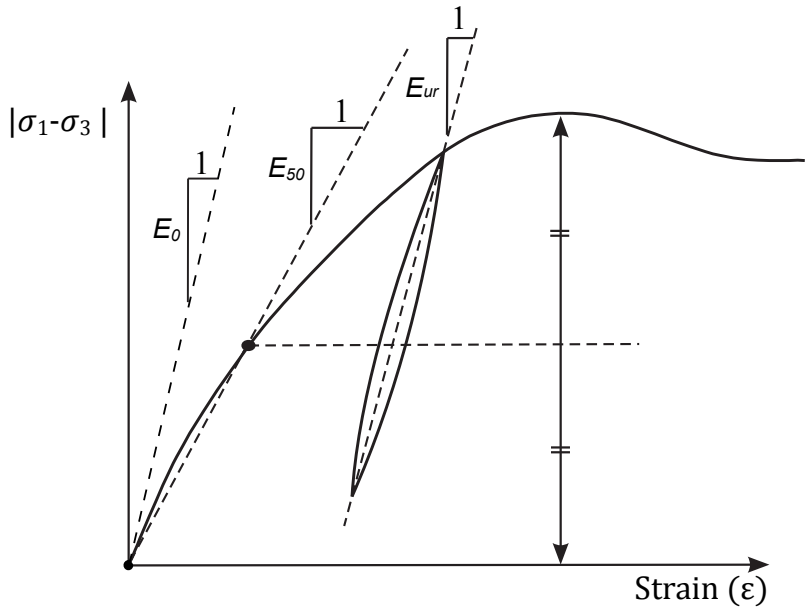


Figure 8: Definition of E_0, E_{50} and E_{ur} for drained triaxial test results

3.3.2 Poisson's ratio (ν)

Standard drained triaxial tests may yield a significant rate of volume decrease at the very beginning of axial loading and, consequently, a low initial value of Poisson's ratio (ν_0). For some cases, such as particular unloading problems, it may be realistic to use such a low initial value, but in general when using the Mohr-Coulomb model the use of a higher value is recommended.

The selection of a Poisson's ratio is particularly simple when the elastic model or Mohr-Coulomb model is used for gravity loading under conditions of one-dimensional compression. For this type of loading PLAXIS should give realistic ratios of $K_0 = \sigma'_h / \sigma'_v$.

As both models will give the well-known ratio of $\sigma'_h / \sigma'_v = \nu / (1 - \nu)$ for one-dimensional compression it is easy to select a Poisson's ratio that gives a realistic value of K_0. Hence, ν is evaluated by matching K_0. In many cases one will obtain ν values in the range between 0.3 and 0.4. In general, such values can also be used for loading conditions other than one-dimensional compression. Please note that in this way it is not possible to create K_0 values larger than 1, as may be observed in highly overconsolidated stress states. For unloading conditions, however, it is more appropriate to use values in the range between 0.15 and 0.25.

Further note that for material data sets where the drainage type is set to *Undrained (A)* or *Undrained (B)*, Poisson's ratio has the meaning of an effective Poisson's ratio, whilst PLAXIS automatically takes care of the incompressibility (Undrained effective stress analysis (effective stiffness parameters) (on page 20)). To ensure that the soil skeleton is much more compressible than the pore water, the effective Poisson's ratio should be smaller than 0.35 for *Undrained (A)* or *Undrained (B)* materials.

3.3.3 Cohesion (c) or undrained shear strength (s_u)

The cohesive strength has the dimension of stress. In the Mohr-Coulomb model, the cohesion parameter may be used to model the effective cohesion c' of the soil (cohesion intercept), in combination with a realistic effective friction angle φ' (see Figure 9 (on page 38) (a)). This may not only be done for drained soil behaviour, but also

if the type of material behaviour is set to *Undrained (A)*, as in both cases PLAXIS will perform an effective stress analysis. Alternatively, the cohesion parameter may be used to model the undrained shear strength s_u of the soil, in combination with $\varphi = \varphi_u = 0$ when the *Drainage type* is set to *Undrained (B)* or *Undrained (C)* In that case the Mohr-Coulomb failure criterion reduces to the well-known Tresca criterion. PLAXIS allows for an increase of shear strength with depth using the $s_{u,inc}$ parameter (Advanced parameters of the Mohr-Coulomb model (on page 40)).

The disadvantage of using effective strength parameters c' and φ' in combination with the drainage type being set to *Undrained (A)* is that the undrained shear strength as obtained from the model may deviate from the undrained shear strength in reality because of differences in the actual stress path being followed. In this respect, advanced soil models generally perform better than the Mohr-Coulomb model, but in all cases it is recommended to compare the resulting stress state in all calculation phases with the present shear strength in reality ($|\sigma_1-\sigma_3| \leq 2\, s_u$) .

On the other hand, the advantage of using effective strength parameters is that the change in shear strength with consolidation is obtained automatically, although it is still recommended to check the resulting stress state after consolidation.

The advantage of using the cohesion parameter to model undrained shear strength in combination with $\varphi = 0$ (*Undrained (B)* or *Undrained (C)*) is that the user has direct control over the shear strength, independent of the actual stress state and stress path followed. Please note that this option may not be appropriate when using advanced soil models.

PLAXIS can handle cohesionless sands ($c = 0$), but some options may not perform well. To avoid complications, non-experienced users are advised to enter at least a small value in soil layers near the ground surface (use $c >$ 0.2 kPa). Please note that a positive value for the cohesion may lead to a tensile strength, which may be unrealistic for soils. By default,the *Tension cut-off* option is used to reduce the tensile strength.

PLAXIS offers a special option for the input of layers in which the cohesion increases with depth (see Advanced parameters of the Mohr-Coulomb model (on page 40)).

3.3.4 Friction angle (φ)

The friction angle φ (phi) is entered in degrees. In general the friction angle is used to model the effective friction of the soil, in combination with an effective cohesion c' (Figure 9 (on page 38) (a)). This may not only be done for drained soil behaviour, but also if the type of material behaviour is set to *Undrained (A)*, since in both cases PLAXIS will perform an effective stress analysis. Alternatively, the soil strength is modelled by setting the cohesion parameter equal to the undrained shear strength of the soil, in combination with $\varphi = 0$ (*Undrained (B)* or *Undrained (C)*) (Figure 9 (on page 38) (b)). In that case the Mohr-Coulomb failure criterion reduces to the well-known Tresca criterion.

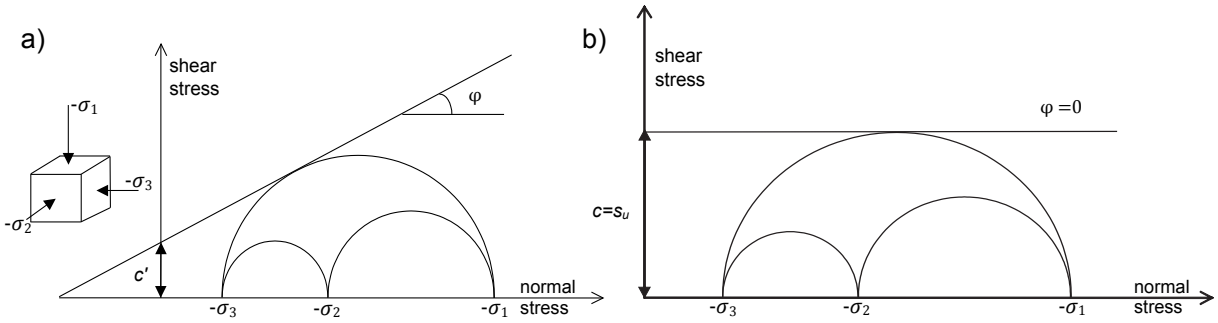


Figure 9: Stress circles at yield; one touches Coulomb's envelope. a) Using effective strength parameters (Mohr-Coulomb) - b) Using undrained strength parameters (Tresca).

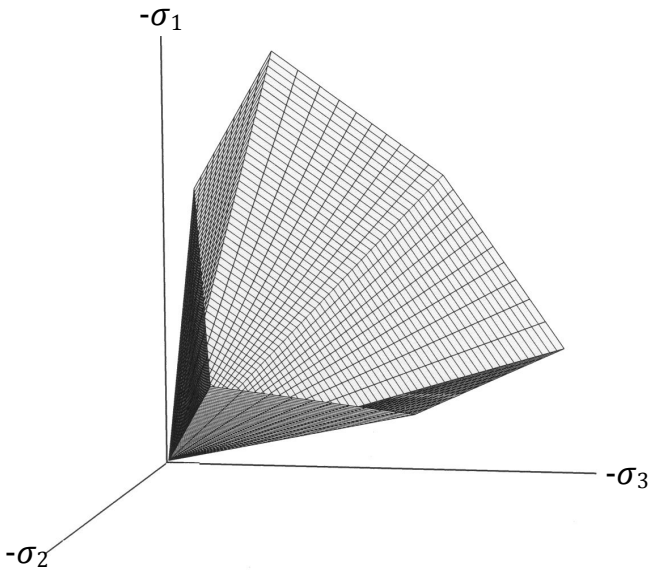


Figure 10: Failure surface in principal stress space for cohesionless soil

High friction angles, as sometimes obtained for dense sands, will substantially increase plastic computational effort. Moreover, high friction may be subjected to strain-softening behaviour, which means that such high friction angles are not sustainable under (large) deformation. Hence, high friction angles should be avoided when performing preliminary computations for a particular project*. The friction angle largely determines the shear strength as shown in Figure 9 (on page 38) by means of Mohr's stress circles. A more general representation of the yield criterion is shown in Figure 10 (on page 39). The Mohr-Coulomb failure criterion proves to be better for describing soil strength for general stress states than the Drucker-Prager approximation.

Note: *The friction angles are in the order of 20 - 30 degrees for clay and silt (the more plastic the clay, the lower the friction), and 30 - 40 degrees for sand and gravel (the denser the sand, the higher the friction).

3.3.5 Dilatancy angle (ψ)

The dilatancy angle, ψ (psi), is specified in degrees. Apart from heavily overconsolidated layers, clay soils tend to show little dilatancy ($\psi \approx 0$). The dilatancy of sand depends on both the density and the friction angle. In general the dilatancy angle of soils is much smaller than the friction angle. For quartz sands the order of magnitude is $\psi \approx -30\ ^\circ$. For φ-values of less than 30°, however, the angle of dilatancy is mostly zero. A small negative value for ψ is only realistic for extremely loose sands. In the Hardening Soil model or Hardening Soil model with small-strain stiffness the end of dilatancy, as generally observed when the soil reaches the critical state, can be modelled using the *Dilatancy cut-off*. However, this option is not available for the Mohr-Coulomb model. For further information about the link between the friction angle and dilatancy, see Bolton (1986). (on page 252).

A positive dilatancy angle implies that in drained conditions the soil will continue to dilate as long as shear deformation occurs. This is clearly unrealistic, as most soils will reach a critical state at some point and further shear deformation will occur without volume changes. In undrained conditions a positive dilatancy angle, combined with the restriction on volume changes, leads to a generation of tensile pore stresses. In an undrained effective stress analysis therefore the strength of the soil may be overestimated.

When the soil strength is modelled as undrained shear strength, s_u, and $\varphi = 0$, (*Undrained (B)* or *Undrained (C)*) the dilatancy angle is automatially set to zero. Great care must be taken when using a positive value of dilatancy

in combination with drainage type set to *Undrained (A)*. In that case the model will show unlimited soil strength due to tensile pore stresses. These tensile pore stresses can be limited by setting the cavitation cut-off.

3.3.6 Shear modulus (G)

The shear modulus, G, has the dimension of stress. According to Hooke's law, the relationship between Young's modulus E and the shear modulus is given by (see Eq. [31] a)):

$$G = \frac{E}{2(1+\upsilon)} \qquad Eq.\ [80]$$

Entering a particular value for one of the alternatives G or E_{oed} results in a change of the E modulus whilst ν remains the same.

3.3.7 Oedometer modulus (E_{oed})

The oedometer modulus, E_{oed}, or constrained modulus, has the dimension of stress. According to Hooke's law, the relationship between Young's modulus E and the oedometer modulus is given by (see Eq. [31] c)).

$$E_{oed} = \frac{(1-\upsilon)E}{(1-2\upsilon)(1+\upsilon)} \qquad Eq.\ [81]$$

Entering a particular value for one of the alternatives G or E_{oed} results in a change of the E modulus whilst ν remains the same.

3.3.8 Compression wave velocity V_p DYN

The compression wave velocity, V_p, in a confined one-dimensional soil is a function of stiffness, E_{oed}, and the mass density, ρ, as:

$$V_p = \sqrt{\frac{E_{oed}}{\rho}} \quad where \quad E_{oed} = \frac{(1-\upsilon)E}{(1+\upsilon)(1-2\upsilon)} \quad and \quad \rho = \frac{\gamma_{unsat}}{g} \qquad Eq.\ [82]$$

in which γ_{unsat} is the total unsaturated unit weight and g is the gravity acceleration (9.8 m/s^2).}

3.3.9 Shear wave velocity V_s DYN

The shear wave velocity, V_s, in a confined one-dimensional soil is a function of shear stiffness, G, and the mass density, ρ, as:

$$V_s = \sqrt{\frac{G}{\rho}} \quad where \quad G = \frac{E}{2(1+\upsilon)} \quad and \quad \rho = \frac{\gamma_{unsat}}{g} \qquad Eq.\ [83]$$

in which γ_{unsat} is the total unsaturated unit weight and g is the gravity acceleration (9.8 m/s^2).

3.4 Advanced parameters of the Mohr-Coulomb model

The advanced features comprise the increase of stiffness and cohesive strength with depth and the use of a tension cut-off. In fact, the latter option is used by default, but it may be deactivated here, if desired. These parameters are defined in the *Advanced* subtree in the **Parameters** tabsheet of the **Soil** window.

3.4.1 Increase of stiffness (E_{inc})

In real soils, the stiffness depends significantly on the stress level, which means that the stiffness generally increases with depth. When using the Mohr-Coulomb model, the stiffness is a constant value. In order to account for the increase of the stiffness with depth the E_{inc}-value may be used, which is the increase of the Young's modulus per unit of depth (expressed in the unit of stress per unit depth). At the level given by the y_{ref} parameter, and above, the stiffness is equal to the reference Young's modulus, E_{ref}, as entered in the **Parameters** tabsheet. Below, the stiffness is given by:

$$E(y) = E_{ref} + (y_{ref} - y)E_{inc} \quad (y < y_{ref}) \qquad Eq.\ [84]$$

where y represents the vertical direction. The actual value of Young's modulus in the stress points is obtained from the reference value and E_{inc}. Note that during calculations a stiffness increasing with depth does not change as a function of the stress state.

Note: Note that in PLAXIS 3D the vertical coordinate is z instead of y.

3.4.2 Increase of cohesion or shear strength with depth (c_{inc} or $s_{u,inc}$)

PLAXIS offers an advanced option for the input of clay layers in which the cohesion, c, (or undrained shear strength, s_u) increases with depth. In order to account for the increase of the cohesion with depth the c_{inc}-value may be used, which is the increase of cohesion per unit of depth (expressed in the unit of stress per unit depth). At the level given by the y_{ref} parameter, and above, the cohesion is equal to the (reference) cohesion, c_{ref}, as entered in the **Parameters** tabsheet. Below, the cohesive strength is given by:

$$\begin{aligned} c(y) &= c_{ref} + (y_{ref} - y)c_{inc} \quad (y < y_{ref}) \quad a) \\ s_u(y) &= s_{u,ref} + (y_{ref} - y)s_{u,inc} \quad (y < y_{ref}) \quad b) \end{aligned} \qquad Eq.\ [85]$$

where y represents the vertical direction. Note that when using effective strength properties ($\varphi' > 0$) it is generally not necessary to use an increase of cohesion with depth, since the friction together with the initial effective stress will result in an increasing shear strength with depth.

3.4.3 Tension cut-off

In some practical problems an area with tensile stresses may develop. According to the Coulomb envelope shown in Figure 9 (on page 38) this is allowed when the shear stress (radius of Mohr circle) is sufficiently small. However, the soil surface near a trench in clay sometimes shows tensile cracks. This indicates that soil may also fail in tension instead of in shear. Such behaviour can be included in a PLAXIS analysis by selecting the tension cut-off. In this case Mohr circles with positive principal stresses are not allowed. When selecting the tension cut-off the allowable tensile strength may be entered. For the Mohr-Coulomb model the tension cut-off is, by default, selected with a tensile strength of zero.

3.5 On the use of the Mohr-Coulomb model in dynamic calculations

When using the Mohr-Coulomb model in dynamic calculations, the stiffness parameters need to be selected such that the model correctly predicts wave velocities in the soil (Eq. [82] and Eq. [83]). This generally requires a much larger small strain stiffness rather than a stiffness at engineering strain levels. When subjected to dynamic or cyclic loading, the Mohr-Coulomb model may generate plastic strains if stress points reach the Mohr-Coulomb failure criterion, which will lead to damping in dynamic calculations. However, it should be noted that the stress cycles within the Mohr-Coulomb failure contour will only generate elastic strains and no (hysteretic) damping, nor accumulation of strains or pore pressure or liquefaction. In order to simulate the soil's damping characteristics in cyclic loading, Rayleigh damping may be defined.

4 The Hoek-Brown model (rock behaviour)

The material behaviour of rock differs from the behaviour of soils in the sense that it is generally stiffer and stronger. The dependency of the stiffness on the stress level is almost negligible, so stiffness of rocks can be considered constant. On the other hand, the dependency of the (shear) strength on the stress level is significant. In this respect, heavily jointed or weathered rock can be regarded a frictional material. A first approach is to model the shear strength of rock by means of the Mohr-Coulomb failure criterion. However, considering the large range of stress levels where rock may be subjected to, a linear stress-dependency, as obtained from the Mohr-Coulomb model, is generally not sufficient. Furthermore, rock may also show a significant tensile strength. The Hoek-Brown failure criterion is a better non-linear approximation of the strength of rocks. It involves shear strength as well as tensile strength in a continuous formulation. Together with Hooke's law of isotropic linear elastic behaviour it forms the Hoek-Brown model for rock behaviour. The 2002 edition of this model (Hoek, Carranza-Torres & Corkum, 2002) (on page 253) has been implemented in to simulate the isotropic behaviour of rock-type materials. The implementation of the model, including the material strength factorization, is based on Bentz, Schwab, Vermeer &Kauther, (2007) (on page 252). More background information on the Hoek-Brown model and the selection of model parameters can be found in Hoek, 2006 (on page 253). For anisotropic behaviour of stratified rock reference is made to The Joined Rock model (anisotropy) (on page 55).

4.1 Formulation of the Hoek-Brown model

The generalised Hoek-Brown failure criterion can be formulated as a non-linear relationship between the major and minor effective principal stresses (considering tension positive and compression negative):

$$\sigma_1' = \sigma_3' - \mid \sigma_{ci} \mid \left(m_b \frac{\sigma_3'}{\sigma_{ci}} + s \right)^a \qquad Eq.\ [86]$$

where m_b is a reduced value of the intact rock parameter m_i, which also depends on the Geological Strength Index (GSI) and the Disturbance Factor (D):

$$m_b = m_i \exp\left(\frac{GSI - 100}{28 - 14D} \right) \qquad Eq.\ [87]$$

s and a are auxiliary material constants for the rock mass, that can be expressed as:

$$s = \exp\left(\frac{GSI - 100}{9 - 3D} \right) \qquad Eq.\ [88]$$

$$a = \frac{1}{2} + \frac{1}{6}\left[\exp\left(\frac{-GSI}{15} \right) - \exp\left(\frac{-20}{3} \right) \right] \qquad Eq.\ [89]$$

σ_{ci} is the uni-axial compressive strength of the intact rock material (defined as a positive value). From this value, the uni-axial compressive strength of the specific rock under consideration, σ_c, can be obtained by:

$$\sigma_c = - \mid \sigma_{ci} \mid s^a \qquad \textit{Eq. [90]}$$

The tensile strength of the specific rock under consideration, σ_t, can be obtained by:

$$\sigma_t = \frac{s \mid \sigma_{ci} \mid}{m_b} \qquad \textit{Eq. [91]}$$

The Hoek-Brown failure criterion is illustrated in Figure 11 (on page 44).

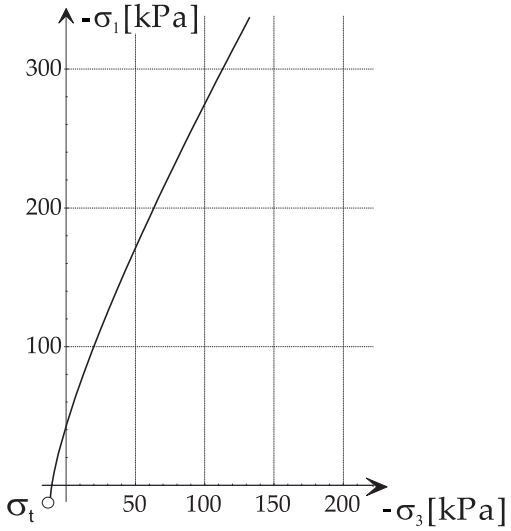


Figure 11: Hoek-Brown failure criterion in principal stresses

In the framework of plasticity theory, the Hoek-Brown failure criterion is reformulated into the following yield function:

$$f_{HB} = \sigma_1' - \sigma_3' + \bar{f}(\sigma_3') \quad where \quad \bar{f}(\sigma_3') = \mid \sigma_{ci} \mid \left(m_b \frac{-\sigma_3'}{\mid \sigma_{ci} \mid} + s \right)^a \qquad \textit{Eq. [92]}$$

For general three-dimensional stress states, more than one yield function is required to deal with the corners of the yield contour, similar as for the full Mohr-Coulomb criterion. Defining compression as negative and considering ordering of principal stresses such that $\sigma'_1 \leq \sigma'_2 \leq \sigma'_3$, the full criterion can be captured by two yield functions:

$$f_{HB,13} = \sigma_1' - \sigma_3' + \bar{f}(\sigma_3') \quad where \quad \bar{f}(\sigma_3') = \mid \sigma_{ci} \mid \left(m_b \frac{-\sigma_3'}{\mid \sigma_{ci} \mid} + s \right)^a \qquad \textit{Eq. [93]}$$

$$f_{HB,12} = \sigma_1' - \sigma_3' + \bar{f}(\sigma_2') \quad where \quad \bar{f}(\sigma_2') = \mid \sigma_{ci} \mid \left(m_b \frac{-\sigma_2'}{\mid \sigma_{ci} \mid} + s \right)^a \qquad \textit{Eq. [94]}$$

The full Hoek-Brown failure contour ($f_i = 0$) in principal stress space is illustrated in Figure 12 (on page 45)

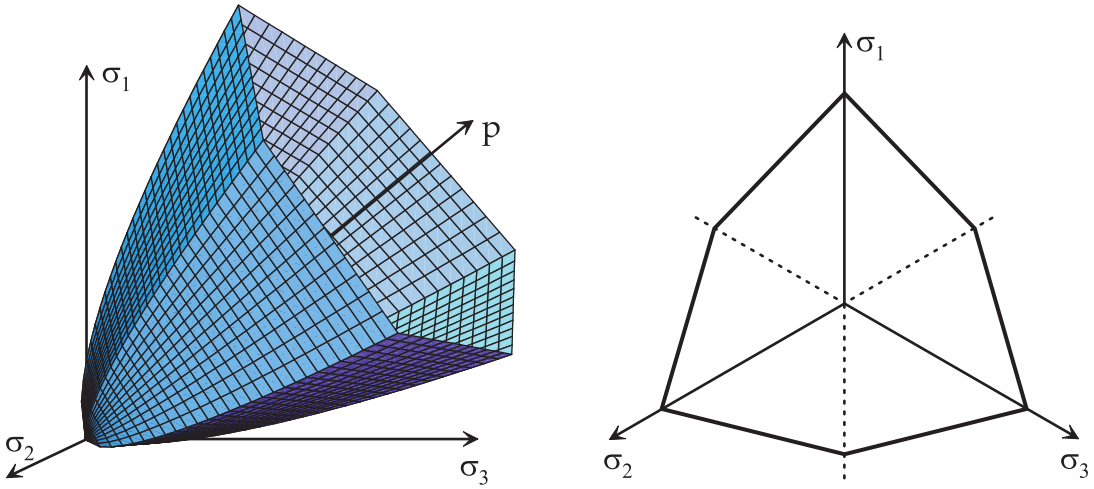


Figure 12: The Hoek-Brown failure contour in principal stress space

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In addition to the two yield functions, two corresponding plastic potential functions are defined for the Hoek-Brown model:

$$g_{HB,13} = S_1 - \left(\frac{1 + \sin(\psi_{mob})}{1 - \sin(\psi_{mob})} \right) S_3 \qquad \textit{Eq. [95]}$$

$$g_{HB,12} = S_1 - \left(\frac{1 + \sin(\psi_{mob})}{1 - \sin(\psi_{mob})} \right) S_2 \qquad \textit{Eq. [96]}$$

where S_i are the transformed stresses, defined as:

$$S_i = \left(\frac{-\sigma_i}{m_b \mid \sigma_{ci} \mid} + \frac{s}{m_b^2} \right) \quad for \quad i = 1,\ 2,\ 3 \qquad \textit{Eq. [97]}$$

ψ_{mob} is the mobilised dilatancy angle, varying with σ'_3 from its input value at ($\sigma'_3 = 0$) down to zero at $-\sigma'_3 = \sigma_\psi$ and beyond:

$$\psi_{mob} = \frac{\sigma_\psi + \sigma'_3}{\sigma_\psi} \psi \geq 0 \qquad (0 \geq -\sigma'_3 \geq \sigma_\psi) \qquad \textit{Eq. [98]}$$

Moreover, in order to allow for plastic expansion in the tensile zone, an increased artificial value of the mobilised dilatancy is used:

$$\psi_{mob} = \psi + \frac{\sigma'_3}{\sigma_t}(90^o - \psi) \qquad (\sigma'_t \geq \sigma'_3 \geq 0) \qquad \textit{Eq. [99]}$$

The evolution of the mobilised dilatancy angle as a function of σ'_3 is visualized in Figure 13 (on page 46).

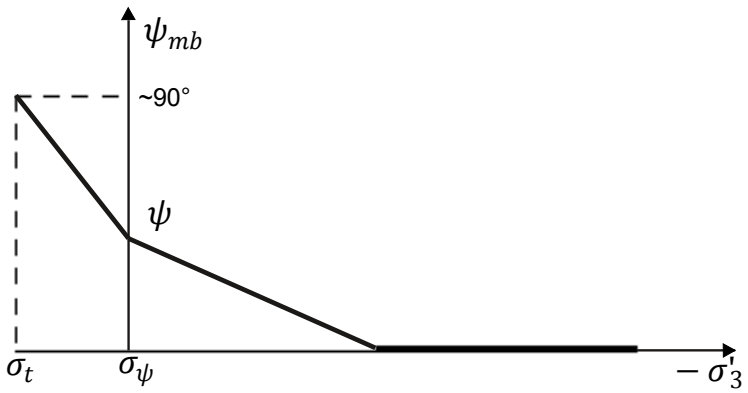


Figure 13: Evolution of mobilised dilatancy angle

Regarding the elastic behaviour of the Hoek-Brown model, Hooke's law of isotropic linear elastic behaviour, as described in Elastic strains (on page 18), is adopted. This part of the model involves Young's modulus, E, representing the in-situ stiffness of the jointed rock mass before failure, and Poisson's ratio, ν, describing transverse straining.

4.2 Conversion of Hoek-Brown to Mohr-Coulomb

In order to compare the Hoek-Brown failure criterion with the well-known Mohr-Coulomb failure criterion for practical applications involving a particular stress range, a balanced fit can be made for confining stresses in the range (considering tension positive and compression negative):

$$-\sigma_t < \sigma_3' < -\sigma'_{3,\max}$$

This gives the following expressions for the Mohr-Coulomb effective strength parameters φ' and c' (Carranza-Torres, 2004 (on page 252)):

$$\sin(\phi') = \frac{6am_b\left(s + m_b\sigma'_{3n}\right)^{a-1}}{2(1+a)(2+a) + 6am_b\left(s + m_b\sigma'_{3n}\right)^{a-1}} \qquad \textit{Eq. [100]}$$

$$c' = \frac{\left|\sigma_{ci}\right|\left[(1+2a)\,s + (1-a)\,m_b\sigma'_{3n}\right]\left(s + m_b\sigma'_{3n}\right)^{a-1}}{(1+a)(2+a)\sqrt{1 + \dfrac{6am_b\left(s + m_b\sigma'_{3n}\right)^{a-1}}{(1+a)(2+a)}}} \qquad \textit{Eq. [101]}$$

where $\sigma'_{3n} = -\sigma'_{3max} / |\sigma_{ci}|$ The upper limit of the confining stress, $\sigma'_{3,max}$, depends on the application.

4.3 Parameters of the Hoek-Brown model

The Hoek-Brown model involves a total of 8 parameters, which are generally familiar to geologists and mining engineers. These parameters with their standard units are listed below:

E_{rm}	The rock mass Young's modulus	[kN/m^2]
ν	Poisson's ratio	[-]
$\|\sigma_{ci}\|$	Uni-axial compressive strength of the intact rock (>0)	[kN/m^2]
m_i	Intact rock parameter	[-]
GSI	Geological Strength Index	[-]
D	Disturbance factor	[-]
ψ_{max}	Dilatancy angle (at $\sigma'_3 = 0$)	[°]
σ_{ψ}	Absolute value of confining pressure σ'_3 at which $\psi = 0°$	[kN/m^2]

In the *Parameters* tabsheet the rock mass intrinsic parameters are also displayed:

m_b	Rock mass parameter	[-]
s	Rock mass parameter	[-]
a	Rock mass parameter	[-]
σ_t	Rock mass tensile strength	[kN/m^2]
σ_c	Rock mass uni-axial compressive strength	[kN/m^2]

Note: Note that it is common in rock mechanics to express E, σ_{ci} and σ_{ψ}; in the unit MPa (megaPascal = MN/m^2), whereas the input values in PLAXIS are given in standard units as defined in the project properties.

The Hoek-Brown model is the most used failure criterion for rock masses, nevertheless there are some uncertainties regarding the input parameters that require a consolidated experience. For this reason, PLAXIS implements in the side panel of the *Parameters* tabsheet of the Hoek-Brown model a pre-processing tool to guide the user in the determination of the rock mass strength and stiffness parameters.

- *Analysis*: shows the Hoek-Brown failure envelope in the plane of principal effective stresses σ'_3 - σ'_1, in order to visualise the effects of changing of rock mass parameters on the failure envelope.
- The second tabsheet is specific to determine the parameter $|\sigma_{ci}|$, m_i, *GSI* and *D*. More details are given below.

4.3.1 The rock mass Young's modulus E_{rm}

In principle, Young's modulus can be measured from axial compression tests or direct shear tests on rock samples. However, this modulus is more applicable to the intact rock material, and should be reduced to obtain a representative stiffness of the in-situ rock mass. The rock mass Young's modulus E_{rm} is assumed to be a constant value for the considered rock layer. The rock mass stiffness E_{rm} can be estimated through one of the suggested empirical correlations.

- Generalised Hoek & Diederichs (2006) (on page 253):

$$E_{rm} = E_i\left(0.02 + \frac{1 - D/2}{1 + e^{(60+15D-GSI)/11}}\right) \qquad Eq.\ [102]$$

where

E_i = The intact rock modulus.
GSI = Geological strength Index.
D = Disturbance factor.

When no direct values of the intact rock modulus E_i are available or where undisturbed sampling for measurement of E_i is difficult, it is possible to estimate the intact rock modulus from the following relationship:

$$E_i = MR\sigma_{ci} \qquad Eq.\ [103]$$

where

MR = The Modulus Ratio originally proposed by Deere, 1968 (on page 252) and reported in Table 1 (on page 48) and σ_{ci} is the uni-axial compressive strength.

Table 1: Guidelines for the selection of modulus ratio (*MR*) values (Hoek & Diederichs (2006))

Name	Rock type	Texture	MR	MR±
Agglomerate	Igneous	Coarse	500	100
Amphibolites	Metamorphic	Medium	450	50
Andesite	Igneous	Medium	400	100
Anhydrite	Sedimentary	Fine	350	0
Basalt	Igneous	Fine	350	100
Breccia	Igneous	Medium	500	0
Breccia	Sedimentary	Coarse	290	60
Chalk	Sedimentary	Very fine	1000	0
Claystones	Sedimentary	Very fine	250	50
Conglomerates	Sedimentary	Coarse	350	50
Crystalline limestone	Sedimentary	Coarse	500	100
Dacite	Igneous	Fine	400	50
Diabase	Igneous	Fine	325	25
Diorite	Igneous	Medium	325	25
Dolerite	Igneous	Medium	350	50

Name	Rock type	Texture	MR	MR±
Dolomites	Sedimentary	Very fine	425	75
Gabbro	Igneous	Coarse	450	50
Gneiss	Metamorphic	Fine	525	225
Granite	Igneous	Coarse	425	125
Granodiorite	Igneous	Coarse, Medium	425	25
Greywackes	Sedimentary	Fine	350	0
Gypsum	Sedimentary	Medium	350	0
Hornfels	Metamorphic	Medium	550	150
Marble	Metamorphic	Coarse	850	150
Marls	Sedimentary	Very fine	175	25
Metasandstone	Metamorphic	Medium	250	50
Mictric limestones	Sedimentary	Fine	900	100
Migmatite	Metamorhpic	Coarse	375	25
Norite	Igneous	Coarse, Medium	375	25
Peridotite	Igneous	Very fine	275	25
Phyllites	Metamorhpic	Fine	550	250
Porphyries	Igneous	Coarse, Medium	400	0
Quartzites	Metamorhpic	Fine	375	75
Rhyolite	Igneous	Medium	400	100
Sandstones	Sedimentary	Medium	275	75
Schists	Metamorhpic	Medium	675	425
Shales	Sedimentary	Very fine	200	50
Siltstones	Sedimentary	Fine	375	25
Slates	Metamorhpic	Very fine	500	100
Sparitic limestones	Sedimentary	Medium	700	100
Tuff	Igneous	Fine	300	100

- Simplified Hoek & Diederichs (2006) (on page 253) that depends only in *GSI* and *D*:

$$E_{rm}(Mpa) = 100000\left(\frac{1 - D/2}{1 + e^{((75+25D-GSI)/11)}}\right) \qquad Eq.\ [104]$$

Note that the input of Young's modulus in PLAXIS is generally in kN/m^2 (= kPa = 10^{-3} MPa), which means that the value obtained from the above formula must be multiplied by 10^3.

4.3.2 Poisson's ratio ν

Poisson's ratio, ν, is generally in the range of 0.1 - 0.4. Typical values for particular rock types are listed in Figure 14 (on page 50).

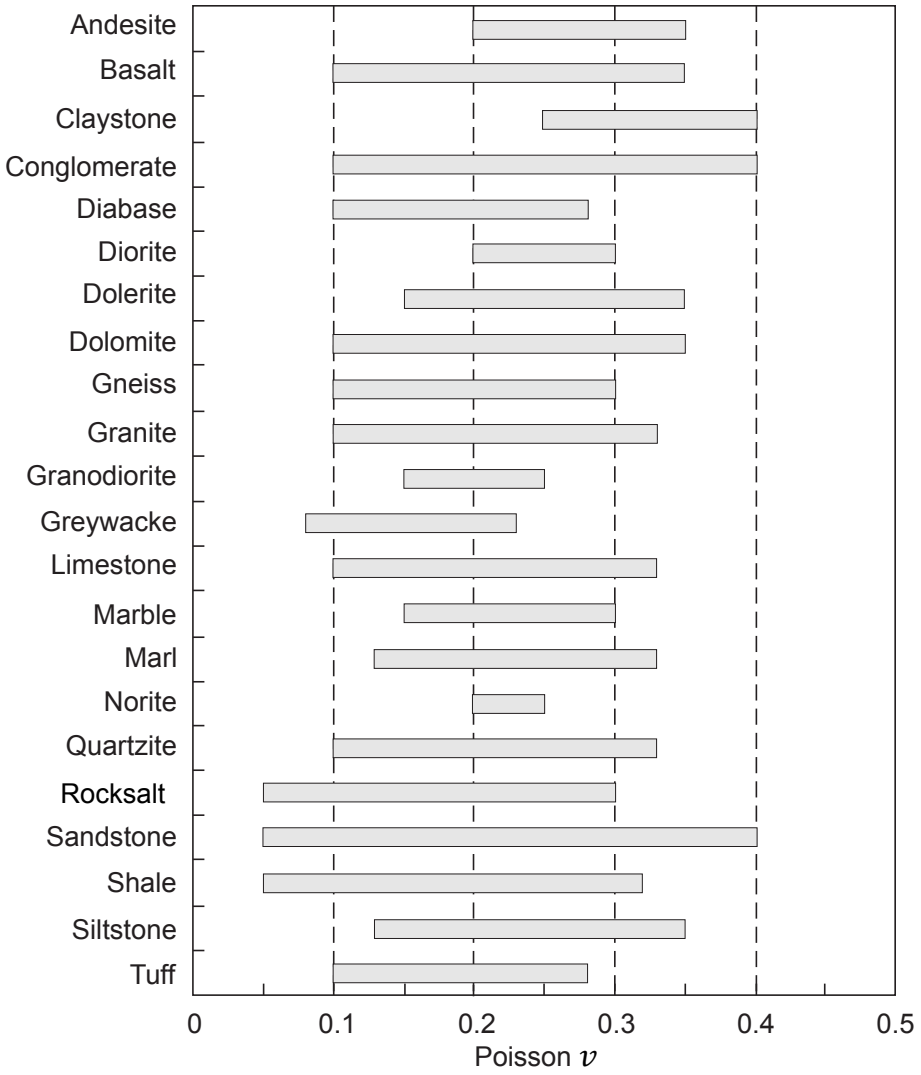


Figure 14: Typical Poisson's ratio values

4.3.3 Uni-axial compressive strength of intact rock $|\sigma_{ci}|$

The uni-axial strength of intact rock $|\sigma_{ci}|$ can be determined in laboratory testing, e.g. axial compression. Laboratory testing is often conducted on intact rock so that *GSI = 100* and *D = 0*. In accordance with estimation methods generally executed in the field (i.e. geological hammer, pocket knife), typical values are reported in the side panel of the pre-processing tool.

4.3.4 Intact rock parameter m_i

The intact rock parameter m_i is an empirical model parameter. Typical values are given in the side panel of the pre-processing tool which are based on the rock type as reported by Marinos & Hoek (2001) (on page 253) and Wyllie & Mah (2004) (on page 255) (see also Reference Manual - *Chapter 6 - Hoek-Brown pre-processing tool - Table: Values of the constant m_i for intact rock.*)

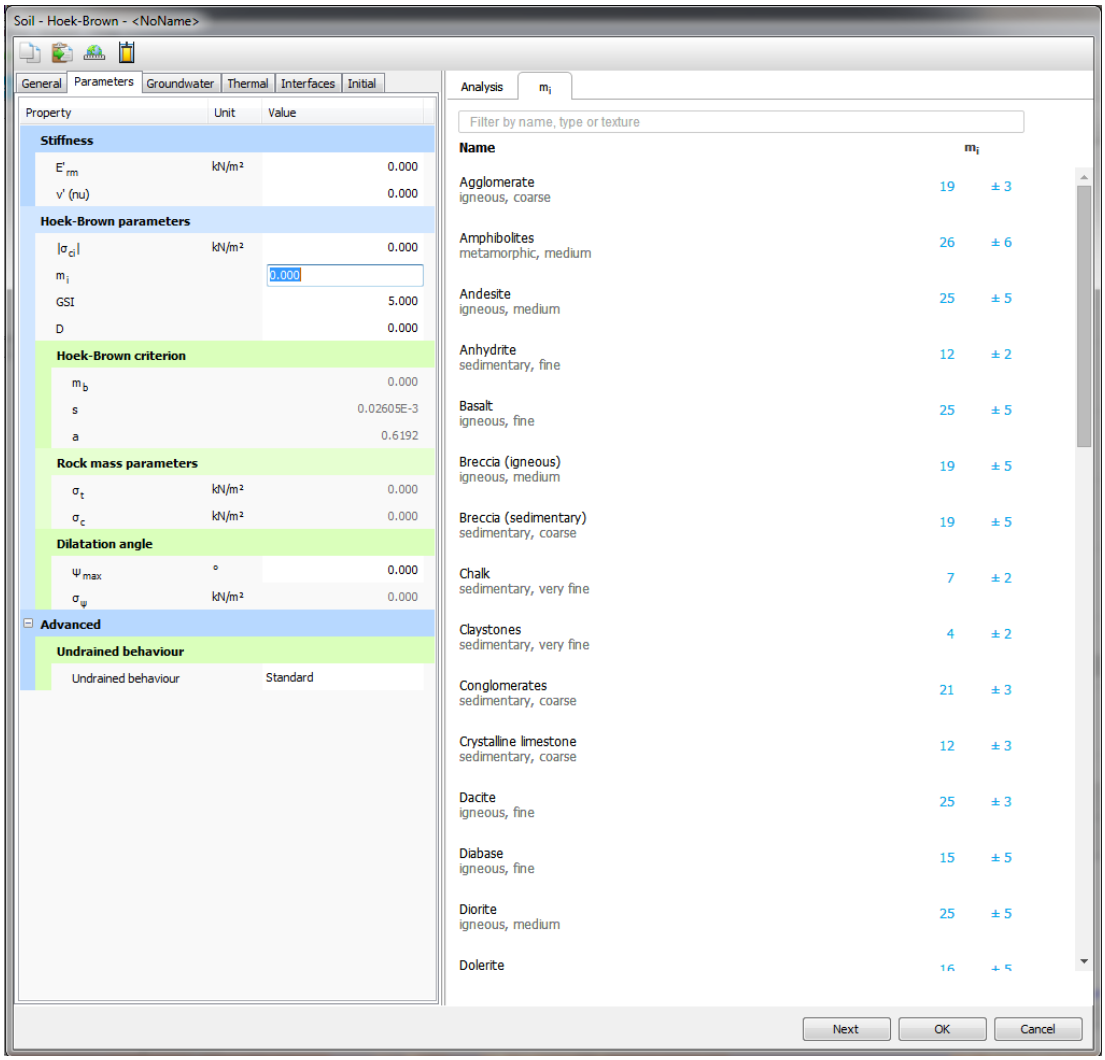


Figure 15: Intact rock parameter m_i for Hoek-Brown model

4.3.5 Geological Strength Index *GSI*

The GSI parameter can be computed thanks to the side panel of the pre-processing tool. The *GSI* tabsheet allows to choose between two rock types: *General* and *Flysch*. An intact rock is equivalent to *GSI* = 100, whereas a soil structure is in proximity to *GSI* = 0. Based on the selected rock type, the *GSI* can be chosen taking the structure and the surface conditions of the rock mass into account.

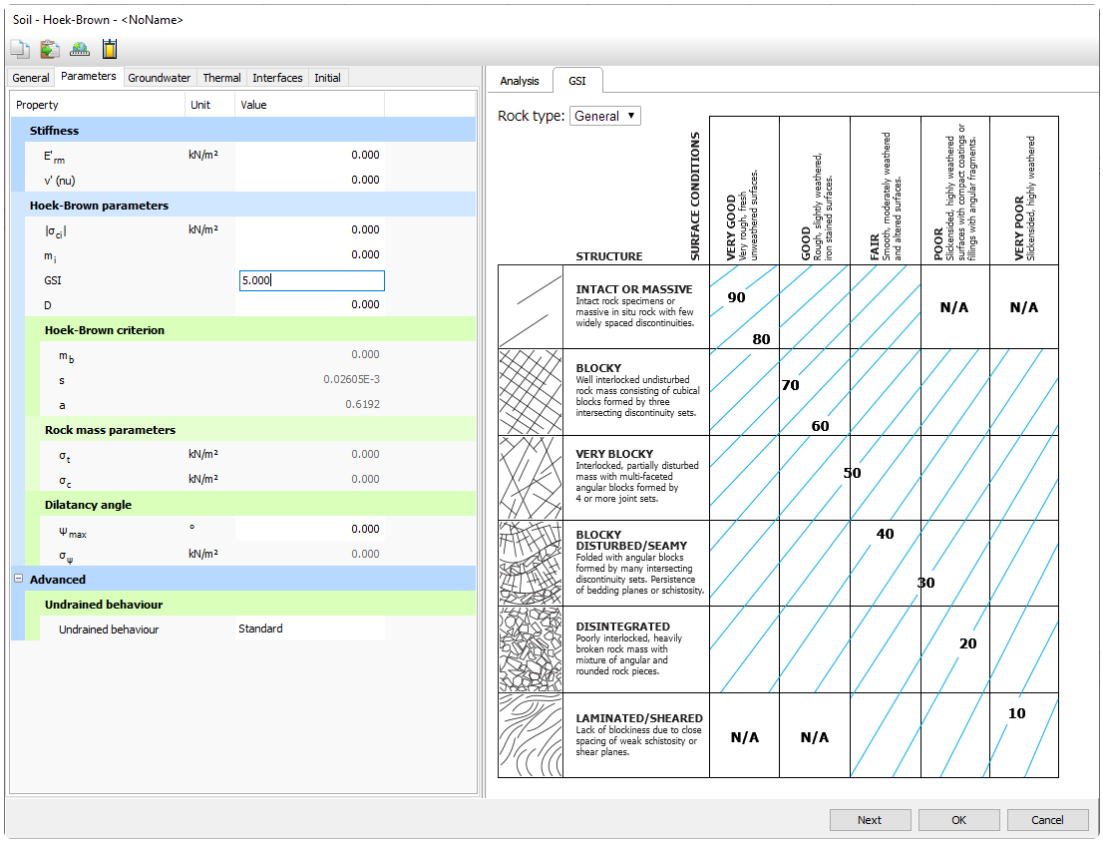


Figure 16: Geological Strength Index GSI for Hoek-Brown model

4.3.6 Disturbance factor *D*

The *Disturbance factor*, D, is a parameter that depends on the amount of disturbance of the rock as a result of mechanical processes in open excavations, tunnels or mines, such as blasting, tunnel boring, machine driven or manual excavation. No disturbance is equivalent to *D = 0*, whereas severe disturbance is equivalent to *D = 1*. For more information see Hoek (2006) (on page 253). Typical values are given in the side panel of the pre-processing tool.

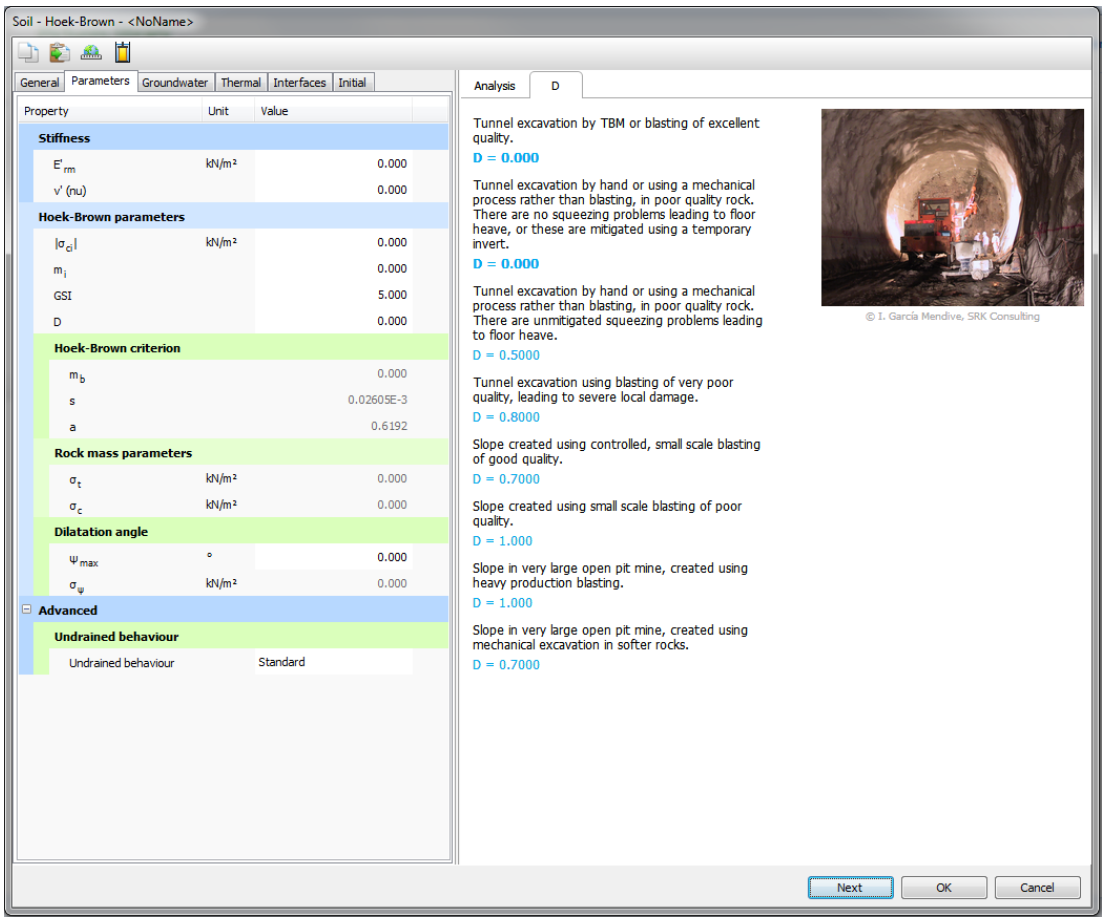


Figure 17: Disturbance factor D for Hoek-Brown model

Note: The disturbance factor *D* should only be applied to the actual zone of damaged rock in order to avoid greatly underestimation of the strength and overall stability. The thickness *T* of the blast damaged zone depends upon the design of the blast (Reference Manual- *Chapter 6- Hoek-Brown preprocessing tool*).

4.3.7 Dilatancy ψ and σ_ψ

Rocks may show dilatant material behaviour when subjected to shear under relatively low confining stress. At larger confining stress, dilatancy is suppressed. This behaviour is modelled by means of a specified value of ψ for $\sigma_3 = 0$, with a linear decrease down to zero for $\sigma'_3 = \sigma_\psi$, where σ_ψ is an additional input parameter (Figure 13 (on page 46)).

4.4 On the use of the Hoek-Brown model in dynamic calculations

When using the Hoek-Brown model in dynamic calculations, the stiffness need to be selected such that the model correctly predicts wave velocities in the soil (Eq. [83]). When subjected to dynamic or cyclic loading, the Hoek-

Brown model may generate plastic strains if stress points reach the Hoek-Brown failure criterion, which will lead to damping in dynamic calculations. However, the stress cycles within the Hoek-Brown failure contour will only generate elastic strains and no (hysteretic) damping, nor accumulation of strains or pore pressure or liquefaction. In order to simulate the rock's damping characteristics in cyclic loading, Rayleigh damping may be defined.

5 The Joined Rock model (anisotropy)

Materials may have different properties in different directions. As a result, they may respond differently when subjected to particular conditions in one direction or another. This aspect of material behaviour is called anisotropy. When modelling anisotropy, distinction can be made between elastic anisotropy and plastic anisotropy. Elastic anisotropy refers to the use of different elastic stiffness properties in different directions. Plastic anisotropy may involve the use of different strength properties in different directions, as considered in the Joined Rock model. Another form of plastic anisotropy is kinematic hardening. The latter is not considered in PLAXIS.

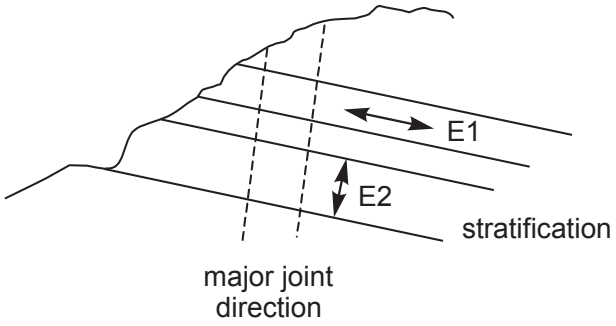


Figure 18: Visualization of concept behind the Jointed Rock model

The Joined Rock model is an anisotropic elastic perfectly-plastic model, especially meant to simulate the behaviour of stratified and jointed rock layers. In this model it is assumed that there is intact rock with an optional stratification direction and major joint directions. The intact rock is considered to behave as a transversely anisotropic elastic material, quantified by five parameters and a direction. The anisotropy may result from stratification or from other phenomena. In the major joint directions it is assumed that shear stresses are limited according to Coulomb's criterion. Upon reaching the maximum shear stress in such a direction, plastic sliding will occur. A maximum of three sliding directions ('planes') can be defined, of which the first plane is assumed to coincide with the direction of elastic anisotropy. Each plane may have different shear strength properties. In addition to plastic shearing, the tensile stresses perpendicular to the three planes are limited according to a predefined tensile strength (tension cut-off).

The application of the Joined Rock model is justified when families of joints or joint sets are present. These joint sets have to be parallel, not filled with fault gouge, and their spacing has to be small compared to the characteristic dimension of the structure.

Some basic characteristics of the Joined Rock model are:

- Anisotropic elastic behaviour for intact rock: Parameters E_1, E_2,ν_1,ν_2,G_2
- Shear failure according to Coulomb in 3 directions: Parameters c_i, φ_i and ψ_i
- Limited tensile strength in three directions: Parameters $\sigma_{t,i}$

5.1 Anisotropic elastic material stiffness matrix

The elastic material behaviour in the Joined Rock model is described by an elastic material stiffness matrix, $\mathbf{D}^*$. In contrast to Hooke's law, the D^*-matrix as used in the Jointed Rock model is transversely anisotropic. Different stiffnesses can be used normal to and in a predefined direction ('plane 1'). This direction may correspond to the stratification direction or to any other direction with significantly different elastic stiffness properties.

Consider, for example, a horizontal stratification, where the stiffness in z- direction, E_2, is different from the stiffness in the rock as a continuum, E_1. In this case the 'plane 1' direction is parallel to the xy-plane and the following constitutive relations exist (See: Zienkiewicz & Taylor: The Finite Element Method, 4th Ed.):

$$\dot{\varepsilon}_{xx} = \frac{\dot{\sigma}_{xx}}{E_1} - \frac{\upsilon_1 \dot{\sigma}_{yy}}{E_1} - \frac{\upsilon_2 \dot{\sigma}_{zz}}{E_2} \quad a)$$

$$\dot{\varepsilon}_{yy} = \frac{\upsilon_1 \dot{\sigma}_{xx}}{E_1} + \frac{\dot{\sigma}_{yy}}{E_1} - \frac{\upsilon_2 \dot{\sigma}_{zz}}{E_2} \quad b)$$

$$\dot{\varepsilon}_{zz} = \frac{\upsilon_2 \dot{\sigma}_{xx}}{E_2} - \frac{\upsilon_2 \dot{\sigma}_{yy}}{E_2} + \frac{\dot{\sigma}_{zz}}{E_2} \quad c)$$

$$\dot{\gamma}_{xy} = \frac{2(1+\upsilon_1)}{E_1}\sigma_{xy} \quad d)$$

$$\dot{\gamma}_{yz} = \frac{\dot{\sigma}_{yz}}{G_2} \quad e)$$

$$\dot{\gamma}_{zx} = \frac{\dot{\sigma}_{zx}}{G_2} \quad f)$$

Eq. [105]

The inverse of the anisotropic elastic material stiffness matrix, $(\mathbf{D}^*)^{-1}$, follows from the above relations. This matrix is symmetric. The regular material stiffness matrix $\mathbf{D}^*$ can only be obtained by numerical inversion.

In order for the D^* to remain positive definite, the following requirement has to be obeyed:

$$\upsilon_2 < \sqrt{\frac{E_2}{E_1}\left(\frac{1-\upsilon_1}{2}\right)} \qquad \textit{Eq. [106]}$$

In general, the stratification plane will not be parallel to the global xy-plane, but the above relations will generally hold for a local (*n*,*s*,*t*) coordinate system where the stratification plane is parallel to the st-plane. The orientation of this plane is defined by the *dip angle* (or shortly *dip*) and *strike* (see Parameters of the Joined Rock model (on page 60)). As a consequence, the local material stiffness matrix has to be transformed from the local to the global coordinate system. Therefore we consider first a transformation of stresses and strains:

$$\sigma_{nst} = \mathbf{R}_\sigma \sigma_{xyz} \qquad \sigma_{xyz} = \mathbf{R}_\sigma \sigma_{nst} \qquad \textit{Eq. [107]}$$

$$\varepsilon_{nst} = \mathbf{R}_\varepsilon \varepsilon_{xyz} \qquad \varepsilon_{xyz} = \mathbf{R}_\varepsilon \varepsilon_{nst} \qquad \textit{Eq. [108]}$$

where

$$\mathbf{R}_\sigma = \begin{bmatrix} n_x^2 & n_y^2 & n_z^2 & 2n_xn_y & 2n_yn_z & 2n_xn_z \\ s_x^2 & s_y^2 & s_z^2 & 2s_xs_y & 2s_ys_z & 2s_xs_z \\ t_x^2 & t_y^2 & t_z^2 & 2t_xt_y & 2t_yt_z & 2t_xt_z \\ n_xs_x & n_ys_y & n_zs_z & n_xs_y+n_ys_x & n_ys_z+n_zs_y & n_zs_x+n_xs_z \\ s_xt_x & s_yt_y & s_zt_z & s_xt_y+s_yt_x & s_yt_z+s_zt_y & s_xt_z+s_zt_x \\ n_xt_x & n_yt_y & n_zt_z & n_xt_y+n_yt_x & n_yt_z+n_zt_y & n_zt_x+n_xs_z \end{bmatrix} \qquad \textit{Eq. [109]}$$

and

$$\mathbf{R}_\varepsilon = \begin{bmatrix} n_x^2 & n_y^2 & n_z^2 & n_xn_y & n_yn_z & n_xn_z \\ s_x^2 & s_y^2 & s_z^2 & s_xs_y & s_ys_z & s_xs_z \\ t_x^2 & t_y^2 & t_z^2 & t_xt_y & t_yt_z & t_xt_z \\ 2n_xs_x & 2n_ys_y & 2n_zs_z & n_xs_y+n_ys_x & n_ys_z+n_zs_y & n_zs_x+n_xs_z \\ 2s_xt_x & 2s_yt_y & 2s_zt_z & s_xt_y+s_yt_x & s_yt_z+s_zt_y & s_xt_z+s_zt_x \\ 2n_xt_x & 2n_yt_y & 2n_zt_z & n_xt_y+n_yt_x & n_yt_z+n_zt_y & n_zt_x+n_xs_z \end{bmatrix} \qquad \textit{Eq. [110]}$$

n_x, n_y, n_z, s_x, s_y, s_z, t_x, t_y and t_z are the components of the normalised n, s and t-vectors in global (x,y,z)-coordinates (i.e. 'sines' and 'cosines'; see Parameters of the Joined Rock model (on page 60)). For plane strain condition $n_z = s_z = t_x = t_y = 0$ and $t_z = 1$.

It further holds that:

$$\mathbf{R}_\varepsilon^T = \mathbf{R}_\sigma^{-1} \qquad \mathbf{R}_\sigma^T = \mathbf{R}_\varepsilon^{-1} \qquad \textit{Eq. [111]}$$

A local stress-strain relationship in (n,s,t)-coordinates can be transformed to a global relationship in (x,y,z)-coordinates in the following way:

$$\left.\begin{aligned} \sigma_{nst} &= \mathbf{D}^*_{nst}\varepsilon_{nst} \\ \sigma_{nst} &= \mathbf{R}^*_{nst}\sigma_{xyz} \\ \varepsilon_{nst} &= \mathbf{R}^*_{nst}\varepsilon_{xyz} \end{aligned}\right\} \Rightarrow \mathbf{R}_\sigma\sigma_{xyz} = \mathbf{D}^*_{nst}\mathbf{R}_\varepsilon\varepsilon_{xyz} \qquad \textit{Eq. [112]}$$

Hence,

$$\sigma_{xyz} = \mathbf{R}_\sigma^{-1}\mathbf{D}^*_{nst}\mathbf{R}_\varepsilon\varepsilon_{xyz} \qquad \textit{Eq. [113]}$$

Using to above condition (Eq. [111])

$$\sigma_{xyz} = \mathbf{R}_\varepsilon^T\mathbf{D}^*_{nst}\mathbf{R}_\varepsilon\varepsilon_{xyz} = \mathbf{D}^*_{xyz}\varepsilon_{xyz} \qquad \textit{or} \qquad \mathbf{D}^*_{xyz} = \mathbf{R}_\varepsilon^T\mathbf{D}^*_{nst}\mathbf{R}_\varepsilon \qquad \textit{Eq. [114]}$$

Actually, not the D^*-matrix is given in local coordinates but the inverse matrix ($\mathbf{D}^{*-1}$).

$$\left.\begin{aligned} \varepsilon_{nst} &= \mathbf{D}^*_{nst}\sigma_{nst} \\ \sigma_{nst} &= \mathbf{R}^*_\sigma\sigma_{xyz} \\ \varepsilon_{nst} &= \mathbf{R}^*_\varepsilon\varepsilon_{xyz} \end{aligned}\right\} \Rightarrow \varepsilon_{xyz} = \mathbf{R}_\varepsilon^{-1}\,\mathbf{D}^{*-1}_{nst}\mathbf{R}_\sigma\sigma_{xyz} = \mathbf{R}_\varepsilon^T\,\mathbf{D}^{*-1}_{nst}\mathbf{R}_\sigma\sigma_{xyz} \qquad \textit{Eq. [115]}$$

Hence,

$$\mathbf{D}^{*}_{xyz}{}^{-1} = \mathbf{R}_{\sigma}^{T}\ \mathbf{D}^{*}_{nst}{}^{-1}\mathbf{R}_{\sigma} \qquad or \qquad \mathbf{D}^{*}_{xyz} = \left[\mathbf{R}_{\sigma}^{T}\mathbf{D}^{*}_{nst}{}^{-1}\mathbf{R}_{\sigma}\right]^{-1} \qquad Eq.\ [116]$$

Instead of inverting the ($\mathbf{D}^{*}_{nst}{}^{-1}$)-matrix in the first place, the transformation is considered first, after which the total is numerically inverted to obtain the global material stiffness matrix $\mathbf{D}^{*}_{xyz}$.

5.2 Plastic behaviour in three directions

A maximum of 3 sliding directions (sliding planes) can be defined in the Joined Rock model. The first sliding plane corresponds to the direction of elastic anisotropy. In addition, a maximum of two other sliding directions may be defined. However, the formulation of plasticity on all planes is similar. On each plane a local Coulomb condition applies to limit the shear stress, $|\tau|$. Moreover, a tension cut-off criterion is used to limit the tensile stress on a plane. Each plane, i, has its own strength parameters c_i, φ_i, ψ_i and $\sigma_{t,i}$.

In order to check the plasticity conditions for a plane with local (n, s, t)-coordinates it is necessary to calculate the local stresses from the Cartesian stresses. The local stresses involve three components, i.e. a normal stress component, σ_n, and two independent shear stress components, τ_s and τ_t.

$$\underline{\sigma}_i = \mathbf{T}_i^{T}\,\underline{\sigma} \qquad Eq.\ [117]$$

where

$$\underline{\sigma} = (\sigma_n \ \ \tau_s \ \ \tau_t)^{T} \qquad a)$$

$$\underline{\sigma} = (\sigma_{xx} \ \ \sigma_{yy} \ \ \sigma_{zz} \ \ \sigma_{xy} \ \ \sigma_{yz} \ \ \sigma_{zx})^{T} \qquad b) \qquad Eq.\ [118]$$

$$\mathbf{T}_i^{T} = transformation\ matrix\ (3x6),\ \ for\ plane\ i$$

As usual in PLAXIS, tensile (normal) stresses are defined as positive whereas compression is defined as negative.

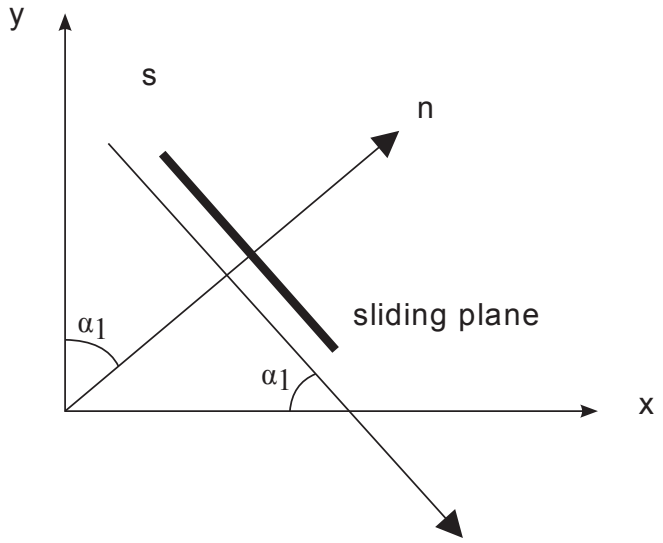


Figure 19: Plane strain situation with a single sliding plane and vectors n, s

Consider a plane strain situation as visualised in Figure 19 (on page 58). Here a sliding plane is considered under an angle α_1 (= *dip*) with respect to the *x*-axis. In this case the transformation matrix $\mathbf{T}^T$ becomes:

$$\mathbf{T}^T = \begin{bmatrix} s^2 & c^2 & 0 & -2sc & 0 & 0 \\ sc & -sc & 0 & -s^2+c^2 & 0 & 0 \\ 0 & 0 & 0 & 0 & -c & -c \end{bmatrix} \qquad \textit{Eq. [119]}$$

where:

$$s = \sin(\alpha_1)$$

$$c = \cos(\alpha_1)$$

In the general three-dimensional case the transformation matrix is more complex, since it involves both *dip* and *strike* (see Parameters of the Joined Rock model (on page 60)):

$$\mathbf{T}^T = \begin{bmatrix} n_x^2 & n_y^2 & n_z^2 & 2n_xn_y & 2n_yn_z & 2n_zn_x \\ n_xs_x & n_ys_y & n_zs_z & n_xs_y+n_ys_x & n_zs_y+n_ys_z & n_zs_x+n_xs_z \\ n_xt_x & n_yt_y & n_zt_z & n_yt_x+n_xt_y & n_yt_z+n_zt_y & n_zt_x+n_xt_z \end{bmatrix} \qquad \textit{Eq. [120]}$$

Note that the general transformation matrix, **T**, for the calculation of local stresses corresponds to rows 1, 4 and 6 of $\mathbf{R}_\sigma$ (see Eq. [109]).

After having determined the local stress components, the plasticity conditions can be checked on the basis of yield functions. The yield functions for plane *i* are defined as:

$$\begin{aligned} f_i^c &= |\tau_s| + \sigma_n \tan(\alpha_i) - c_i \qquad (Coulomb) \\ f_i^c &= \sigma_n - \sigma_{t,i} (\sigma_{t,i} \le c_i \cot(\phi_i)) \qquad (Tension\ cut-off) \end{aligned} \qquad \textit{Eq. [121]}$$

Figure 20 (on page 59) visualizes the full yield criterion on a single plane.

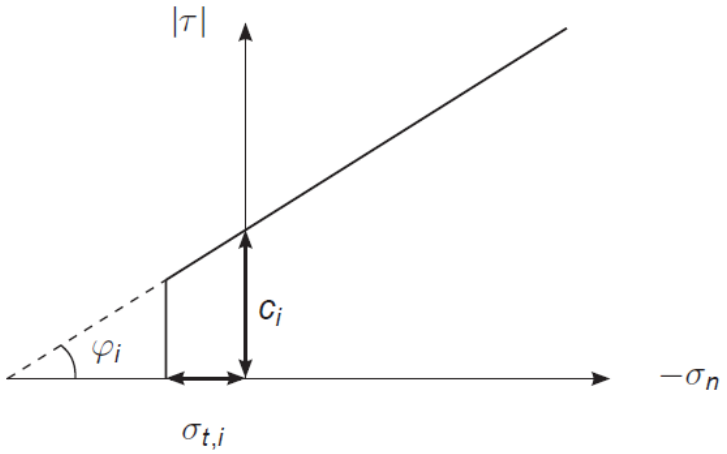


Figure 20: Yield criterion for individual plane

The local plastic strains are defined by:

$$\Delta\varepsilon_j^p = \lambda_j \frac{\partial g_j^c}{\partial \sigma_j} \qquad \textit{Eq. [122]}$$

where g_j is the local plastic potential function for plane j:

$$\begin{aligned} g_i^c &= \mid \tau_j \mid + \sigma_n \tan(\psi_i) - c_i \qquad (Coulomb) \\ g_i^c &= \sigma_n - \sigma_{t,i} \qquad (Tension\ cut-off) \end{aligned} \qquad \textit{Eq. [123]}$$

The transformation matrix, **T**, is also used to transform the local plastic strain increments of plane *j*, $\Delta\varepsilon_j^p$, into global plastic strain increments, $\Delta\varepsilon^p$:

$$\Delta\varepsilon^p = \mathbf{T}_j \Delta\varepsilon_j^p \qquad \textit{Eq. [124]}$$

The consistency condition requires that at yielding the value of the yield function must remain zero for all active yield functions. For all planes together, a maximum of 6 yield functions exist, so up to 6 plastic multipliers must be found such that all yield functions are at most zero and the plastic multipliers are non-negative.

$$\begin{aligned} f_i^c &= f_i^{c(e)} - \sum_{j=1}^{np} <\lambda_j^c> \frac{\partial f_i^c}{\partial \sigma}^T T_i^T DT_j \frac{\partial g_j^c}{\partial \sigma} - \sum_{j=1}^{np} <\lambda_j^t> \frac{\partial f_i^c}{\partial \sigma}^T T_i^T DT_j \frac{\partial g_j^t}{\partial \sigma} \\ f_i^t &= f_i^{t(e)} - \sum_{j=1}^{np} <\lambda_j^c> \frac{\partial f_i^t}{\partial \sigma}^T T_i^T DT_j \frac{\partial g_j^c}{\partial \sigma} - \sum_{j=1}^{np} <\lambda_j^t> \frac{\partial f_i^t}{\partial \sigma}^T T_i^T DT_j \frac{\partial g_j^t}{\partial \sigma} \end{aligned} \qquad \textit{Eq. [125]}$$

This means finding up to 6 values of $\lambda_i \geq 0$ such that all $f_i \leq 0$ and $\lambda_i f_i = 0$.

When the maximum of 3 planes are used, there are $2^6 = 64$ possibilities of (combined) yielding. In the calculation process, all these possibilities are taken into account in order to provide an exact calculation of stresses.

5.3 Parameters of the Joined Rock model

Most parameters of the Joined Rock model coincide with those of the isotropic Mohr-Coulomb model. These are the basic elastic parameters and the basic strength parameters.

Elastic parameters as in Mohr-Coulomb model (see Basic parameters of the Mohr-Coulomb model (on page 35))		
E_1	Young's modulus for rock as a continuum	[kN/m^2]
ν_1	Poisson's ratio for rock as a continuum	[-]

Anisotropic elastic parameters 'Plane 1' direction (e.g. stratification direction)		
E_2	Young's modulus perpendicular to 'Plane 1' direction	[kN/m^2]

Anisotropic elastic parameters 'Plane 1' direction (e.g. stratification direction)		
G_2	Shear modulus perpendicular to 'Plane 1' direction	[kN/m^2]
ν_2	Poisson's ratio perpendicular to 'Plane 1' direction $\nu_2 < \sqrt{\frac{E_2}{E_1}\left(\frac{1-\nu_1}{2}\right)}$	[-]

Strength parameters in joint directions (Plane i=1, 2, 3):		
c_i	Cohesion	[kN/m^2]
φ_i	Friction angle	[°]
ψ_i	Dilatancy angle	[°]
$\sigma_{t,i}$	Tensile strength	[kN/m^2]

Definition of joint directions (Plane i=1, 2, 3):		
Number of planes	Number of joint directions ($1 \leq n \leq 3$)	[-]
$\alpha_{1,i}$	Dip ($-180 \leq \alpha_{1,i} \leq 180$)	[°]
$\alpha_{2,i}$	Strike ($-180 \leq \alpha_{2,i} \leq 180$) ($\alpha_{2,i}$ = 90 in PLAXIS 2D)	[°]

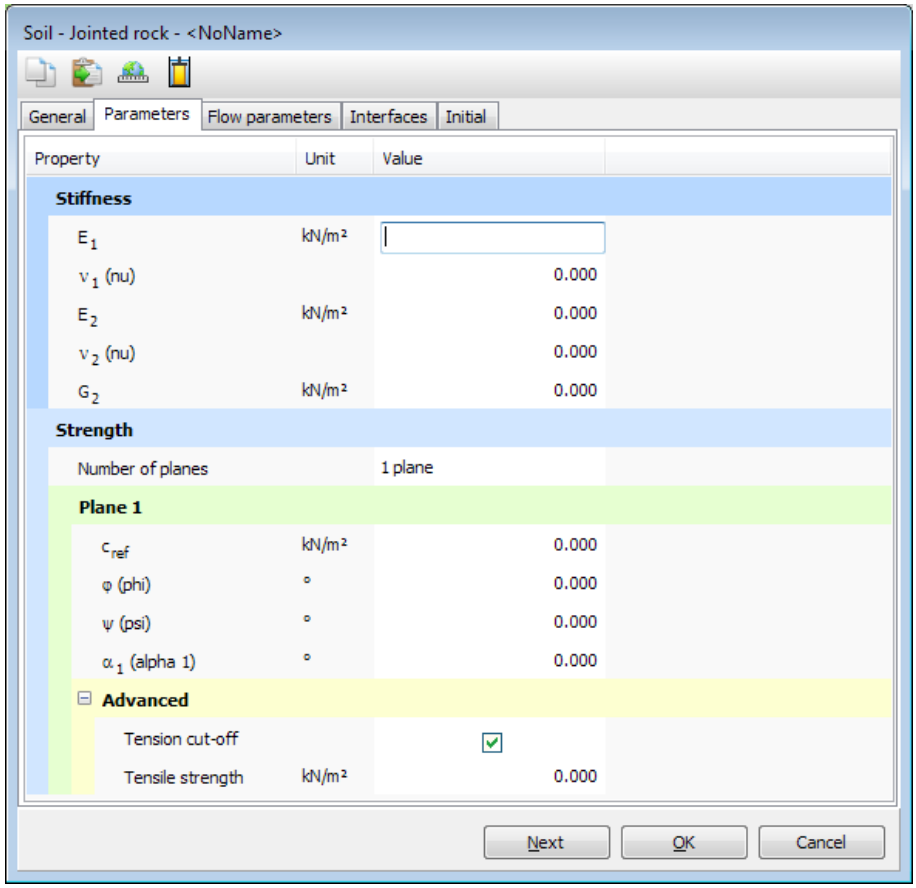


Figure 21: Parameters for theJoined Rock model

5.3.1 *Elastic parameters*

The elastic parameters E_1 and ν_1 are the (constant) stiffness (Young's modulus) and Poisson's ratio of the rock as a continuum according to Hooke's law, i.e. as if it would not be anisotropic.

Elastic anisotropy in a rock formation may be introduced by stratification. The stiffness perpendicular to the stratification direction is usually reduced compared with the general stiffness. This reduced stiffness can be represented by the parameter E_2, together with a second Poisson's ratio, ν_2. In general, the elastic stiffness normal to the direction of elastic anisotropy is defined by the parameters E_2 and ν_2. In order to avoid singularity of the material stiffness matrix, the input of ν_2 is limited by:

$$\upsilon_2 < \sqrt{\frac{E_2}{E_1}\left(\frac{1-\upsilon_1}{2}\right)} \qquad \textit{Eq. [126]}$$

Elastic shearing in the stratification direction is also considered to be 'weaker' than elastic shearing in other directions. In general, the shear stiffness in the anisotropic direction can explicitly be defined by means of the elastic shear modulus G_2. In contrast to Hooke's law of isotropic elasticity, G_2 is a separate parameter and is not simply related to Young's modulus by means of Poisson's ratio (see 22 d) and 22 e)).

If the elastic behaviour of the rock is fully isotropic, then the parameters E_2 and ν_2 can be simply set equal to E_1 and ν_1 respectively, whereas G_2 should be set to $1/2E_1/(1+\nu_1)$.

5.3.2 *Strength parameters*

Each sliding direction (plane) has its own strength properties c_i, φ_i and $\sigma_{t,i}$ and dilatancy angle ψ_i. The strength properties c_i and φ_i determine the allowable shear strength according to Coulomb's criterion and σ_t determines the tensile strength according to the tension cut-off criterion. The latter is displayed after pressing *Advanced* button. By default, the tension cut-off is active and the tensile strength is set to zero. The dilatancy angle, ψ_i, is used in the plastic potential function g, and determines the plastic volume expansion due to shearing.

5.3.3 *Definition of joint directions*

It is assumed that the direction of elastic anisotropy corresponds with the first direction where plastic shearing may occur ('plane 1'). This direction must always be specified. In the case the rock formation is stratified without major joints, the *number of sliding planes* (= sliding directions) is still 1, and strength parameters must be specified for this direction anyway. A maximum of three sliding directions can be defined. These directions may correspond to the most critical directions of joints in the rock formation.

The sliding directions are defined by means of two parameters: The *Dip angle* (α_1) (or shortly *Dip*) and the *Strike* (α_2). The definition of both parameters is visualised in Figure 22 (on page 64).

Consider a sliding plane, as indicated in Figure 22 (on page 64). The sliding plane can be defined by the vectors (s,t), which are both normal to the vector n. The vector n is the 'normal' to the sliding plane, whereas the vector s is the 'fall line' of the sliding plane (*dip*) and the vector t is the 'horizontal line' of the sliding plane (*strike*). The sliding plane makes an angle α_1 with respect to the horizontal plane, where the horizontal plane can be defined by the vectors (s^*,t), which are both normal to the vertical axis. The angle α_1 is the *dip*, which is defined as the positive 'downward' inclination angle between the horizontal plane and the sliding plane. Hence, α_1 is the angle between the vectors s^* and s, measured clockwise from s^* to s when looking in the positive t-direction. The dip ought to be entered in the range [0°, 90°], but negative values as well as values larger than 90° can also be entered.

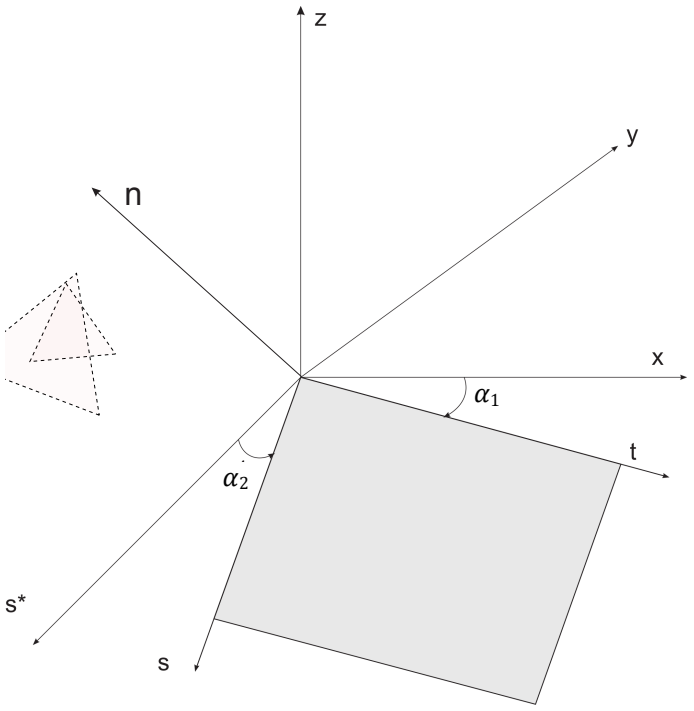


Figure 22: Definition of dip angle and strike

The orientation of the sliding plane is further defined by the *strike*, α_2, which is defined in PLAXIS as the orientation of the vector *t* with respect to the *x*-direction. The strike is defined as the positive angle from the *x*-direction, measured clockwise to the *t*-axis. The dip direction is entered in the range [-180°, 180°].

From the definitions as given above, it follows for PLAXIS 3D that:

$$\underline{n} = \begin{bmatrix} n_x \\ n_y \\ n_z \end{bmatrix} = \begin{bmatrix} -\sin(\alpha_1)\sin(\alpha_2) \\ -\sin(\alpha_1)\cos(\alpha_2) \\ \cos(\alpha_1) \end{bmatrix} \qquad \textit{Eq. [127]}$$

$$\underline{s} = \begin{bmatrix} s_x \\ s_y \\ s_z \end{bmatrix} = \begin{bmatrix} -\cos(\alpha_1)\sin(\alpha_2) \\ -\cos(\alpha_1)\cos(\alpha_2) \\ -\sin(\alpha_1) \end{bmatrix} \qquad \textit{Eq. [128]}$$

$$\underline{t} = \begin{bmatrix} t_x \\ t_y \\ t_z \end{bmatrix} = \begin{bmatrix} \cos(\alpha_2) \\ -\sin(\alpha_2) \\ -\sin(\alpha_1) \end{bmatrix} \qquad \textit{Eq. [129]}$$

whereas for PLAXIS 2D α_2 is taken by definition as $\alpha_2 = 90°$, such that:

$$\underline{n} = \begin{bmatrix} n_x \\ n_y \\ n_z \end{bmatrix} = \begin{bmatrix} -\sin(\alpha_1) \\ \cos(\alpha_1) \\ 0 \end{bmatrix} \qquad \textit{Eq. [130]}$$

$$\underline{s} = \begin{bmatrix} s_x \\ s_y \\ s_z \end{bmatrix} = \begin{bmatrix} -\cos(\alpha_1) \\ -\sin(\alpha_2) \\ 0 \end{bmatrix} \qquad \textit{Eq. [131]}$$

$$\underline{t} = \begin{bmatrix} t_x \\ t_y \\ t_z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \qquad \textit{Eq. [132]}$$

Figure 23 (on page 65) shows some examples of how sliding planes occur in a 3D models for different values of α_1 and α_2. As it can be seen, for plane strain conditions (the cases considered in PLAXIS 2D) only α_1 is required. By default, α_2 is fixed at 90°.

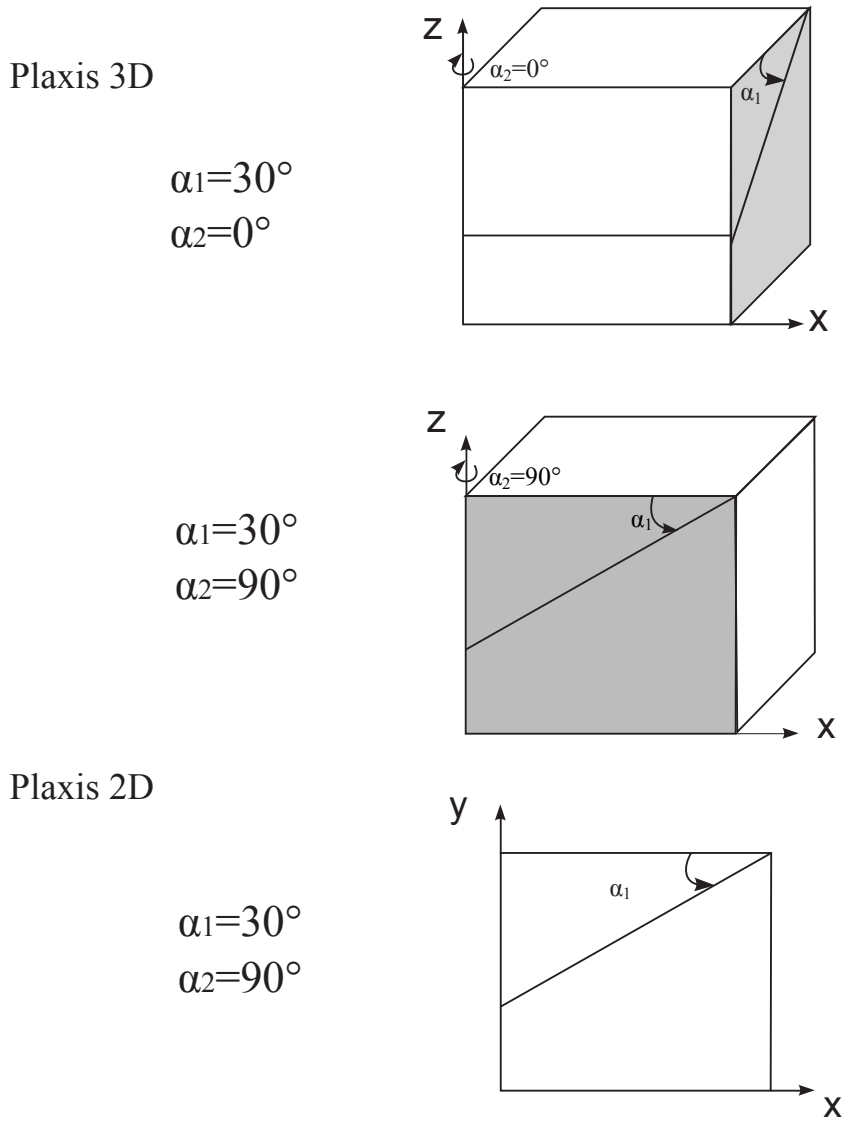


Figure 23: Examples of failure directions defined by α1 and α2

5.4 On the use of the Joined Rock model in dynamic calculations

When using the Joined Rock model in dynamic calculations, the stiffness need to be selected such that the model correctly predicts wave velocities in the soil (Equation Eq. [83]). When subjected to dynamic or cyclic loading, the Joined Rock model may generate plastic strains if stress points reach the Coulomb failure criterion, which will lead to damping in dynamic calculations. However, it should be noted that stress cycles within the Coulomb failure contour will only generate elastic strains and no (hysteretic) damping, nor accumulation of strains or pore pressure or liquefaction. In order to simulate the rock's damping characteristics in cyclic loading, Rayleigh damping may be defined.

Note: A slightly modified version of the Joined Rock model with generalised Mohr-Coulomb failure criterion in addition to the individual failure directions is available as user-defined soil model. Contact Plaxis for more information.

Note:

- In a geological context, *strike* is defined as the angle from the North to the *strike* of the *dipping plane* (positive towards East direction), whereas in PLAXIS definition *strike* is defined from the global *x-direction* to the strike of the dipping plane (with the same positive rotation direction). If we define the angle from the North direction to the *x-direction* of the PLAXIS model as declination, then strike in PLAXIS is the geological strike minus declination.
- Moreover, there might be confusion between true *strike* and its opposite direction (*180°* direction). Hence, care must be taken when translating *strike* from geological data into PLAXIS input.

6 The Hardening Soil model (Isotropic hardening)

In contrast to an elastic perfectly-plastic model, the yield surface of a hardening plasticity model is not fixed in principal stress space, but it can expand due to plastic straining. Distinction can be made between two main types of hardening, namely shear hardening and compression hardening. Shear hardening is used to model irreversible strains due to primary deviatoric loading. Compression hardening is used to model irreversible plastic strains due to primary compression in oedometer loading and isotropic loading. Both types of hardening are contained in the present model.

The Hardening Soil model is an advanced model for simulating the behaviour of different types of soil, both soft soils and stiff soils, Shanz (1998) (on page 254). When subjected to primary deviatoric loading, soil shows a decreasing stiffness and simultaneously irreversible plastic strains develop. In the special case of a drained triaxial test, the observed relationship between the axial strain and the deviatoric stress can be well approximated by a hyperbola. Such a relationship was first formulated by Kondner (1963) (on page 253) and later used in the well-known hyperbolic model (Duncan & Chang, 1970) (on page 252). The Hardening Soil model, however, supersedes the hyperbolic model by far: Firstly by using the theory of plasticity rather than the theory of elasticity, secondly by including soil dilatancy and thirdly by introducing a yield cap. Some basic characteristics of the model are:

- Stress dependent stiffness according to a power law: Input parameter m
- Plastic straining due to primary deviatoric loading: Input parameter E_{50}^{ref}
- Plastic straining due to primary compression: Input parameter E_{oed}^{ref}
- Elastic unloading / reloading: Input parameters E_{ur}^{ref}, ν_{ur}
- Failure according to the Mohr-Coulomb failure criterion: Parameters c, φ and ψ

A basic feature of the present Hardening Soil model is the stress dependency of soil stiffness. For oedometer conditions of stress and strain, the model implies for example the relationship $E_{oed} = E_{oed}^{ref} (\sigma / p^{ref})^m$. In the special case of soft soils it is realistic to use $m = 1$. In such situations there is also a simple relationship between the modified compression index λ^*, as used in models for soft soil and the oedometer loading modulus (see also Parameters of the Soft Soil Creep model (on page 128)).

$$E_{oed}^{ref} = \frac{p^{ref}}{\lambda^*} \qquad \lambda^* = \frac{\lambda}{(1 + e_0)} \qquad Eq.\ [133]$$

where p^{ref} is a reference pressure. Here we consider a tangent oedometer modulus at a particular reference pressure p^{ref}. Hence, the primary loading stiffness relates to the modified compression index λ^* or to the standard Cam-Clay compression index λ.

Similarly, the unloading-reloading modulus relates to the modified swelling index κ^* or to the standard Cam-Clay swelling index κ. There is the approximate relationship:

$$E_{oed}^{ref} \approx \frac{p^{ref}}{\kappa^*} \qquad k^* = \frac{k}{(1+e_0)} \qquad Eq.\ [134]$$

This relationship applies in combination with the input value $m = 1$.

6.1 Hyperbolic relationship for standard drained triaxial test

A basic idea for the formulation of the Hardening Soil model is the hyperbolic relationship between the vertical strain, ε_1, and the deviatoric stress, q, in primary triaxial loading. Here standard drained triaxial tests tend to yield curves that can be described by:

$$-\varepsilon_1 = \frac{1}{E_i}\frac{q}{1 - q/q_a} \quad for:\ q < q_r \qquad Eq.\ [135]$$

where

qa = Asymptotic value of the shear strength.
E_i = Initial stiffness.

E_i is related to E_{50} by:

$$E_i = \frac{2E_{50}}{2 - R_f} \qquad Eq.\ [136]$$

This relationship is plotted in Figure 24 (on page 69). The parameter E_{50} is the confining stress dependent stiffness modulus for primary loading and is given by the equation:

$$E_{50} = E_{50}^{ref}\left(\frac{c\cos(\varphi) - \sigma_3'\sin(\varphi)}{c\cos(\varphi) - p^{ref}\sin(\varphi)}\right)^m \qquad Eq.\ [137]$$

where

E_{50}^{ref} = Reference stiffness modulus corresponding to the reference confining pressure p^{ref}.

In PLAXIS, a default setting $p^{ref} = 100$ stress units is used. The actual stiffness depends on the minor principal stress, σ'_3, which is the confining pressure in a triaxial test. Please note that σ'_3 is negative for compression. The amount of stress dependency is given by the power m. In order to simulate a logarithmic compression behaviour, as observed for soft clays, the power should be taken equal to 1.0. Janbu (1963) (on page 253) reports values of m around 0.5 for Norwegian sands and silts, whilst von Soos (1990) (on page 255) reports various different values in the range $0.5 < m < 1.0$.

The ultimate deviatoric stress, q_f, and the quantity q_a in Eq. [135] are defined as:

$$q_f = (c\cot(\varphi) - \sigma_3')\frac{2\sin(\varphi)}{1 - \sin(\varphi)} \qquad and: \qquad q_a = \frac{q_f}{R_f} \qquad Eq.\ [138]$$

Again it is remarked that σ'_3 is usually negative. The above relationship for q_f is derived from the Mohr-Coulomb failure criterion, which involves the strength parameters c and φ. As soon as $q = q_f$, the failure criterion is satisfied and perfectly plastic yielding occurs as described by the Mohr-Coulomb model.

The ratio between q_f and q_a is given by the failure ratio R_f, which should obviously be smaller than or equal to 1. In PLAXIS, $R_f = 0.9$ is chosen as a suitable default setting.

For unloading and reloading stress paths, another stress-dependent stiffness modulus is used:

$$E_{ur} = E_{ur}^{ref}\left(\frac{c\cos(\varphi) - \sigma_3^{'}\sin(\varphi)}{c\cos(\varphi) - p^{ref}\sin(\varphi)}\right)^{m} \qquad Eq.\ [139]$$

where

E_{ur}^{ref} = Reference Young's modulus and reloading, corresponding to the reference pressure p^{ref}.

Note: In many practical cases it is appropriate to set E_{ur}^{ref} equal to $3E_{ur}^{ref}$; this is the default setting used in PLAXIS.

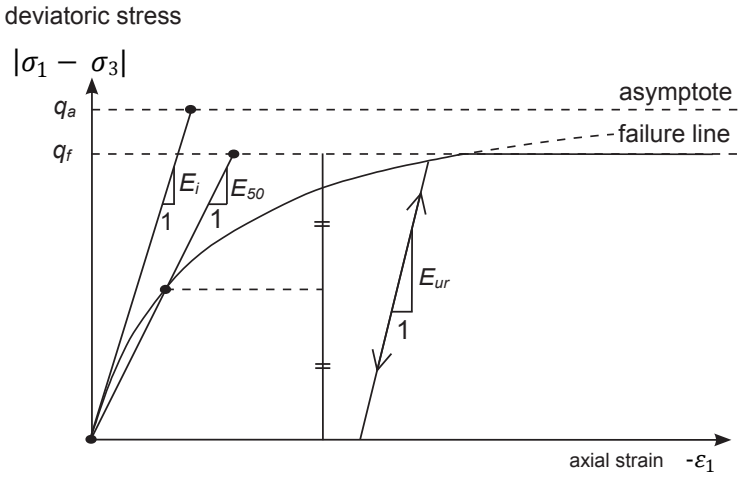


Figure 24: Hyperbolic stress-strain relation in primary loading for a standard drained triaxial test

6.2 Approximation of hyperbola by the Hardening Soil model

For the sake of convenience, restriction is made here to triaxial loading conditions with $\sigma'_2 = \sigma'_3$ and σ'_1 being the major compressive stress. In fact, for general states of stress, q can be replaced by $\tilde{q}$ where:

$$\tilde{q} = \sigma_1 + (\alpha - 1)\sigma_2^{'} - \alpha\sigma_3^{'} \qquad with \qquad \alpha = \frac{3 + \sin(\varphi)}{3 - \sin(\varphi)} \qquad Eq.\ [140]$$

(refer to On the cap yield surface in the Hardening Soil model (on page 79) for more details). Moreover, it is assumed that $q < q_f$, as also indicated in Figure 24 (on page 69). It should also be realised that compressive stress and strain are considered negative. For a more general presentation of the Hardening Soil model the reader is referred to Schanz, Vermeer & Bonnier (1999) (on page 254). In this section it will be shown that this model gives virtually the hyperbolic stress strain curve of Eq. [135] when considering stress paths of standard drained triaxial tests. Let us first consider the corresponding plastic strains. This stems from a shear hardening yield function of the form:

$$f = \bar{f} - \gamma^{p} \qquad Eq.\ [141]$$

where

$\bar{f}$ = Function of stress

γ^{p} = Function of plastic strains:

$$\bar{f} = \frac{2}{E_i}\frac{q}{1 - q/q_a} - \frac{2q}{E_{ur}} \qquad \gamma^p = -(2\varepsilon_1^p - \varepsilon_v^p) \approx -2\varepsilon_1^p \qquad \textit{Eq. [142]}$$

with q, q_a, E_i and E_{ur} as defined by Eq. [135] to Eq. [138], whilst the superscript p is used to denote plastic strains. For hard soils, plastic volume changes (ε_v^p) tend to be relatively small and this leads to the approximation $\gamma^p \approx -2\varepsilon_1^p$. The above definition of the strain-hardening parameter γ^p will be referred to later.

An essential feature of the above definitions for $\bar{f}$ is that it matches the well-known hyperbolic law Eq. [135]. For checking this statement, one has to consider primary loading, as this implies the yield condition $f = 0$. For primary loading, it thus yields $\gamma^p = \bar{f}$ and it follows from Eq. [141] that:

$$\varepsilon_1^p \approx \frac{1}{2}\bar{f} = \frac{1}{E_i}\frac{q}{1 - q/q_a} - \frac{q}{E_{ur}} \qquad \textit{Eq. [143]}$$

In addition to the plastic strains, the model accounts for elastic strains. Plastic strains develop in primary loading alone, but elastic strains develop both in primary loading and unloading / reloading. For drained triaxial test stress paths with $\sigma'_2 = \sigma'_3$ = constant, the elastic Young's modulus E_{ur} remains constant and the elastic strains are given by the equations:

$$-\varepsilon_1^e = \frac{q}{E_{ur}} \qquad -\varepsilon_2^e = -\varepsilon_3^e = -\nu_{ur}\frac{q}{E_{ur}} \qquad \textit{Eq. [144]}$$

where ν_{ur} is the unloading / reloading Poisson's ratio. Here it should be realised that restriction is made to strains that develop during deviatoric loading, whilst the strains that develop during the very first stage of the test (isotropic compression with consolidation) are not considered.

For the deviatoric loading stage of the triaxial test, the axial strain is the sum of an elastic component given by Eq. [144] and a plastic component according to Eq. [143]. Hence, it follows that:

$$-\varepsilon_1 = -\varepsilon_1^e - \varepsilon_1^p \approx \frac{1}{E_i}\frac{q}{1 - q/q_a} \qquad \textit{Eq. [145]}$$

This relationship holds exactly in absence of plastic volume strains, i.e. when $\varepsilon_v^p = 0$.

In reality, plastic volumetric strains will never be precisely equal to zero, but for hard soils plastic volume changes tend to be small when compared with the axial strain so that this formulation yields a hyperbolic stress-strain curve under triaxial testing conditions.

For a given constant value of the hardening parameter, γ^p, the yield condition $f = 0$, can be visualised in p' - q-plane by means of a yield locus. Hence, γ^p is associated with mobilised friction. When plotting such yield loci, one has to use Eq. [142] as well as Eq. [139] and Eq. [138] for E_{50} and E_{ur} respectively. Because of the latter expressions, the shape of the yield loci depends on the exponent m. For $m = 1$, straight lines are obtained, but slightly curved yield loci correspond to lower values of the exponent. Figure 25 (on page 71) shows the shape of yield loci for increasing values of γ^p considering $m = 0.5$, being typical for hard soils. Hence, γ^p can be regarded as the plastic shear strain related to the mobilised shear resistance.

Note: Note that there is approximately a factor 2 difference between the plastic shear strain parameter γ^p and the deviatoric plastic strain ε_q^p ($\gamma^p \approx \varepsilon_q^p$)

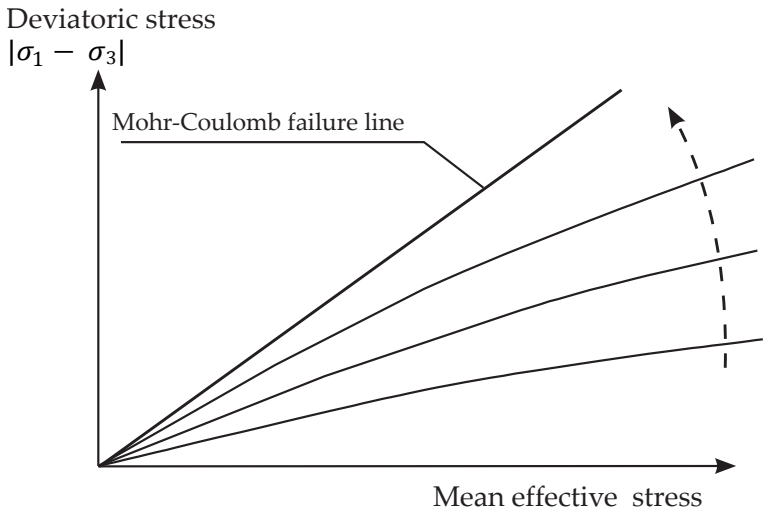


Figure 25: Successive yield loci for various constant values of the hardening parameter γ^p

6.3 Plastic volumetric strain for triaxial states of stress

Having presented a relationship for the plastic shear strain, γ^p, attention is now focused on the plastic volumetric strain, ε_v^p. As for all plasticity models, the Hardening Soil model involves a relationship between rates of plastic strain, i.e. a relationship between $\dot{\varepsilon}_v^p$ and $\dot{\gamma}^p$. This shear hardening flow rule has the linear form:

$$\dot{\varepsilon}_v^p = \sin(\psi_m)\dot{\gamma}^p \qquad \textit{Eq. [146]}$$

Clearly, further detail is needed by specifying the mobilised dilatancy angle ψ_m. For the present model, the following is considered (see also Figure 26 (on page 71)):

$$\begin{aligned}
&\textit{For} \quad \sin(\varphi_m) < 3/4\sin(\varphi): && \psi_m = 0 \\
&\textit{For} \quad \sin(\varphi_m) < 3/4\sin(\varphi) \quad \textit{and} \quad \psi > 0 && \sin(\psi_m) = \max\left(\frac{\sin(\varphi_m) - \sin(\varphi_{cv})}{1 - \sin(\varphi_m)\sin(\varphi_{cv})},\ 0\right) \\
&\textit{For} \quad \sin(\varphi_m) < 3/4\sin(\varphi) \quad \textit{and} \quad \psi \le 0 && \psi_m = \psi \\
&\textit{If} \quad \varphi = 0 && \psi_m = 0
\end{aligned} \qquad \textit{Eq. [147]}$$

where

φ_{cv} = Critical state friction angle, being a material constant independent of density.

φ_m = Mobilised friction angle:

$$\sin(\varphi_m) = \frac{\sigma_1' - \sigma_3'}{\sigma_1' + \sigma_3' - 2c\cot(\varphi)} \qquad \textit{Eq. [148]}$$

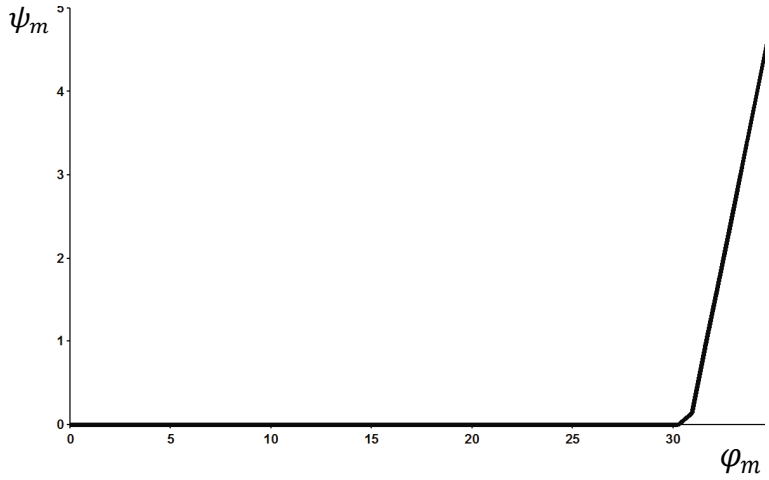


Figure 26: Plot of mobilized dilatancy angle ψ_m and mobilized friction angle φ_m for Hardening Soil model

The above equations are a small adaptation from the well-known stress-dilatancy theory by Rowe (1962) (on page 254), as explained by Schanz & Vermeer (1966) (on page 254). The mobilised dilatancy angle, ψ_m, follows Rowe's theory for larger values of the mobilised friction angle, as long as this results in a positive value of ψ_m. For small mobilised friction angles and for negative values of ψ_m, as computed by Rowe's formula (as long as the dilatancy angle ψ is positive), ψ_m is taken zero. Furthermore, in all cases when $\varphi = 0$, ψ_m is set equal to zero.

The essential property of the stress-dilatancy theory is that the material contracts for small stress ratios $\varphi_m < \varphi_{cv}$, whilst dilatancy occurs for high stress ratios $\varphi_m > \varphi_{cv}$. At failure, when the mobilised friction angle equals the failure angle, φ, it is found from Eq. [147] that:

$$\sin(\psi) = \frac{\sin(\varphi) - \sin(\varphi_{cv})}{1 - \sin(\varphi)\sin(\varphi_{cv})} \qquad \textit{Eq. [149]}$$

or equivalently:

$$\sin(\varphi_{cv}) = \frac{\sin(\varphi) - \sin(\psi)}{1 - \sin(\varphi)\sin(\psi)} \qquad \textit{Eq. [150]}$$

Hence, the critical state angle can be computed from the failure angles φ and ψ. PLAXIS performs this computation automatically and therefore users do not need to specify a value for φ_{cv}. Instead, one has to provide input data on the peak friction angle, φ, and the peak dilatancy angle, ψ.

The shear hardening process will continue with the mobilization of the shear strength, until the maximum shear strength according to the Mohr-Coulomb model failure criterion is reached.

6.4 Parameters of the Hardening Soil Model

Some parameters of the present hardening model coincide with those of the non-hardening Mohr-Coulomb model. These are the failure parameters c, φ and ψ.

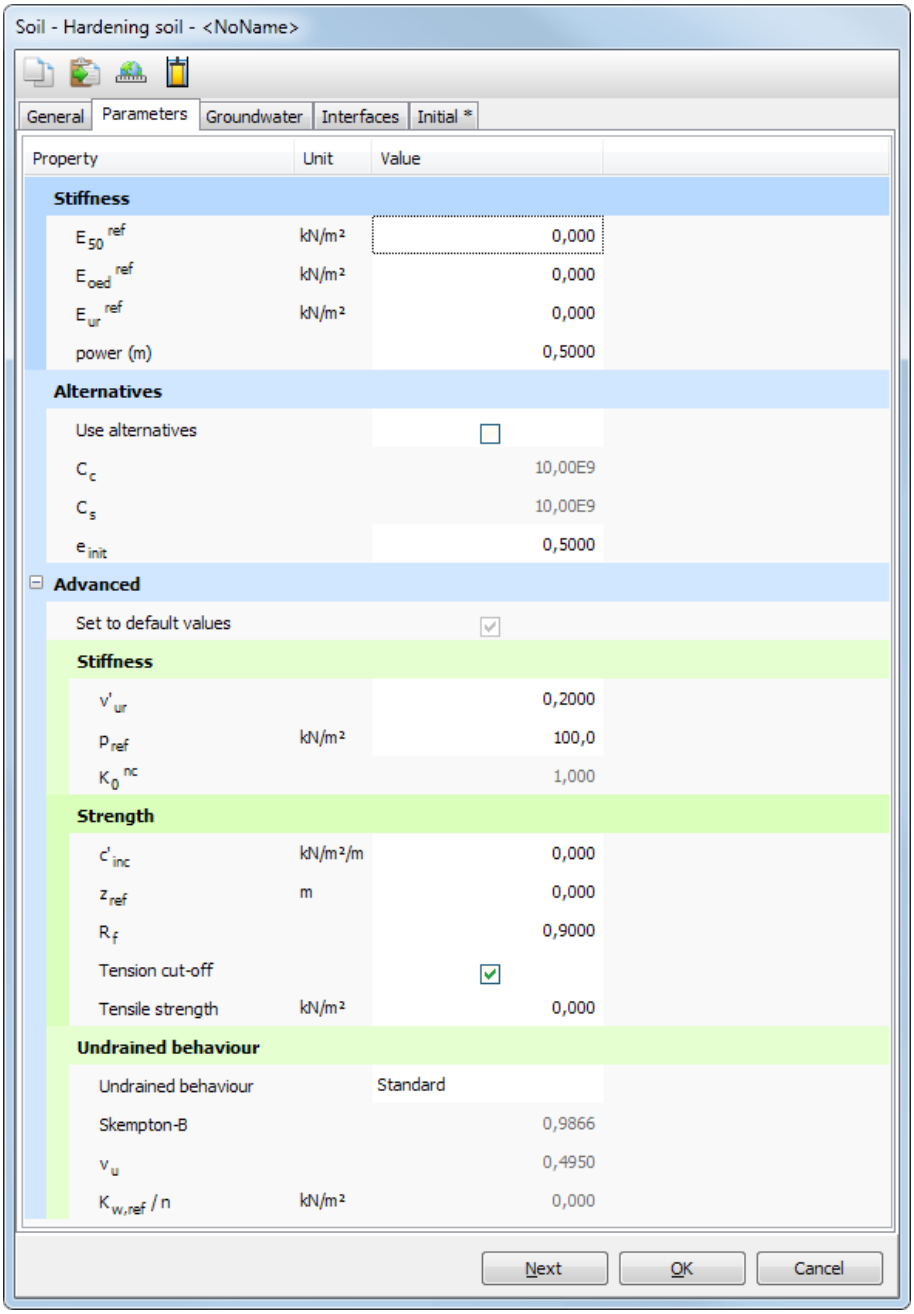


Figure 27: Parameters for the Hardening Soil model

Failure parameters as in Mohr-Coulomb model (see Basic parameters of the Mohr-Coulomb model (on page 35))

c	(Effective) cohesion	[kN/m^2]
φ	(Effective) angle of internal friction	[°]
ψ	Angle of dilatancy	[°]

σ_t	Tension cut-off and tensile strength	[kN/m^2]

Basic parameters for soil stiffness:

E_{50}^{ref}	Secant stiffness in standard drained triaxial test	[kN/m^2]
E_{oed}^{ref}	Tangent stiffness for primary oedometer loading	[kN/m^2]
E_{ur}^{ref}	Unloading / reloading stiffness (default $E_{ur}^{ref} = 3E_{50}^{ref}$)	[kN/m^2]
m	Power for stress-level dependency of stiffness	[-]

Advanced parameters (it is advised to use the default setting):

ν_{ur}	Poisson's ratio for unloading-reloading (default ν_{ur} = 0.2)	[-]
p^{ref}	Reference stress for stiffnesses (default p^{ref} = 100 kN/m^2)	[kN/m^2]
K_0^{nc}	K_0-value for normal consolidation (default $K_0^{nc} = 1 - \sin\varphi$)	[-]
R_f	Failure ratio q_f / q_a (default R_f = 0.9) (see Figure 24 (on page 69)).	[-]
$\sigma_{tension}$	Tensile strength (default $\sigma_{tension}$ = 0 stress units	[kN/m^2]
c_{inc}	As in Mohr-Coulomb model (default c_{inc} = 0)	[kN/m^3]

Instead of entering the basic parameters for soil stiffness, alternative parameters can be entered. These parameters are listed below:

C_c	Compression index	[-]
C_s	Swelling index or reloading index	[-]
e_{init}	Initial void ratio	[-]

6.4.1 Stiffness moduli E_{50}^{ref}, E_{oed}^{ref} & E_{ur}^{ref} and power m

The advantage of the Hardening Soil model over the Mohr-Coulomb model is not only the use of a hyperbolic stress-strain curve instead of a bi-linear curve, but also the control of stress level dependency. When using the Mohr-Coulomb model, the user has to select a fixed value of Young's modulus whereas for real soils this stiffness depends on the stress level. It is therefore necessary to estimate the stress levels within the soil and use these to obtain suitable values of stiffness. With the Hardening Soil model, however, this cumbersome selection of input parameters is not required.

Instead, a stiffness modulus E_{50}^{ref} is defined for a reference minor principal effective stress of - $\sigma'_3 = p^{ref}$. This is the secant stiffness at 50 % of the maximum deviatoric stress, at a cell pressure equal to the reference stress p^{ref} (Figure 28 (on page 75)). As a default value, the program uses p^{ref} = 100 kN/m^2.

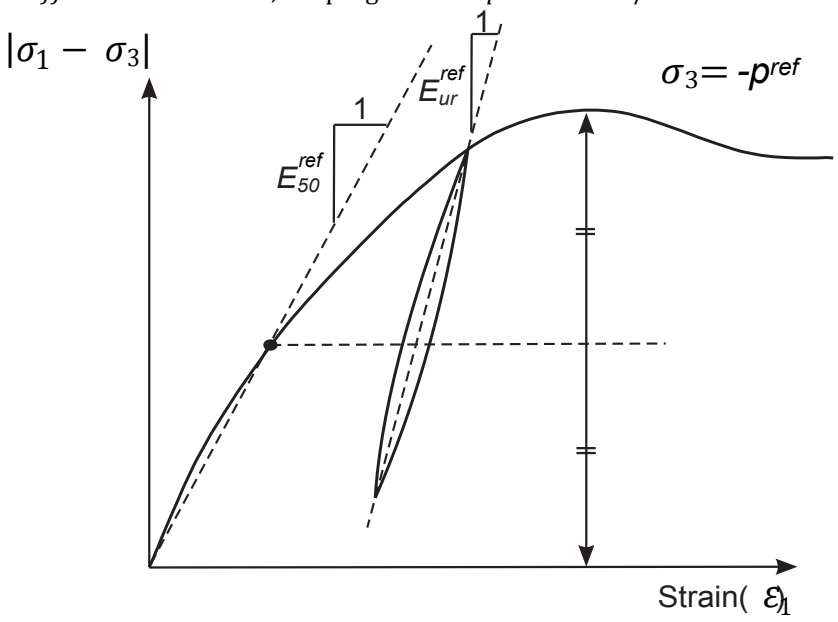


Figure 28: Definition of E_{50}^{ref} and E_{ur}^{ref} for drained triaxial test results

As some PLAXIS users are familiar with the input of shear moduli rather than the above stiffness moduli, shear moduli will now be discussed. Within Hooke's law of isotropic elasticity conversion between E and G goes by the equation $E = 2(1 + \upsilon)G$. As E_{ur} is a real elastic stiffness, one may thus write $E_{ur} = 2(1 + \upsilon)G_{ur}$, where G_{ur} is an elastic shear modulus.

Note: PLAXIS allows for the input of E_{ur} and ν_{ur} but not for a direct input of G_{ur}. In contrast to E_{ur}, the secant modulus E_{50} is not used within a concept of elasticity. As a consequence, there is no simple conversion from E_{50} to G_{50}.

In contrast to elasticity based models, the elastoplastic Hardening Soil model does not involve a fixed relationship between the (drained) triaxial stiffness E_{50} and the oedometer stiffness E_{oed} for one-dimensional compression. Instead, these stiffnesses can be inputted independently. Having defined E_{50} by Eq. [137], it is now important to define the oedometer stiffness. Here we use the equation:

$$E_{oed} = E_{oed}^{ref} \left(\frac{c\cos(\varphi) - \frac{\sigma'_3}{K_0^{nc}} \sin(\varphi)}{c\cos(\varphi) + p^{ref} \sin(\varphi)} \right)^m \qquad \text{Eq. [151]}$$

where E_{oed} is a tangent stiffness modulus obtained from an oedometer test, as indicated in Figure 29 (on page 76).

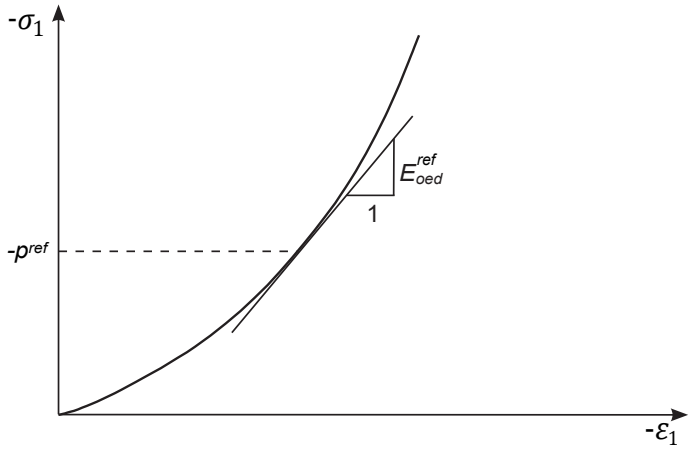


Figure 29: Definition of E_{oed}^{ref} and E_{ur}^{ref} in oedometer test results

Hence, $E_{oed}{}^{ref}$ is a tangent stiffness at a vertical stress of $-\sigma_1' = \frac{\sigma_3'}{K_0^{nc}} = p^{ref}$. Note that we basically use σ_1' rather than σ_3' and that we consider primary loading.

When undrained behaviour is considered in the Hardening Soil model the *Drainage type* should preferably be set to *Undrained (A)*. Alternatively, *Undrained (B)* can be used in case the effective strength properties are not known or the undrained shear strength is not properly captured using *Undrained (A)*. However, it should be noted that the material loses its stress-dependency of stiffness in that case. *Undrained (C)* is not possible since the model is essentially formulated as an effective stress model.

6.4.2 Alternative stiffness parameters

When soft soils are considered, the stiffness parameters can be calculated from the compression index, swelling index and the initial void ratio [1]. The relationship between these parameters and the compression index, C_c, is given by:

$$C_c = \frac{2.3(1+e_{init})p_{red}}{E_{oed}^{ref}} \qquad Eq.\ [152]$$

The relationship between the $E_{ur}{}^{ref}$ and the swelling index, C_s, is given by:

$$C_s \approx \frac{2.3(1+e_{init})(1+\nu_{ur})(1-2\nu_{ur})p_{ref}}{(1-\nu_{ur})\,E_{ur}^{ref}\,K_0} \qquad Eq.\ [153]$$

Note: During unloading the K_0-value will increase, where values above 1.0 may be observed for significant unloading. By default, PLAXIS assumes that on average the horizontal stress is equal to the vertical stress (K_0=1).

Regardless the previous value of E_{50}, a new value will be automatically assigned according to:

$$E_{50}^{ref} = 1.25E_{oed}^{ref} \qquad Eq.\ [154]$$

[1] In the PLAXIS material database, these alternative parameters depend on the initial void ratio. In reality, these parameters depend on the actual void ratio, which is not a constant.

Although for *Soft soils*, E_{50}^{ref} could be as high as $2E_{oed}^{ref}$, this high value could lead to a limitation in the modeling; therefore a lower value is used. Changing the value of C_s will change the stiffness parameter E_{ur}.

Note that the value of the power for stress-level dependency of stiffness (m) is automatically set to 1.

6.4.3 Advanced parameters

Realistic values of ν_{ur} are about 0.2 and this value is thus used as a default setting, as indicated in Figure 27 (on page 73). Note that in the Hardening Soil model, ν_{ur} is a pure elastic parameter.

In contrast to the Mohr-Coulomb model, K_0^{nc} is not simply a function of Poisson's ratio, but an independent input parameter. As a default setting PLAXIS uses the correlation K_0^{nc} *= 1-sin φ*. It is suggested to maintain this value as the correlation is quite realistic. However, users do have the possibility to select different values. Not all possible input values for K_0^{nc} can be accommodated for. Depending on other parameters, such as E_{50}^{ref}, E_{oed}^{ref}, E_{ur}^{ref} and ν_{ur}, there happens to be a certain range of valid K_0^{nc}-values. K_0^{nc} values outside this range are rejected by PLAXIS. On inputting values, the program shows the nearest possible value that will be used in the computations.

6.4.4 Dilatancy cut-off

After extensive shearing, dilating materials arrive in a state of critical density where dilatancy has come to an end, as indicated in Figure 30 (on page 78). This phenomenon of soil behaviour can be included in the Hardening Soil model by means of a dilatancy cut-off. In order to specify this behaviour, the initial void ratio, e_{init}, and the maximum void ratio, e_{max}, of the material must be entered as general parameters. As soon as the volume change results in a state of maximum void, the mobilised dilatancy angle, ψ_m, is automatically set back to zero, as indicated in Figure 30 (on page 78).

$$for \quad e < e_{max} \quad \sin(\psi_m) = \frac{\sin(\varphi_m) - \sin(\varphi_{cv})}{1 - \sin(\varphi_m)\sin(\varphi_{cv})} \qquad Eq.\ [155]$$

$$where: \qquad \sin(\varphi_{cv}) = \frac{\sin(\varphi) - \sin(\psi)}{1 - \sin(\varphi)\sin(\psi)}$$

$$for \quad e \geq e_{max} \quad \psi_m = 0 \qquad Eq.\ [156]$$

The void ratio is related to the volumetric strain, ε_v by the relationship:

$$-(\varepsilon_v - \varepsilon_v^{init}) = \ln\left(\frac{1+e}{1+e_{init}}\right) \qquad Eq.\ [157]$$

where an increment of ε_v is positive for dilatancy.

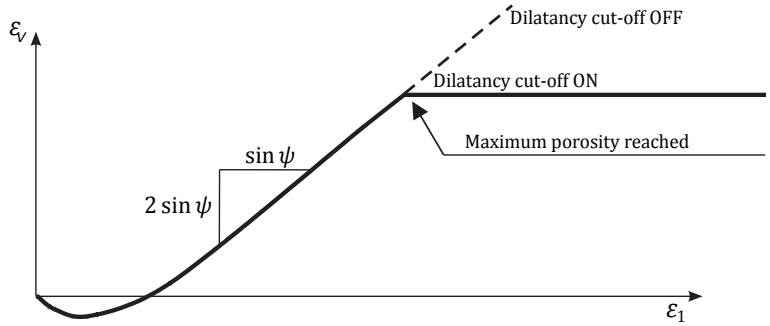


Figure 30: Resulting strain curve for a standard drained triaxial test when including dilatancy cut-off

The initial void ratio, e_{init}, is the in-situ void ratio of the soil body. The maximum void ratio is the void ratio of the material in a state of critical void (critical state). As soon as the maximum void ratio is reached, the dilatancy angle is set to zero. The minimum void ratio, e_{min}, of a soil can also be input, but this general soil parameter is not used within the context of the Hardening Soil model.

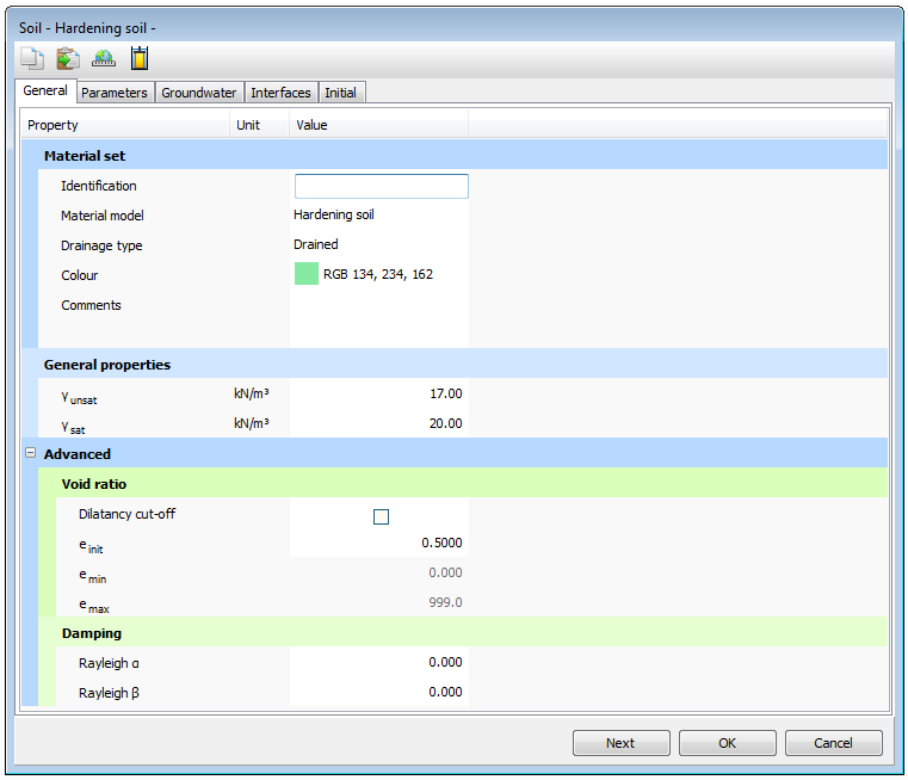


Figure 31: General tabsheet

Please note that the selection of the dilatancy cut-off and the input of void ratios are done in the **General** tabsheet (Figure 31 (on page 78)) of the **Soil** window and not in the **Parameters** tabsheet. The selection of the *Dilatancy cut-off* is only available when the Hardening Soil model or the Hardening Soil model with small-strain stiffness has been selected. By default, the *Dilatancy cut-off* is not active. Note that the dilatancy cut-off does not help in limiting the shear strength when using the *Undrained (A)* drainage type with a positive dilatancy angle. This is because the void ratio remains constant for undrained materials. Therefore, it is strongly recommended to set $\psi = 0$ for undrained material behaviour (*Undrained A*).

6.5 On the cap yield surface in the Hardening Soil model

Shear hardening yield surfaces as indicated in Figure 25 (on page 71) do not explain the plastic volume strain that is measured in isotropic compression which is mostly observed in softer types of soil. A second type of yield surface must therefore be introduced to close the elastic region for compressive (compaction hardening) stress paths. Without such a cap type yield surface it would not be possible to formulate a model with independent input of both E_{50}^{ref} and E_{oed}^{ref}. The triaxial modulus largely controls the shear yield surface and the oedometer modulus controls the cap yield surface. In fact, E_{50}^{ref} largely controls the magnitude of the plastic strains that are associated with the shear yield surface. Similarly, E_{oed}^{ref} is used to control the magnitude of plastic strains that originate from the yield cap. In this section the yield cap will be described in detail. To this end we consider the definition of the cap yield surface:

$$f_c = \frac{\tilde{q}^2}{M^2} + (p')^2 - p_p^2 \qquad Eq.\ [158]$$

where

M = auxiliary model parameter that relates to K_0^{nc} (discussed later).

Furthermore we have:

$p' = (\sigma'_1 + \sigma'_2 + \sigma'_3) / 3$ and $q = \sigma'_1 + (\alpha\text{-}1)\sigma'_2 - \alpha\sigma'_3$ with $\alpha = (3 + \sin\varphi) / (3 - \sin\varphi)$. q is a special stress measure for deviatoric stresses.

In the special case of triaxial compression ($-\sigma'_1 > -\sigma'_2 = -\sigma'_3$) it yields $q = -(\sigma'_1 - \sigma'_3)$ and for triaxial extension ($-\sigma'_1 = -\sigma'_2 > -\sigma'_3$) $\tilde{q}$ reduces to $\tilde{q} = -\alpha(\sigma'_1 - \sigma'_3)$. The magnitude of the yield cap is determined by the isotropic pre-consolidation stress p_p. In a (p', q) plane, the yield cap ($f_c = 0$) is a part of an ellipse with its centre point in the origin (Figure 32 (on page 80)). The hardening law relating $\dot{p}$ to volumetric cap strain $\dot{\varepsilon}_v^{pc}$ is:

$$\dot{\varepsilon}_v^{pc} = \frac{K_s / K_c}{K_s^{ref}} \left[\left(\frac{p_p + c\cot(\varphi)}{p^{ref} + c\cot(\varphi)} \right)^{-m} \right] \dot{p}_p \qquad Eq.\ [159]$$

in which K_s^{ref} is the reference bulk modulus in unloading / reloading:

$$K_s^{ref} = \frac{E_{ur}^{ref}}{3(1 - 2\nu_{ur})} \qquad Eq.\ [160]$$

and K_s/K_c is the ratio of bulk moduli in isotropic swelling and primary isotropic compression.

The volumetric cap strain is the plastic volumetric strain in isotropic compression. In addition to the well known constants m and p^{ref} there is another model constant K_s/K_c. Both M (Eq. [158]) and K_s/K_c (Eq. [159]) are cap parameters, but these are not used as direct input parameters. Instead, there is a relationship of the form:

$$M \leftrightarrow K_0^{nc} \qquad \left(default:\ K_0^{nc} = 1 - \sin(\varphi) \right) \qquad Eq.\ [161]$$

and the ratio K_s/K_c can be approximated as:

$$K_s / K_c \approx \frac{E_{ur}^{ref}}{E_{oed}^{ref}} \frac{K_0^{nc}}{\left(1 + 2K_0^{nc}\right)\left(1 - 2\nu_{ur}\right)} \qquad \textit{Eq. [162]}$$

such that K_0^{nc}, E_{ur}^{ref} and E_{oed}^{ref} can be used as input parameters that determine the magnitude of M and K_s/K_c respectively.

The ellipse on which the yield cap is located has length p_p on the p-axis and $M\,p_p$ on the $\tilde{q}$-axis. Hence, p_p determines its magnitude and M its aspect ratio. High values of M lead to steep caps underneath the Mohr-Coulomb line and correspondingly small K_0^{nc}-values, whereas small M-values define caps that are much more pointed around the p-axis leading to large K_0^{nc}-values. The ellipse is used both as a yield surface and as a plastic potential (associated plasticity). Input data on initial p_p-values is provided by means of the PLAXIS procedure for initial stresses. Here, p_p is either computed from the input overconsolidation ratio (OCR) or the pre-overburden pressure (POP) (see On the initial stresses (on page 30)).

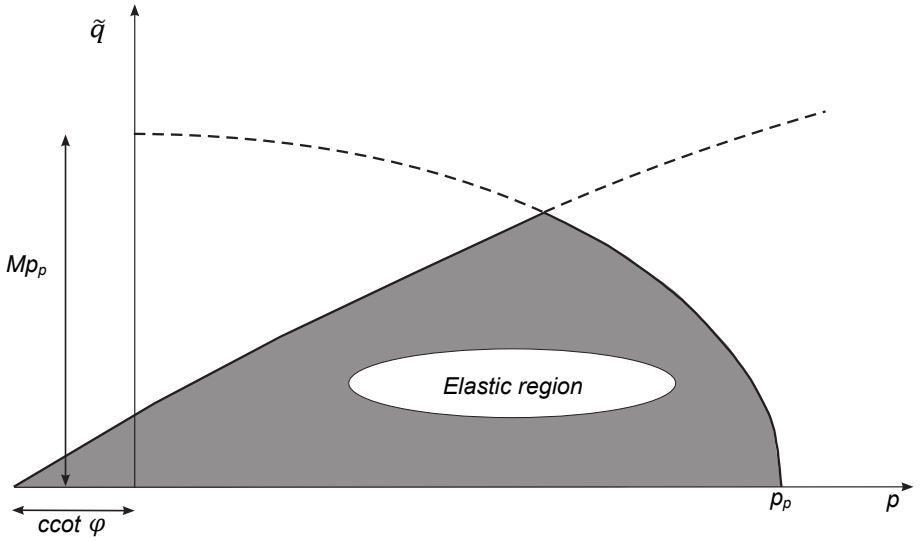


Figure 32: Yield surfaces of in p - $\tilde{q}$ -plane. The elastic region can be further reduced by means of a tension cut-off

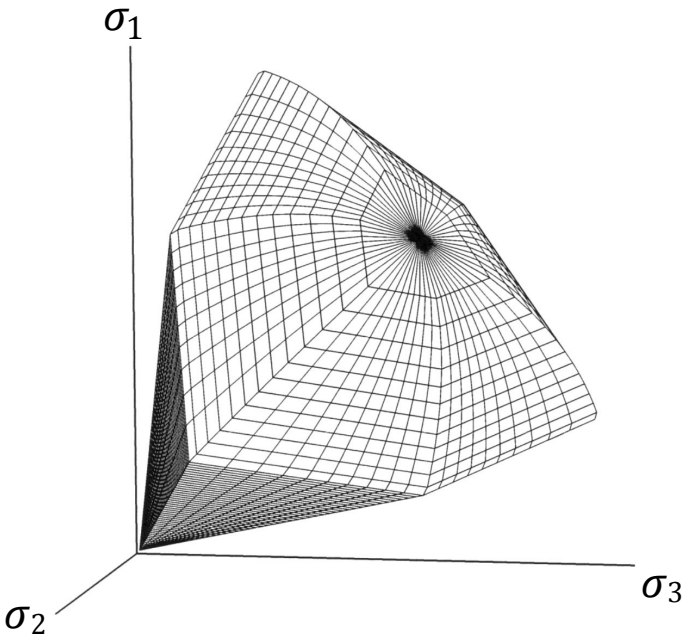


Figure 33: Representation of total yield contour of the Hardening Soil model in principal stress space for cohesionless soil

For understanding the yield surfaces in full detail, one should consider both Figure 32 (on page 80) and Figure 33 (on page 81). The first figure shows simple yield lines, whereas the second one depicts yield surfaces in principal stress space. Both the shear locus and the yield cap have the hexagonal shape of the classical Mohr-Coulomb failure criterion. In fact, the shear yield locus can expand up to the ultimate Mohr-Coulomb failure surface. The cap yield surface expands as a function of the pre-consolidation stress p_p.

6.6 State parameters in the Hardening Soil model

In addition to the output of standard stress and strain quantities, the Hardening Soil model provides output (when being used) on state variables such as the hardening parameter γ^p and the isotropic pre-consolidation stress p_p. These parameters can be visualised by selecting the *State parameters* option from the *stresses* menu. An overview of available state parameters is given below:

p_{eq}	Equivalent isotropic stress $p_{eq} = \sqrt{\frac{q}{M^2} + (p')^2}$	[kN/m^2]
p_p	Isotropic preconsolidation stress	[kN/m^2]
OCR	Isotropic overconsolidation ratio ($OCR = p^p/p^{eq}$)	[-]
γ^p	Hardening parameter (equivalent mobilised plastic shear strain)	[-]

E_{ur}	Current stress-dependent elastic Young's modulus	[kN/m^2]
c	Current depth-dependent cohesion	[kN/m^2]

6.7 On the use of the Hardening Soil model in dynamic calculations

When using the Hardening Soil model in dynamic calculations, the elastic stiffness parameter E_{ur}^{ref} needs to be selected such that the model correctly predicts wave velocities in the soil. This generally requires an even larger small strain stiffness rather than just an unloading-reloading stiffness to be entered for E_{ur}^{ref}. When subjected to dynamic or cyclic loading, the Hardening Soil model will generate plastic strains when mobilizing the soil's material strength (shear hardening) or increasing the soil's preconsolidation stress (compaction hardening). However, it should be noted that stress cycles within the current hardening contours will only generate elastic strains and no (hysteretic) damping, nor accumulation of strains or pore pressure nor liquefaction. In order to simulate the soil's damping characteristics in cyclic loading, Rayleigh damping may be defined. Note that some of the limitations of the Hardening Soil model in dynamic applications can be overcome by using the Hardening Soil model with small-strain stiffness (The Hardening Soil model with small-strain stiffness (HSsmall) (on page 83)).

7

The Hardening Soil model with small-strain stiffness (HSsmall)

The original Hardening Soil model assumes elastic material behaviour during unloading and reloading. However, the strain range in which soils can be considered truly elastic, i.e. where they recover from applied straining almost completely, is very small. With increasing strain amplitude, soil stiffness decays nonlinearly. Plotting soil stiffness against log(strain) yields characteristic S-shaped stiffness reduction curves. Figure 34 (on page 83) gives an example of such a stiffness reduction curve. It outlines also the characteristic shear strains that can be measured near geotechnical structures and the applicable strain ranges of laboratory tests. It turns out that at the minimum strain which can be reliably measured in classical laboratory tests, i.e. triaxial tests and oedometer tests without special instrumentation, soil stiffness is often decreased to less than half its initial value.

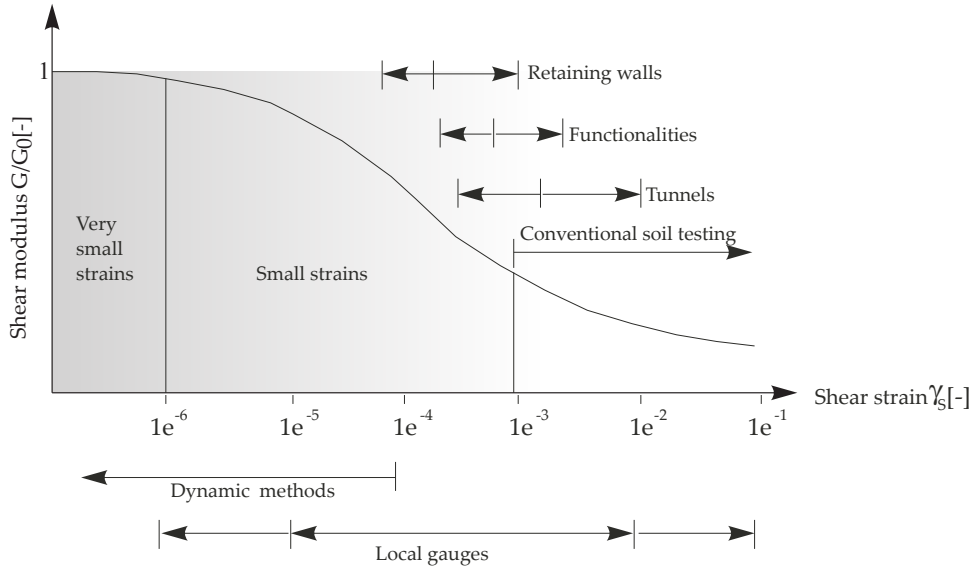


Figure 34: Characteristic stiffness-strain behaviour of soil with typical strain ranges for laboratory tests and structures (after Atkinson & Sallfors,1991)

The soil stiffness that should be used in the analysis of geotechnical structures is not the one that relates to the strain range at the end of construction according to Figure 34 (on page 83). Instead, very small-strain soil stiffness and its non-linear dependency on strain amplitude should be properly taken into account. In addition to all features of the Hardening Soil model, the Hardening Soil model with small-strain stiffness offers the possibility to do so.

The Hardening Soil model with small-strain stiffness implemented in PLAXIS is based on the Hardening Soil model and uses almost entirely the same parameters (see Parameters of the Hardening Soil Model (on page 72)). In fact, only two additional parameters are needed to describe the variation of stiffness with strain:

- the initial or very small-strain shear modulus G_0.
- the shear strain level $\gamma_{0.7}$ at which the secant shear modulus G_s is reduced to about 70% of G_0.

7.1 Describing small-strain stiffness with a Simple Hyperbolic Law

In soil dynamics, small-strain stiffness has been a well known phenomenon for a long time. In static analysis, the findings from soil dynamics have long been considered not to be applicable.

Seeming differences between static and dynamic soil stiffness have been attributed to the nature of loading (e.g. inertia forces and strain rate effects) rather than to the magnitude of applied strain which is generally small in dynamic conditions (earthquakes excluded). As inertia forces and strain rate have only little influence on the initial soil stiffness, dynamic soil stiffness and small-strain stiffness can in fact be considered as synonyms.

Probably the most frequently used model in soil dynamics is the Hardin-Drnevich relationship. From test data, sufficient agreement is found that the stress-strain curve for small strains can be adequately described by a simple hyperbolic law. The following analogy to the hyperbolic law for larger strains by Konder (1963) (on page 253) (see The Hardening Soil model (Isotropic hardening) (on page 67)) was proposed by Hardin & Drnevich(1972) (on page 253):

$$\frac{G_s}{G_0} = \frac{1}{1 + \left| \frac{\gamma}{\gamma_r} \right|} \qquad Eq.\ [163]$$

where the threshold shear strain γ_r is quantified as:

$$\gamma_r = \frac{\tau_{max}}{G_0} \qquad Eq.\ [164]$$

with τ_{max} being the shear stress at failure. Essentially, Eq. [163] and Eq. [164] relate large (failure) strains to small-strain properties which often work well.

More straightforward and less prone to error is the use of a smaller threshold shear strain. Santos & Correia (2001) (on page 254), for example suggest to use the shear strain $\gamma_r = \gamma_{0.7}$ at which the secant shear modulus G_s is reduced to about 70 % of its initial value. Eq. [163] can then be rewritten as:

$$\frac{G_s}{G_0} = \frac{1}{1 + a \left| \frac{\gamma}{\gamma_{0.7}} \right|} \qquad where\ \ a = 0.385 \qquad Eq.\ [165]$$

In fact, using $a = 0.385$ and $\gamma = \gamma_{0.7}$ gives $G_s/G_0 = 0.722$. Hence, the formulation "about 70%" should be interpreted more accurately as 72.2%.

Figure 35 (on page 85) shows the fit of the modified Hardin-Drnevich relationship (Eq. [165]) to normalised test data.

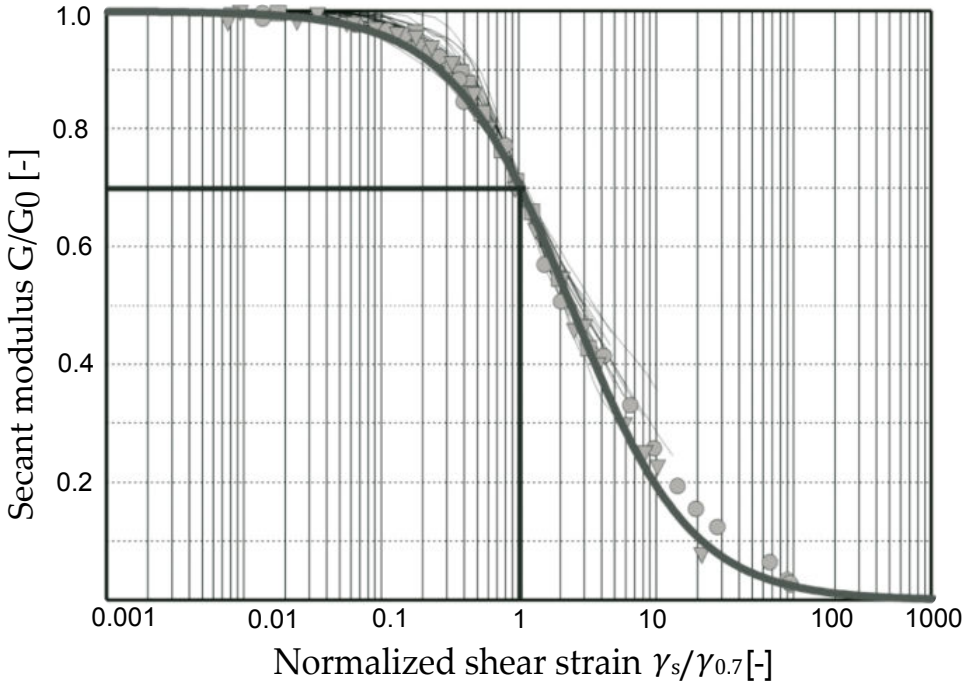


Figure 35: Results from the Hardin-Drnevich relationship compared to test data by Santos & Correia (2001)

7.2 Applying the Hardin-Drnevich relationship in the HS Model

The decay of soil stiffness from small strains to larger strains can be associated with loss of intermolecular and surface forces within the soil skeleton. Once the direction of loading is reversed, the stiffness regains a maximum recoverable value which is in the order of the initial soil stiffness. Then, while loading in the reversed direction is continued, the stiffness decreases again. A strain history dependent, multi-axial extension of the Hardin-Drnevich relationship is therefore needed in order to apply it in the Hardening Soil model. Such an extension has been proposed by Benz (2006) (on page 251) in the form of the small-strain overlay model. Benz derives a scalar valued shear strain γ_{hist} by the following projection:

$$\gamma_{hist} = \sqrt{3}\frac{\| \mathbf{H}\Delta e\|}{\| \Delta e\|} \qquad Eq.\ [166]$$

where

Δe = Actual deviatoric strain increment.
H = Symmetric tensor that represents the deviatoric strain history of the material.

Whenever a strain reversal is detected the tensor **H** is partially or fully reset before the actual strain increment Δe is added.

As the criterion for strain reversals serves a criterion similar as in Simpson's brick model (1992): All three principal deviatoric strain directions are checked for strain reversals separately which resembles three independent brick models. When there is no principal strain rotation, the criterion reduces to two independent brick-models. For further details on the strain tensor **H** and its transformation at changes in the load path it is referred to Benz (2006) (on page 251).

The scalar valued shear strain $\gamma = \gamma_{hist}$ calculated in Eq. [166] is applied subsequently used in Eq. [165]. Note that in both, Eq. [165] and Eq. [166], the scalar valued shear strain is defined as:

$$\gamma = \frac{3}{2}\varepsilon_q \qquad \textit{Eq. [167]}$$

where

ε_q = Second deviatoric strain invariant

In triaxial conditions γ can therefore be expressed as:

$$\gamma = \varepsilon_{axial} - \varepsilon_{lateral} \qquad \textit{Eq. [168]}$$

Within the Hardening Soil model with small-strain stiffnessmall, the stress-strain relationship can be simply formulated from the secant shear modulus (Eq. [165]) as:

$$\tau = G_s\gamma = \frac{G_0\gamma}{1 + 0.385\dfrac{\gamma}{\gamma_{0.7}}} \qquad \textit{Eq. [169]}$$

Taking the derivative with respect to the shear strain gives the tangent shear modulus:

$$G_t = \frac{G_0}{\left(1 + 0.385\dfrac{\gamma}{\gamma_{0.7}}\right)^2} \qquad \textit{Eq. [170]}$$

This stiffness reduction curve reaches far into the plastic material domain. In the Hardening Soil model and Hardening Soil model with small-strain stiffness, stiffness degradation due to plastic straining is simulated with strain hardening. In the Hardening Soil model with small-strain stiffness, the small-strain stiffness reduction curve is therefore bound by a certain lower limit, determined by conventional laboratory tests:

- The lower cut-off of the tangent shear modulus G_t is introduced at the unloading reloading stiffness G_{ur} which is defined by the material parameters E_{ur} and ν_{ur}:

$$G_t \geq G_{ur} \quad where \quad G_{ur} = \frac{E_{ur}}{2(1 + \upsilon_{ur})} \quad and \quad G_t = \frac{E_t}{2(1 + \upsilon_{ur})} \qquad \textit{Eq. [171]}$$

- The cut-off shear strain $\gamma_{cut\text{-}off}$ can be calculated as:

$$\gamma_{cut-off} = \frac{1}{0.385}\left(\sqrt{\frac{G_0}{G_{ur}}} - 1\right)\gamma_{0.7} \qquad \textit{Eq. [172]}$$

Within the Hardening Soil model with small-strain stiffnessmall, the quasi-elastic tangent shear modulus is calculated by integrating the secant stiffness modulus reduction curve over the actual shear strain increment. An example of a stiffness reduction curve used in the Hardening Soil model with small-strain stiffnessmall is shown in Figure 36 (on page 87).

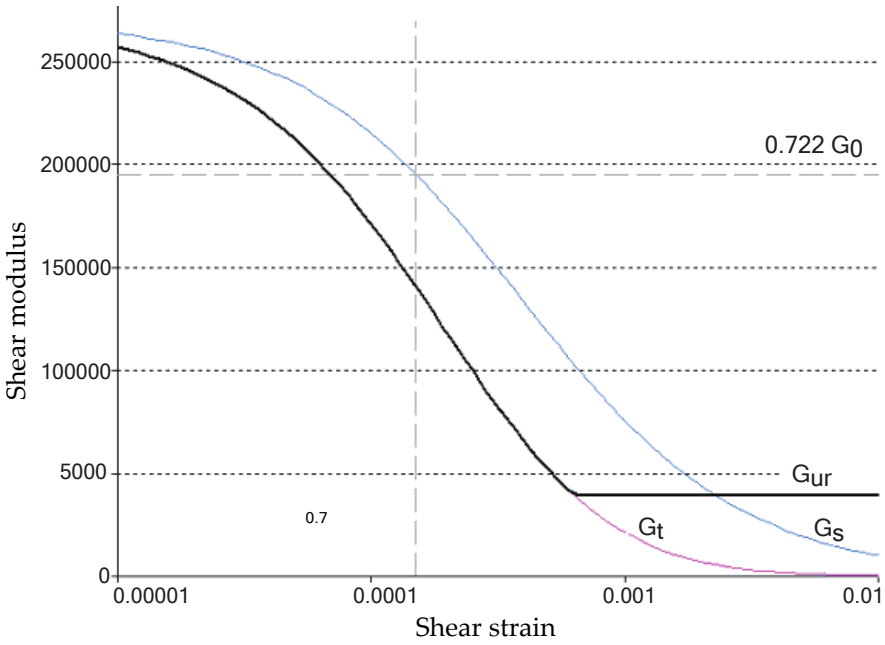


Figure 36: Secant and tangent shear modulus reduction curve

Moreover, the tangent shear modulus G_t and corresponding Young's modulus E_t (considering a constant Poisson's ratio ν_{ur}), is stress-dependent, and follows the same power law as formulated in Eq. [139]. For primary loading situations, the model uses the same hardening plasticity formulations as the Hardening Soil model, where E_{ur} is replaced by E_t as described above.

7.3 Virgin (initial) loading vs unloading/reloading

Masing (1926) (on page 253) described the hysteretic behaviour of materials in unloading / reloading cycles in the form of the following rules:

- The shear modulus in unloading is equal to the initial tangent modulus for the initial loading curve.
- The shape of the unloading and reloading curves is equal to the initial loading curve, but twice its size. In terms of the above introduced threshold shear strain $\gamma_{0.7}$, Masing's rule can be fulfilled by the following setting in the Hardin-Drnevich relation:

$$\gamma_{0.7re-loading} = 2\gamma_{0.7virgin-loading} \qquad Eq.\ [173]$$

The Hardening Soil model with small-strain stiffnessmall adopts Masing's rule. According to it, the threshold shear strain and the reloading curve are obtained by scaling the backbone curve (virgin loading) by a factor of 2. However, in the Hardening Soil model with small-strain stiffness, the hardening plasticity accounts for more rapidly decaying small-strain stiffness during virgin loading. Figure 37 (on page 88) and Figure 38 (on page 88) illustrate Masing's rule and the secant stiffness reduction in virgin loading and unloading / reloading.

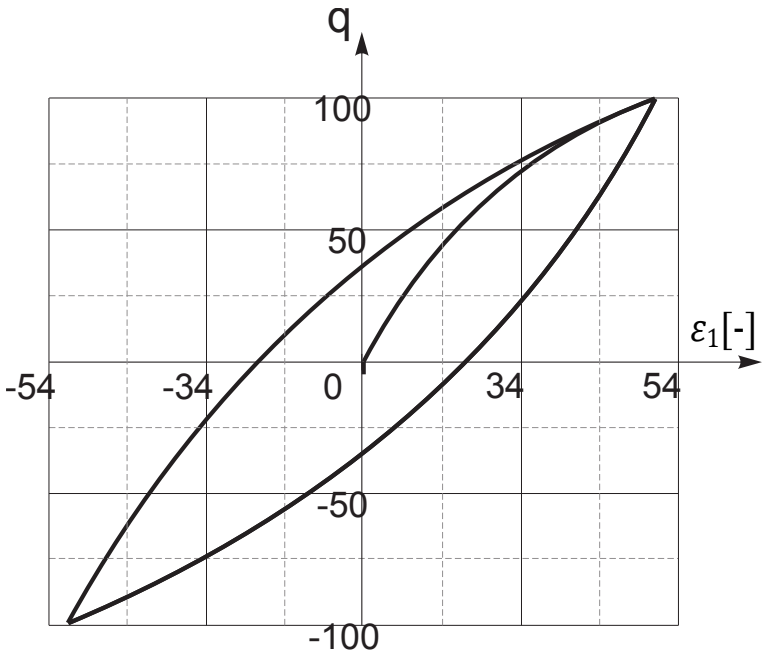


Figure 37: Hysteretic material behaviour

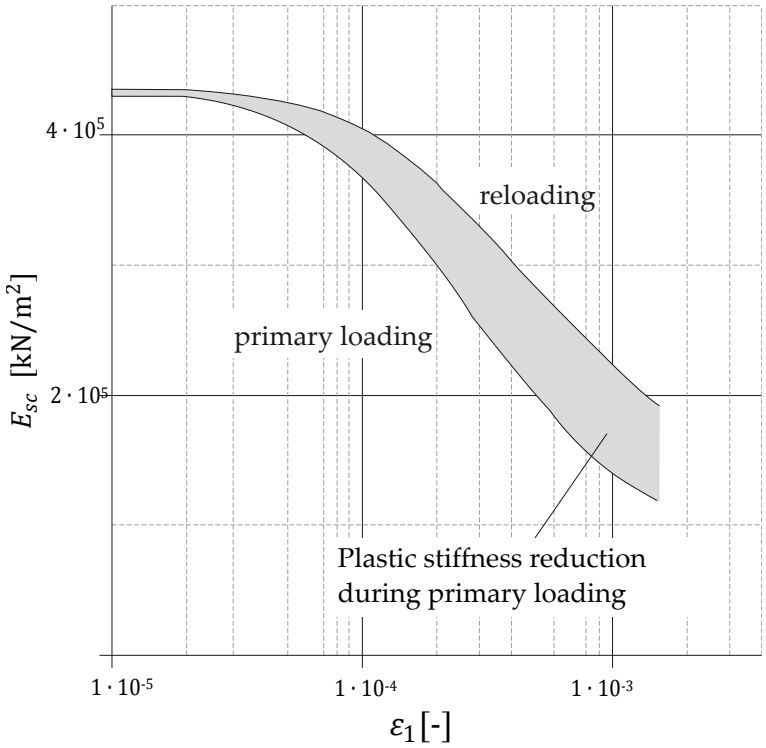


Figure 38: Stiffness reduction in initial -or primary loading and in unloading/reloading

7.4 Model Parameters

Compared to the standard Hardening Soil model, the Hardening Soil model with small-strain stiffness requires two additional stiffness parameters as input: G_0^{ref} and $\gamma_{0.7}$. All other parameters, including the alternative stiffness parameters, remain the same as in the standard Hardening Soil model. G_0^{ref} defines the shear modulus at very small strains e.g. $\varepsilon < 10^{-6}$ at a reference minor principal stress of $-\sigma'_3 = p^{ref}$.

The Poisson's ratio ν_{ur} is assumed a constant, as everywhere in PLAXIS, so that the shear modulus G_0^{ref} can also be calculated from the very small strain Young's modulus as:

$$G_0^{ref} = E_0^{ref} / \left(2(1+\nu_{ur})\right) \qquad Eq.\ [174]$$

The threshold shear strain $\gamma_{0.7}$ is the shear strain at which the secant shear modulus G_s^{ref} is decayed to $0.722G_0^{ref}$. The threshold shear strain $\gamma_{0.7}$ is to be supplied for virgin loading. In summary, the input stiffness parameters of the Hardening Soil model with small-strain stiffness are listed below:

m	Power for stress-level dependency of stiffness	[-]
E_{50}^{ref}	Secant stiffness in standard drained triaxial test	[KN/m^2]
E_{oed}^{ref}	Tangent stiffness for primary oedometer loading	[KN/m^2]
E_{ur}^{ref}	Unloading / reloading stiffness from drained triaxial test	[KN/m^2]
$\nu_{0.7}$	Poisson's ratio for unloading-reloading	[-]
G_0^{ref}	Reference shear modulus at very small strains ($\varepsilon < 10^{-6}$)	[KN/m^2]
$\gamma_{0.7}$	Threshold shear strain at which $G_s = 0.722G_0$	[-]

Figure 39 (on page 90) illustrates the model's stiffness parameters in a drained triaxial test: E_{50}, E_{ur}, and $E_0 = 2G_0(1+\nu_{ur})$. For the order of strains at which E_{ur} and G_0 are defined and determined, one may refer to e.g. Figure 34 (on page 83) and Figure 35 (on page 85).

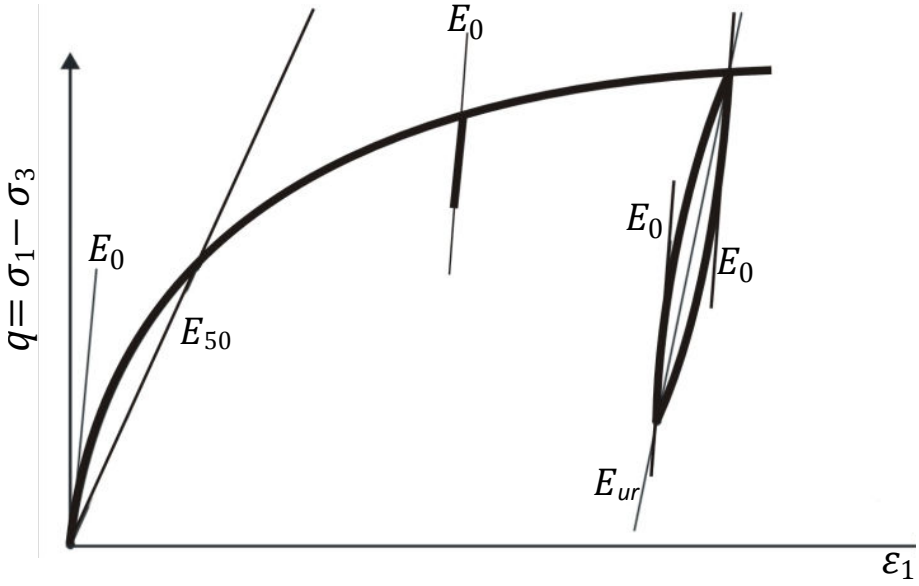


Figure 39: Stiffness parameters E_{50}, E_{ur}, and $E_0 = 2G_0 (1 + \nu_{ur})$ of the Hardening Soil model with small-strain stiffness in a triaxial test

Figure 40 (on page 90) illustrates the model's stiffness parameters in a stress-controlled drained cyclic shear test.

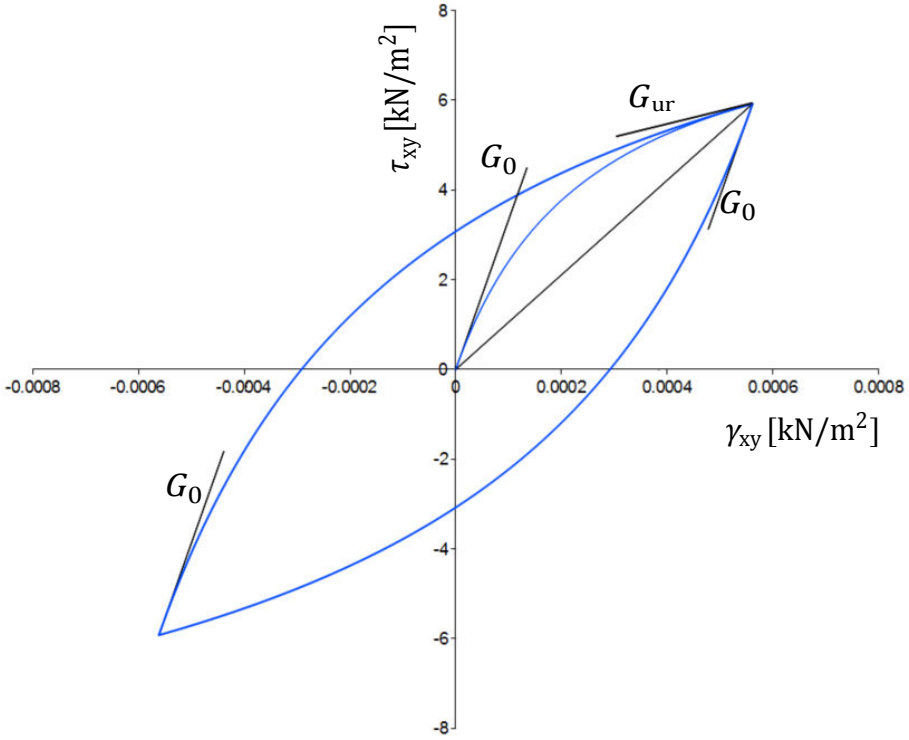


Figure 40: Stiffness parameters in cyclic shear test

A first estimation of the HSsmall parameters for quartz sand based on the relative density (RD) is given in Brinkgreve, Engin & Engin (2010) (on page 252).

7.5 On the parameters G_0 and $\gamma_{0.7}$

A number of factors influence the small-strain parameters G_0 and $\gamma_{0.7}$. Most importantly they are influenced by the material's actual state of stress and void ratio e. In the Hardening Soil model with small-strain stiffness, the stress dependency of the shear modulus G_0 is taken into account with the power law:

$$G_0^{ref} = G_0^{ref}\left(\frac{c\cos(\varphi) - \sigma_3'\sin(\varphi)}{c\cos(\varphi) + p^{ref}\sin(\varphi)}\right)^m \qquad Eq.\ [175]$$

which resembles the ones used for the other stiffness parameters. The threshold shear strain $\gamma_{0.7}$ is taken independently of the mean stress.

Assuming that within a Hardening Soil model with small-strain stiffness (or HS) computation void ratio changes are rather small, the material parameters are not updated for changes in the void ratio. Knowledge of a material's initial void ratio can nevertheless be very helpful in deriving its small-strain shear stiffness G_0. Many correlations are offered in the literature (Benz, 2006) (on page 251). A good estimation for many soils is for example the relation given by Hardin & Black (1969) (on page 253):

$$G_0^{ref} = 33\frac{(2.97 - e)^2}{1 + e}[MPa] \quad for \quad p^{ref} = 100[kPa] \qquad Eq.\ [176]$$

Alpan (1970) (on page 251) empirically related dynamic soil stiffness to static soil stiffness (Figure 41 (on page 91)). The dynamic soil stiffness in Alpan's chart is equivalent to the small-strain stiffness G_0 or E_0. Considering that the static stiffness E_{static} defined by Alpan equals approximately the unloading / reloading stiffness E_{ur} in the Hardening Soil model with small-strain stiffnessmall, Alpan's chart can be used to guess a soil's small-strain stiffness entirely based on its unloading / reloading stiffness E_{ur}. Although Alpan suggests that the ratio E_0 / E_{ur} can exceed 10 for very soft clays, the maximum ratio E_0 / E_{ur} or G_0 / G_{ur} permitted in the HSsmall model is limited to 20.

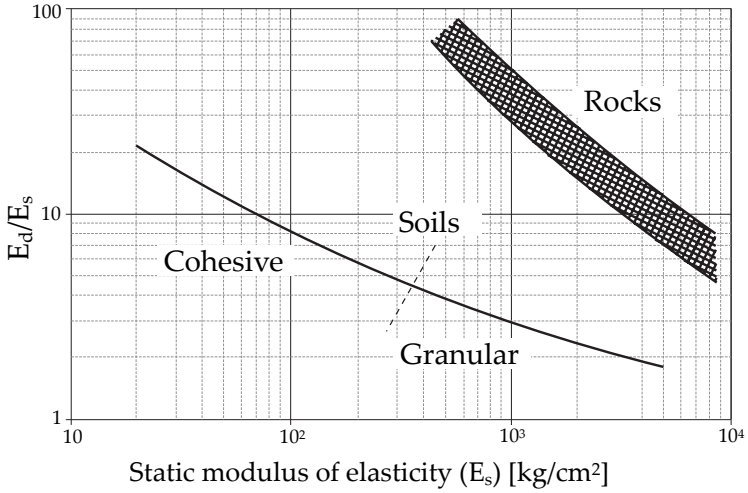


Figure 41: Relation between dynamic ($E_d = E_0$) and static soil stiffness ($E_s \approx E_{ur}$) after Alpan(1970)

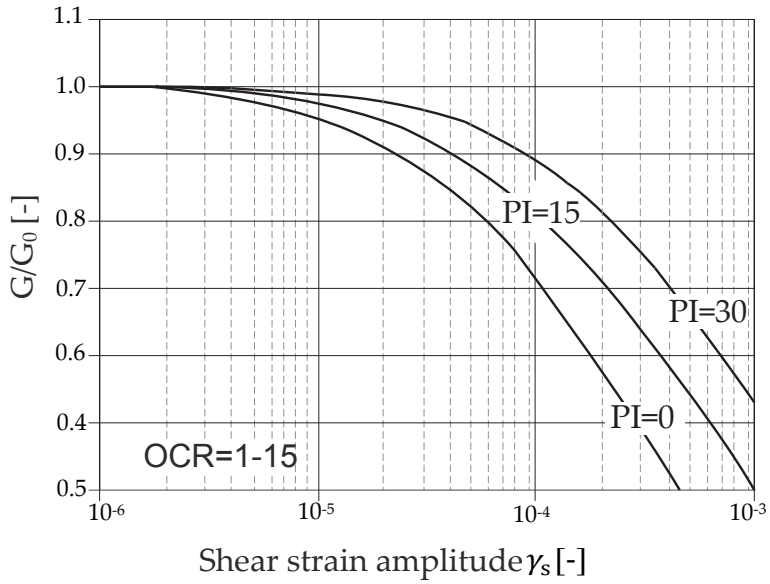


Figure 42: Influence of plasticity index (PI) on stiffness reduction after Vucetic & Dobry (1991)

In the absence of test data, correlations are also available for the threshold shear strain $\gamma_{0.7}$. Figure 42 (on page 92) for example gives a correlation between the threshold shear strain and the Plasticity Index. Using the original Hardin-Drnevich relationship, the threshold shear strain $\gamma_{0.7}$ might be also related to the model's failure parameters. Applying the Mohr-Coulomb failure criterion in Eq. [164] and Eq. [165] yields:

$$\gamma_{0.7} \approx \frac{1}{9G_0}\left[2c'\left(1+\cos\left(2\varphi'\right)\right) - \sigma_1'\left(1+K_0\right)\sin(2\varphi')\right] \qquad \textit{Eq. [177]}$$

where

K_0	=	The earth pressure coefficient at rest.
σ'_1	=	The effective vertical stress (pressure negative).

7.6 Model Initialization

Stress relaxation erases a soil's memory of previous applied stress. Soil aging in the form of particle (or assembly) reorganization during stress relaxation and formation of bonds between them can erase a soil's strain history. Considering that the second process in a naturally deposited soil develops relatively fast, the strain history should start from zero (**H**) in most boundary value problems. This is the default setting in the Hardening Soil model with small-strain stiffnessmall.

However, sometimes an initial strain history may be desired. In this case the strain history can be adjusted by applying an extra load step before starting the actual analysis. Such an additional load step might also be used to model overconsolidated soils. Usually the overconsolidation's cause has vanished long before the start of calculation, so that the strain history should be reset afterwards. Unfortunately, strain history is already triggered by adding and removing a surcharge. In this case the strain history can be reset manually, by using the *Reset small strain* option in the calculation phases window. Also, when resetting displacements to zero, the strain history tensor is reset and the influence of strains from previous calculation phases is ignored.

When using the Hardening Soil model with small-strain stiffnessmall, caution should be given to nil-steps. The strain increments in nil-steps are purely derived from the small numerical unbalance in the system which is due to the accepted tolerated error in the computation. The strain increment direction in nil-steps is therefore arbitrary. Hence, a nil-step may function as randomly reverse load step which is in most cases not desired.

7.7 State parameters in the Hardening Soil model with small-strain stiffness

In addition to the output of standard stress and strain quantities, the Hardening Soil model with small-strain stiffnessmall provides output on *State variables*. These parameters can be visualised by selecting the *State parameters* option from the *stresses* menu. An overview of available state parameters in addition to those listed for the Hardening Soil model is given below:

ε_{xx} - ε_v	Strain history parameter used in strain-dependent stiffness formulation	[-]
ε_{yy} - ε_v	Strain history parameter used in strain-dependent stiffness formulation	[-]
ε_{zz} - ε_v	Strain history parameter used in strain-dependent stiffness formulation	[-]
ε_{xy}	Strain history parameter used in strain-dependent stiffness formulation	[-]
ε_{yz}	Strain history parameter used in strain-dependent stiffness formulation	[-]
ε_{zx}	Strain history parameter used in strain-dependent stiffness formulation	[-]
G_s^{ref}	Reference secant shear modulus at reference stress level	[kN/ m^2]
G/G_{ur}	Ratio of elastic tangent shear modulus over unloading-reloading shear modulus	[-]

7.8 On the use of the Hardening Soil model with small-strain stiffness in dynamic calculations

In contrast to the Hardening Soil model, the Hardening Soil model with small-strain stiffnessmall shows hysteresis in cyclic loading (Figure 39 (on page 90)). The amount of hysteresis depends on the magnitude of the corresponding strain amplitude. However, note that the model does not generate accumulated strains with multiple loading cycles, nor does it generate accumulated pore pressures with undrained behaviour. When the Hardening Soil model with small-strain stiffnessmall is used wave velocities are not shown because they vary due to the stress-dependent stiffness.

When applied in dynamic calculations, the hysteretic behaviour of the Hardening Soil model with small-strain stiffnessmall leads to damping. The amount of hysteretic damping depends on the applied load amplitude and corresponding strain amplitudes. The maximum amount of hysteretic damping obtained with the Hardening Soil

model with small-strain stiffnessmall depend on the ratio of G_0 and $G_{ur} = E_{ur} / 2(1 + \upsilon_{ur})$. A larger ratio leads to a larger maximum amount of hysteretic damping. For more information about the hysteretic damping in the Hardening Soil model with small-strain stiffnessmall reference is made to Brinkgreve, Kappert & Bonnier (on page 252).

7.9 Other differences with the Hardening Soil model

7.9.1 The mobilised dilatancy angle

The shear hardening flow rule of both the Hardening Soil model and the Hardening Soil model with small-strain stiffness have the linear form:

$$\dot{\varepsilon}_v^p = \sin(\psi_m)\dot{\gamma}^p \qquad \textit{Eq. [178]}$$

The mobilised dilatancy angle ψ_m in compression however, is defined differently. The HS model assumes the following:

$$\begin{aligned}
&For \;\; \sin(\varphi_m) < \tfrac{3}{4}\sin(\varphi) && \psi_m = 0 \\
&For \;\; \sin(\varphi_m) < \tfrac{3}{4}\sin(\varphi) \;\; and \;\; \psi > 0 && \sin(\psi_m) = \max\left(\frac{\sin(\varphi_m) - \sin(\varphi_{cv})}{1 - \sin(\varphi_m)\sin(\varphi_{cv})},\, 0\right) \\
&For \;\; \sin(\varphi_m) < \tfrac{3}{4}\sin(\varphi) \;\; and \;\; \psi \le 0 && \psi_m = \psi \\
&If \;\; \varphi = 0 && \psi_m = 0
\end{aligned} \qquad \textit{Eq. [179]}$$

where

φ_{cv} = Critical state friction angle, being a material constant independent of density.

φ_m = The mobilised friction angle.

$$\sin(\phi_m) = \frac{\sigma_1' - \sigma_3'}{\sigma_1' + \sigma_3' - 2c\cot(\phi)} \qquad \textit{Eq. [180]}$$

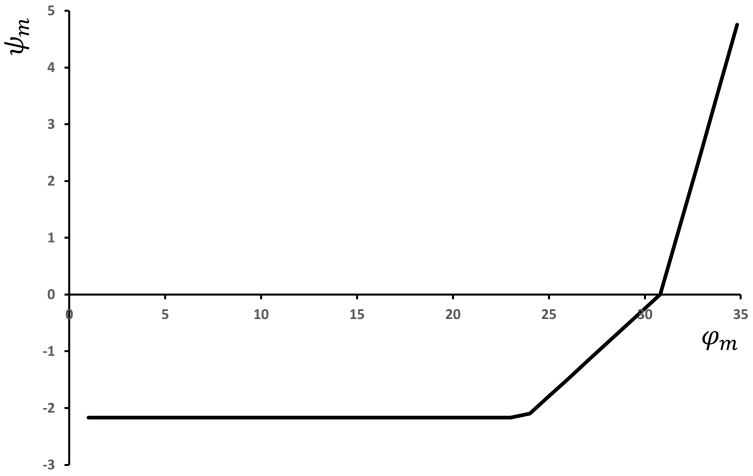


Figure 43: Plot of mobilised dilatancy angle ψ_m and mobilized friction angle φ_m for Hardening Soil model with small-strain stiffness

For small mobilised friction angles and for negative values of ψ_m, as computed by Rowe's formula, ψ_m in the Hardening Soil model is taken zero. Bounding the lower value of ψ_m may sometimes yield too little plastic volumetric strains though. Therefore, the Hardening Soil model with small-strain stiffness adapts an approach by Li & Dafalias (2000) (on page 253) whenever ψ_m, as computed by Rowe's formula, is negative. In that case, the mobilised dilatancy in the Hardening Soil model with small-strain stiffness is calculated by the following equation:

$$\sin(\psi_m) = \frac{1}{10}\left(-M_c \exp\left[\frac{1}{15}\ln\left(\frac{M_c}{M_d}\frac{q}{q_a}\right)\right] + M_d\right) \qquad \textit{Eq. [181]}$$

where:

$$M_c = \frac{6\sin(\varphi_{cv})}{3-\sin(\varphi_{cv})} \qquad \textit{Eq. [182]}$$

$$M_d = \frac{6\sin(\varphi_m)}{3-\sin(\varphi_m)} \qquad \textit{Eq. [183]}$$

$$\frac{q}{q_a} = \max\left(\frac{1-\sin(\varphi_{cv})}{\sin(\varphi_{cv})} \cdot \frac{\sin(\varphi_m)}{1-\sin(\varphi_m)},\ 10^{-4}\right) \qquad \textit{Eq. [184]}$$

And the mobilized friction angle is limited to:

$$\sin(\varphi_m) \geq \frac{\sin(\varphi_{cv})}{2+\sin(\varphi_{cv})} \qquad \textit{Eq. [185]}$$

The mobilised dilatancy as a function of φ_m for the Hardening Soil model with small-strain stiffness is visualised in Figure 43 (on page 95) for the specific case of φ=35° and ψ=5°.

8 The UBC3D-PLM model

During an earthquake, the seismic waves propagate from the source till the ground surface, causing ground shaking. The soil deposit acts as a filter causing the variation of the seismic waves in terms of amplitude, duration and frequency content at any depth of the soil deposit. The effects of an earthquake can be different, such as structural damages, landslides and soil liquefaction.

The term liquefaction is used to describe a variety of phenomena that occurs in saturated cohesionless soils under undrained conditions. Under static and cyclic loading, dry cohesionless soils tend to densify. If these soils are saturated and the applied load acts in a short time, as in the case of an earthquake, the tendency to densify causes an increase in excess pore pressures that cannot rapidly be dissipated and consequently a decrease in the effective stresses occurs. When this happens, the soil behaves as a fluid.

This phenomenon can be explained considering that the shear resistance τ for cohesionless soils is given by Coulomb's formula:

$$\tau = \sigma'_{vo}\tan(\varphi) \qquad \textit{Eq. [186]}$$

where

σ'_{v0} = The initial effective stress
φ = The friction angle.

According to Terzaghi's formula, the effective stress is given by:

$$\sigma'_{vo} = \sigma_{vo} - p_w \qquad \textit{Eq. [187]}$$

where

σ_{v0} = The total vertical stress.
p_w = The pore pressure.

When the excess pore pressures Δp_w develop during an earthquake, the equation can be written as:

$$\sigma'_{vo} = \sigma_{vo} - (p_w + \Delta p_w) \qquad \textit{Eq. [188]}$$

which means that the effective stress state tends to decrease and, when it reaches zero, also the shear resistance is null.

In order to evaluate the potential liquefaction hazard of a site, it is necessary to identify the predisposing and triggering factors for liquefaction. The predisposing factors are the characteristics of the soil deposit such as particle size and shape, gradation and plasticity characteristics. The triggering factors depend on the earthquake magnitude, duration and peak ground acceleration. To establish if liquefaction can occur in a specific site subjected to a selected earthquake semi-empirical procedures or nonlinear dynamic analyses can be used.

The UBC3D-PLM model[2] is an effective stress elasto-plastic model which is capable of simulating the liquefaction behaviour of sands and silty sands under seismic loading (Tsegaye (2010) (on page 255), Petalas & Galavi

[2] PLM = PLAXIS Liquefaction Model

(2012) (on page 254)). The UBC3D-PLM model formulation is based on the original UBCSAND (University of British Columbia Sand) model introduced by Puebla, Byrne & Phillips (1997) (on page 254) and Beaty & Byrne (1988) (on page 251). The original UBCSAND is a 2D model formulated in the classical plasticity theory with a hyperbolic strain hardening rule, based on the original Duncan-Chang model. The hardening rule relates the mobilised friction angle to the plastic shear strain at a given stress. The UBCSAND model contains a 2D Mohr-Coulomb yield surface and a corresponding non-associated plastic potential function. The flow rule in the model is based on the stress-dilatancy theory developed by Rowe (1962) (on page 254), linearised and simplified according to energy considerations.

The main difference between the UBCSAND model and the UBC3D-PLM model is the generalized 3D formulation of the latter. The UBC3D-PLM model uses the Mohr-Coulomb yield condition in a 3D principal stress space for primary loading, and a yield surface with a simplified kinematic hardening rule for secondary loading. Moreover, a modified non-associated plastic potential function based on Drucker-Prager's criterion is used for the primary yield surface, in order to maintain the assumption of stress-strain coaxiality in the deviatoric plane for a stress path beginning from the isotropic line Tsegaye (2010) (on page 255).

The assessment of the liquefaction potential of a soil deposit can be done by performing a dynamice site response analysis. Generally the following steps are needed to perform such an analysis (Laera & Brinkgreve, 2015 (on page 253)):

- Definition of the geotechnical model of the soil deposit, in terms of soil layer distribution, water table depth, appropriate dynamic boundary conditions and soil mechanical properties to describe its behaviour under static and cyclic loading.
- Definition of the seismic input motion, according to the specific site and the probabilistic study as reported in the current regulations (i.e. Eurocode 8, NTC 2008, etc.).
- Definition of the numerical model to perform the analysis including the appropriate dynamic boundary conditions.

A site response analysis requires a deep and extended investigation of the soil deposit to identify the soil layer distribution and hydraulic conditions as well as the mechanical properties of the soil. When possible, the investigation should be extended until the depth of a rock or rock-like formation. In situ and laboratory tests should be performed to evaluate index properties, stiffness and strength of the soil layers with regard to their behaviour under cyclic loading (Cross-hole and Down-hole in situ tests, among others, and cyclic triaxial, cyclic direct simple shear and resonant column laboratory tests). However, in many cases only data from drained triaxial tests (CD TxC) or in situ tests like SPT or CPT are available. For this reason the UBC3D-PLM model implements a specific formulation with input parameters based on these tests.

Main characteristics of the UBC3D-PLM model and the corresponding input parameters are given below:

- Stress dependent stiffness according to a power law k_B^{*e}, k_G^{*e}, *me*, *ne*, *np*.
- Plastic straining due to primary deviatoric loading k_G^{*p}.
- Densification due to the number of cycles during secondary loading f_{dens}.
- Post-liquefaction stiffness degradation f_{Epost}
- Failure according to the Mohr-Coulomb failure criterion φ_{cv}, φ_p and *c*.

8.1 Elasto-plastic behaviour and hardening rule

The UBC3D-PLM model incorporates a non-linear, isotropic law for the elastic behaviour that is defined in terms of the elastic bulk modulus *K* and the elastic shear modulus *G*, which are defined by the following equations:

$$K = k_B^{*e} p_{ref} \left(\frac{p'}{p_{ref}} \right)^{me} \qquad Eq.\ [189]$$

$$G = k_B^{*e} p_{ref} \left(\frac{p'}{p_{ref}} \right)^{ne} \qquad Eq.\ [190]$$

where

k_B^{*e}	=	Bulk modulus factor.
k_G^{*e}	=	Shear modulus factor.
p_{ref}	=	Reference pressure
Factors *me* and *ne*	=	parameters that define the rate of stress dependency of stiffness

Pure elastic behaviour with G_{max} is predicted by the model during the unloading process. Once the stress state reaches the yield surface, plastic behaviour is taken into account as long as the stress point is not going immediately back into the elastic zone.

Note: The implicit Poisson's ratio calculated from elastic bulk and shear modulus from Eq. [189] and Eq. [190] is suitable for dynamic calculation, but using it for gravity loading may give improper initial stress state. Therefore, the user is advised to use another material for the stress initialization.

The first yield surface is defined from a set of Mohr-Coulomb functions. The position and size of the yield surface is defined based on the hardening law. More specifically, plastic hardening based on the principle of strain hardening is used in the model (similar to the Hardening Soil model). The hardening rule governs the amount of plastic strain as a result of mobilisation of the shear strength (*sin* φ_{mob}). The mobilised friction angle derived from the Mohr-Coulomb yield criterion, is given as:

$$\sin(\varphi_{mob}) = \frac{\sigma_1' - \sigma_3'}{\sigma_1' + \sigma_3' - 2c\cot(\varphi_p)} \qquad Eq.\ [191]$$

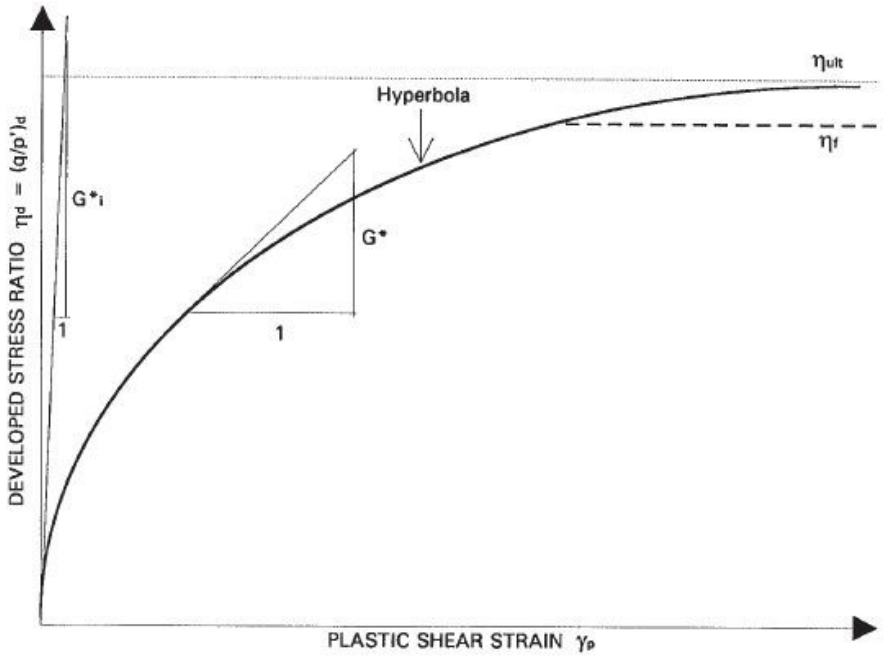


Figure 44: The original UBCSAND hardening rule

The hyperbolic hardening rule (Beaty & Byrne, 1988 (on page 251)) is presented schematically in Figure 44 (on page 98). It relates the increment of the sine of the mobilised friction angle (calculated according to Eq. [191]) to the plastic shear strain increment as follows (Puebla, Byrne & Phillips, 19997 (on page 254)):

$$d\gamma_p = \left(\frac{1}{G^*}\right) d\sin(\varphi_{mob}) \qquad Eq.\ [192]$$

$$G^* = k_G^{*p}\left(\frac{p'}{p_{ref}}\right)^{np}\left(1 - \left(\frac{\sin(\varphi_{mob})}{\sin(\varphi_p)}\right)R_f\right)^2 \qquad Eq.\ [193]$$

where $k^{*p}{}_G$ is the plastic shear modulus factor; np is the plastic shear modulus exponent; φ_{mob} is the mobilised friction angle, which is defined by the stress ratio; φ_p is the peak friction angle; and R_f is the failure ratio η_f / η_{ult}, ranging from 0.5 to 1.0, where η_f is the stress ratio at failure and η_{ult} is the asymptotic stress ratio from the best fit hyperbola. The hardening rule as reformulated by Tsegaye (2010) (on page 255) in UBC3D-PLM model is given as:

$$d\sin(\varphi_{mob}) = 1.5k_G^{*p}\left(\frac{p'}{p_{ref}}\right)^{np}\frac{p_{ref}}{p'}\left(1 - \left(\frac{\sin(\varphi_{mob})}{\sin(\varphi_p)}\right)R_f\right)^2 d\lambda \qquad Eq.\ [194]$$

where $d\lambda$ is the plastic strain increment multiplier.

8.2 Flow rule

The plastic potential function specifies the direction of the plastic strain. A non-associated flow rule based on the Drucker-Prager plastic potential function is used in the UBC3D-PLM model (Tsegaye, 2010 (on page 255)). The plastic potential function g is formulated as:

$$g = q - M(p' + c\cot(\varphi_p)) \qquad Eq.\ [195]$$

$$M = \frac{6\sin(\psi_M)}{3 - \sin(\psi_M)} \qquad Eq.\ [196]$$

where the Drucker-Prager surface is fixed in the compression point.

In the UBC3D-PLM model the flow rule of the original UBCSAND model is used, which is derived from energy considerations by Puebla, Byrne & Phillips (1997) (on page 254). Similar to the Hardening Soil model it is based on three observations (Figure 45 (on page 100)):

- There is a unique stress ratio, defined by the constant volume friction angle φ_{cv}, for which plastic shear strains do not cause plastic volumetric strains.
- Stress ratios which lie below $sin\ \varphi_{cv}$ exhibit contractive behaviour, while stress ratios above $sin\ \varphi_{cv}$ lead to a dilative response. This means that the constant volume friction angle works as the phase transformation angle.
- The amount of contraction or dilatancy depends on the difference between the current stress ratio and the stress ratio at $sin\ \varphi_{cv}$.

The increment of plastic volumetric strain $d\varepsilon^p{}_v$ is calculated as follows:

$$d\varepsilon_{vp} = \sin(\psi_m) d\gamma^p \qquad Eq.\ [197]$$

$$\sin(\psi_m) = \sin(\varphi_m) - \sin(\varphi_{cv}) \qquad Eq.\ [198]$$

where, φ_{cv} is the constant volume friction angle.

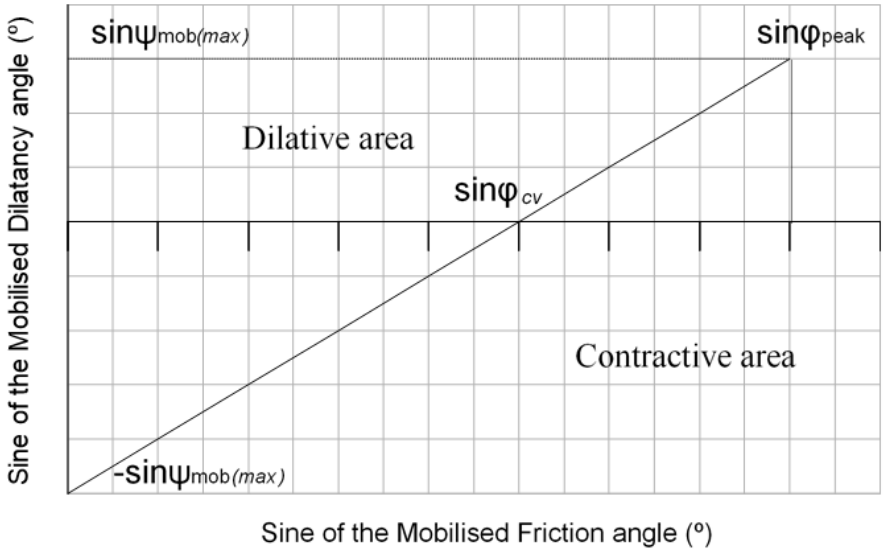


Figure 45: Graphical representation of the modified Rowe's flow rule as used in UBC3D-PLM model

Based on the mobilised friction angle an unloading-reloading criterion is defined in the model as follows:

$$\sin(\varphi^{e}_{mob}) < \sin(\varphi^{0}_{mob}) \ (unloading;\ elastic behaviour) \qquad Eq.\ [199]$$

$$\sin(\varphi^{e}_{mob}) > \sin(\varphi^{0}_{mob}) \ (Loading\ or\ reloading;\ plastic\ behaviour) \qquad Eq.\ [200]$$

The previous mobilised friction angle $sin(\varphi^{0}_{mob})$ is memorised from the previous calculation step, while the current one $sin(\varphi^{e}_{mob})$ is calculated based on the current stresses. During loading, the friction angle is mobilised, and hardening plasticity occurs. During unloading, pure elastic behaviour is predicted until the stress point reaches the p' axis.

8.3 Load state during liquefaction

The UBC3D-PLM model employs two yield surfaces to guarantee a smooth transition into the liquefied state of the soil and to enable the distinction between primary and secondary loading (Figure 46 (on page 101)). The UBC3D-PLM model incorporates a densification law through a secondary yield surface with a kinematic hardening rule that improves the precision of the evolution of the excess pore pressure. This surface generates lower plastic deformations compared to the primary yield surface.

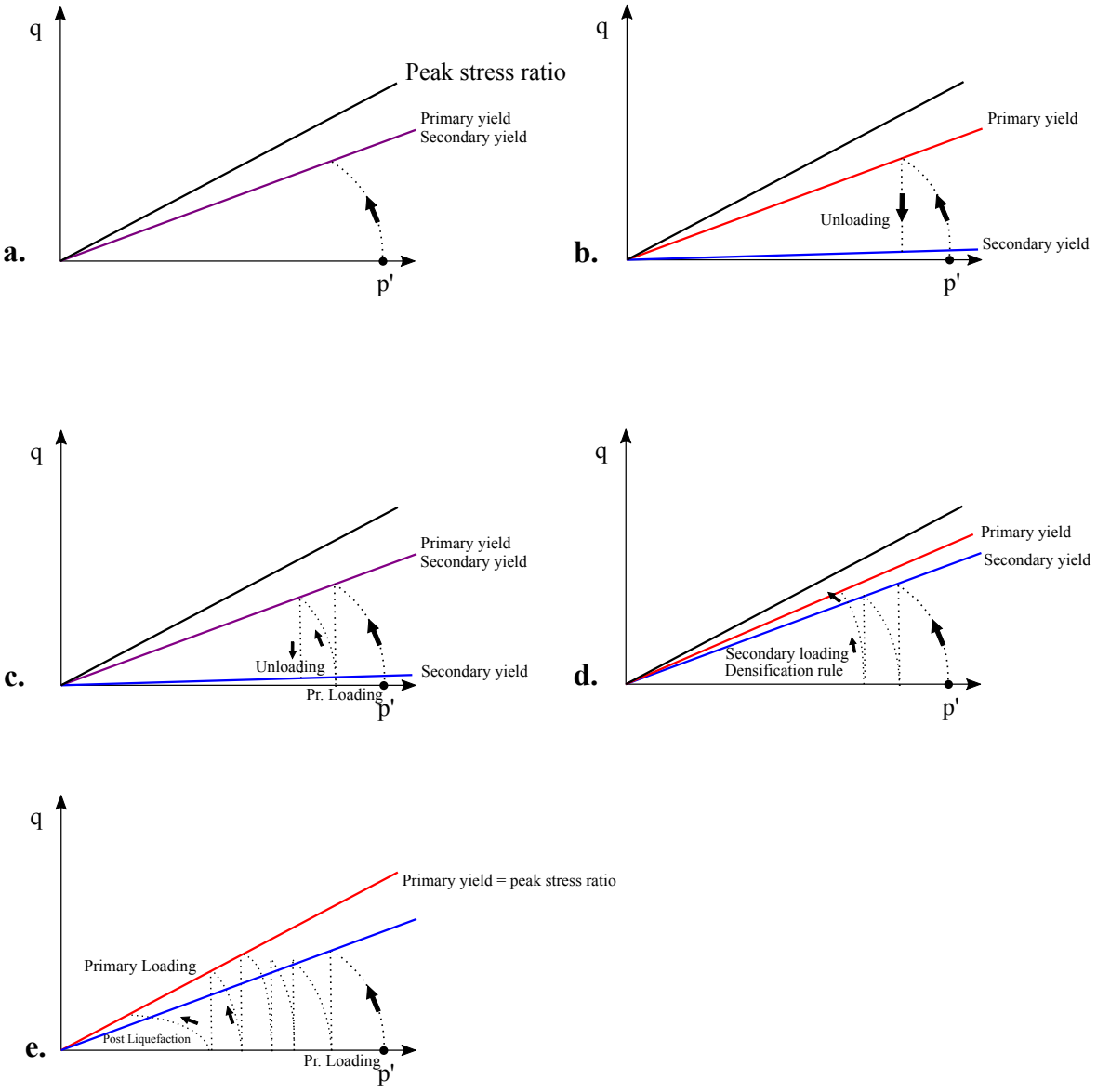


Figure 46: Introduction of two yield surfaces in order to include soil densification, smooth transition in liquefaction and post-liquefaction behaviour

The plastic shear modulus factor k_G^{*p} during primary loading is identical with the one entered as input parameter by the user and is used in the hardening rule governing the hardening of the primary yield surface. The plastic shear modulus factor k_G^{*p} during the secondary loading is a function of the number of cycles followed during the loading process. A simple rule based on stress reversals of loading to unloading and vise versa is used to define the counting of cycles. This leads to an increase of the excess pore pressure during undrained cyclic loading with a decreasing rate until the liquefied state is approached. The modification of the plastic shear modulus factor during the secondary loading is calculated as follows:

$$K_{G,\,\text{secondary}}^{*p} = k_G^{*p}\left(4 + \frac{n_{rew}}{2}\right) hard\, f_{dense} \qquad Eq.\ [201]$$

where

k_G^{*p}	=	Input plastic shear modulus factor.
$k_{G,secondary}^{*p}$	=	Secondary plastic shear modulus factor.
n_{rev}	=	Number of shear stress reversals from loading to unloading or vice versa.
$hard$	=	Factor which is correcting the densification rule for loose soils.
f_{dens}	=	Multiplier which is a user input parameter to adjust the densification rule.

A correction is made in the densification rule for loose sands ($5 \leq (N_1)_{60} \leq 9$) according to the experimental observations and following the formulation of the UBCSAND model proposed by Beaty & Byrne (2011) (on page 251) and reported by Naesgaard (2011) (on page 254). The correction rule is as follows:

$$hard = \min\left(1;\ \max\left(0.5;\ 0.1(N_1)_{60}\right)\right) \qquad Eq.\ [202]$$

Note: The corrected penetration resistance $(N_1)_{60}$ from SPT tests is an input parameter to define only the *hard* factor. However, the user can correlate the other input parameters of the UBC3D-PLM model using $(N_1)_{60}$ (Parameters of the UBC3D-PLM model (on page 103)).

The plastic shear modulus is limited according to the maximum corrected SPT value ($max(N_1)_{60}$) of corresponding dense soils defined as 60.

$$K_{G,\max}^{*p} = K_G^{*p}\left(K_G^{*e}(\max N_{1,60}^2)0.003 + 100\right) \qquad Eq.\ [203]$$

This rule is the result of calibrating a number of direct simple shear tests. Thus, the calibration factor plays a key role when the user wants to model different stress paths (i.e. cyclic triaxial tests, etc.) and the final value is a matter of judgement according to the most critical stress path for a specific problem. It finally leads to an increase of the excess pore pressure during undrained cyclic loading until the liquefied state is approached. The rate of generation of excess pore pressure decreases by increasing number of cycles.

8.4 Post-liquefaction rule and cyclic mobility

An important issue during the modelling of cyclic liquefaction in sands is the volumetric locking. The evolution of the plastic volumetric strains, after the stress path reaches the yield surface defined by the peak friction angle, becomes constant due to the formulation of the flow rule (in Eq. [197]). In the case $sin\ \varphi_{mob}$ becomes $sin\ \varphi_p$ and remains constant meaning that $sin\ \psi_m$ is also constant.

Consequently the stiffness degradation of loose non-cohesive soils due to the post liquefaction behaviour as well as dense non-cohesive soils due to the cyclic mobility cannot be modelled. This limitation is overcome in the formulation of the UBC3D-PLM model with the equation which gradually decreases the plastic shear modulus as a function of the generated plastic deviatoric strain during dilation, due to the deconstruction of the soil skeleton which occurs during dilative behaviour. This leads to the decreased soil stiffness during the contraction phase which follows after the unloading phase. This behaviour is presented in Figure 47 (on page 103) picturing the process of cyclic mobility of a dense sand. The aforementioned stiffness degradation is computed as follows:

$$K_{G,\ post-liquefaction}^{*p} = k_G^{*p} E_{\mathrm{dil}} \qquad Eq.\ [204]$$

$$E_{\mathrm{dil}} = \max\left(e^{-110\varepsilon_{dil}};\ f_{Epost}\right) \qquad Eq.\ [205]$$

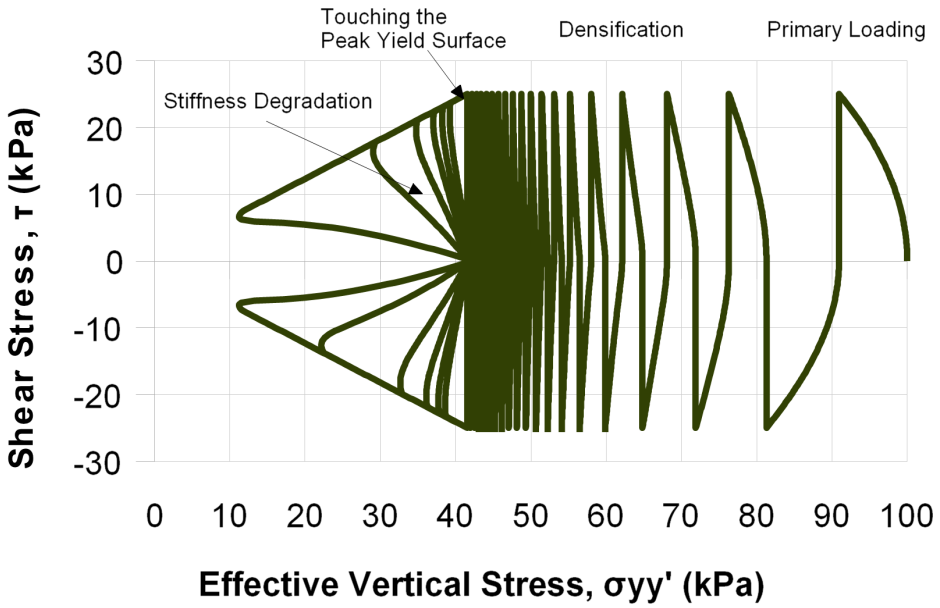


Figure 47: Undrained cyclic shear stress path reproduced with UBC3D-PLM model for a dense sand. Cyclic mobility, stiffness degradation and soil densification are indicated on the graph

where $k^{*p}{}_G$ is the input plastic shear modulus factor, $k^{*p}{}_{G,post\text{-}liquefaction}$ is the plastic shear modulus factor during liquefaction, ε_{dil} is the accumulation of the plastic deviatoric strain which is generated during dilation of the soil element. The minimum value of E_{dil} term in the above mentioned equation is limited by the input parameter f_{Epost}.

8.5 Parameters of the UBC3D-PLM model

Usually, in earthquake engineering, when the onset of liquefaction is the modelling target a cyclic triaxial or a cyclic direct simple shear test is the proper way to extract all the parameters for the UBC3D-PLM model. However, in many cases only data from drained triaxial tests (CD TxC) or in situ tests (SPT) are available. For this reason the UBC3D-PLM model implements a specific formulation with input parameters based on these tests. However, some of the equations based on SPT values proposed by Beaty & Byrne (2011) (on page 251) for the generic calibration of the UBCSAND model should be used with careful consideration for the calibration of the UBC3D-PLM model.

The parameters with their standard units are listed below.

Stiffness parameters:		
$k^{*e}{}_B$	Elastic bulk modulus factor	[-]
$k^{*e}{}_G$	Elastic shear modulus factor	[-]
$k^{*p}{}_G$	Plastic shear modulus factor	[-]

me	Rate of stress-dependency of elastic bulk modulus	[-]
ne	Rate of stress-dependency of elastic bulk modulus	[-]
np	Rate of stress-dependency of plastic shear modulus	[-]
p_{ref}	Reference pressure	[kN/m^2]
Strength parameters:		
φ_{cv}	Constant volume friction angle	[°]
φ_p	Peak friction angle	[°]
c	Cohesion	[kN/m^2]
σ_t	Tension cut-off and tensile strength	[kN/m^2]
Advanced parameters:		
R_f	Failure ratio	[-]
$(N_1)_{60}$	Corrected SPT value	[-]
f_{dens}	Densification factor	[-]
f_{Epost}	Post-liquefaction factor	[-]

The UBC3D-PLM model allows two drainage types: Drained and Undrained A. The other undrained calculations are not available due to the effective stress nature of the model.

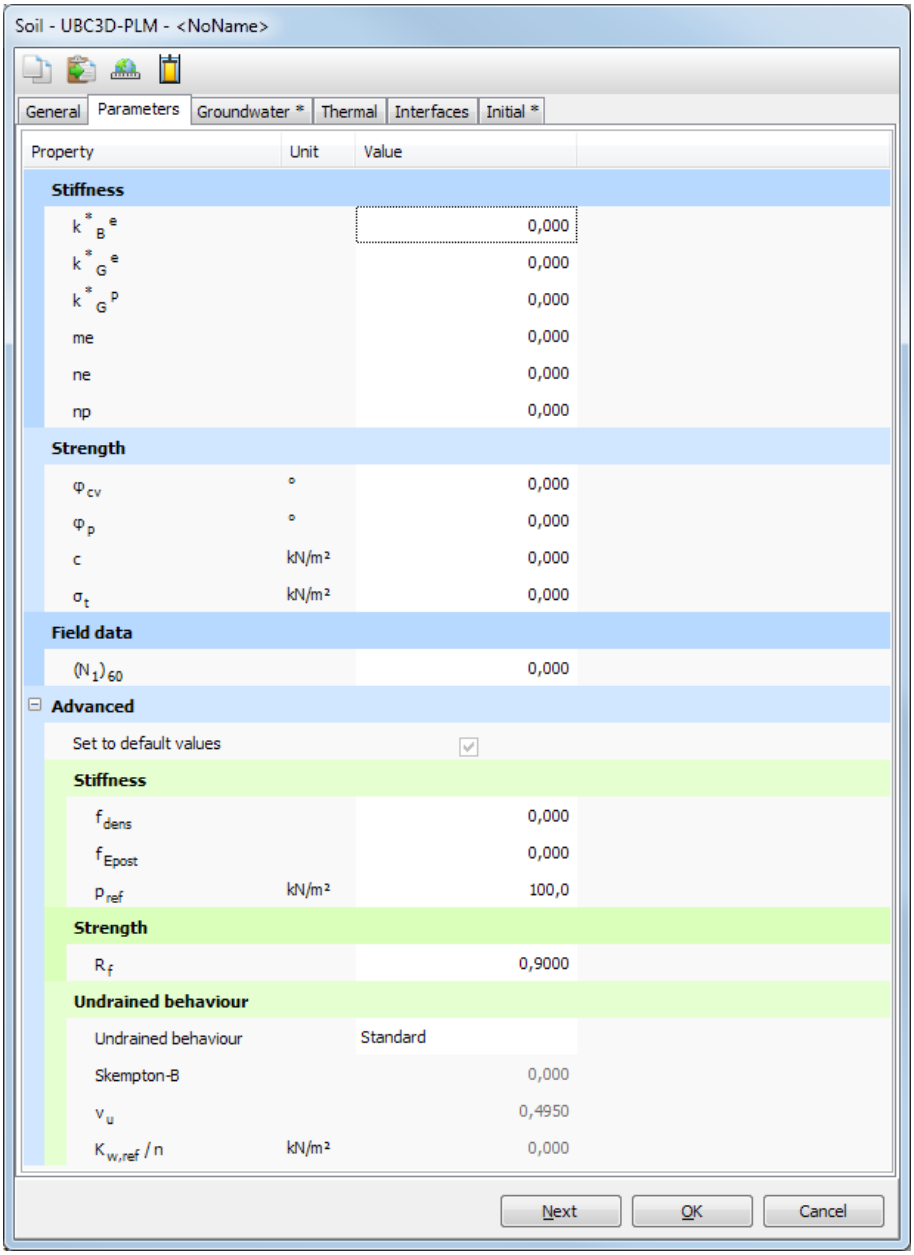


Figure 48: Parameters of the UBC3D-PLM model

8.5.1 *Stiffness modulus factors k^{*e}_B, k^{*e}_G & k^{*p}_G and indexes me, ne and np*

Beaty & Byrne (2011) (on page 251) proposed a set of equations based on the normalised N_{SPT} value, $(N_1)_{60}$ for the initial generic calibration of the UBCSAND *904aR* model. Makra (2013) revised the proposed equations and highlighted the differences between the original UBCSAND 2D formulation and the UBC3D-PLM model, as implemented in PLAXIS. The proposed equations for the generic initial calibration are the following:

$$k_G^{*p} = 21.7 \times 20 \times (N_1)_{60}^{0.3333} \qquad Eq.\ [206]$$

$$k_B^{*p} = 0.7 \times k_G^{*e} \qquad Eq.\ [207]$$

$$k_B^{*p} = k_G^{*e} \times (N_1)_{60}^2 \times 0.003 + 100 \qquad Eq.\ [208]$$

The index parameters *me*, *ne* and *np* should be calibrated by curve fitting. The range of these values is *0-1*. The suggested default values are *me = ne = 0.5* and *np = 0.4*. Alternatively the relative density correlations can be used to calibrate the above mentioned parameters as suggested by Souliotis & Gerolymos (2016) (on page 255).

Note: The implicit Poisson's ratio that is defined based on $k^{*e}{}_B$ and $k^{*e}{}_G$ is suitable for dynamic calculation, but it does not generate a proper initial stress state if the initial stress condition is established by gravity loading procedure. In such a case the user should define another material set for the stress initialization step with proper characteristics.

8.5.2 *Strength parameters φ_{cv}, φ_p and c*

The strength parameters of the primary yield surface φ_{cv}, φ_p and c can be derived directly from CD TxC or DSS tests. The default value for the cohesion c is 0, as in most cases for granular soils without relevant fine component. The peak friction angle φ_p can be calculated from SPT test as:

$$\varphi_p = \varphi_{cv} + \frac{(N_1)_{60}}{10} + \max\left(0;\ \frac{(N_1)_{60} - 15}{5}\right) \qquad Eq.\ [209]$$

The constant volume friction angle φ_{cv} can be derived directly from SPT test using one of the correlations available in literature (Bolton, 1986 (on page 252); Mayne, 2001 (on page 253)).

Note: In the UBC3D-PLM model, the constant volume friction angle φ_{cv} plays the role of the phase transformation angle φ_{pt}.

8.5.3 *Advanced parameters R_f, f_{dens} and f_{Epost}*

The densification factor f_{dens} is a multiplier that controls the scaling of the plastic shear modulus factor during secondary loading. The acceptable range is 0 - 1, when a value below 1 means the $k^{*p}{}_G$ becomes lower and the behaviour softer. It is recommended to use f_{dens} = 1.0 (Petalas & Galavi, 2012 (on page 254))because the variation of the densification does not significantly affect liquefaction triggering.

f_{Epost} is the parameter to adjust post-liquefaction behaviour. The acceptable range of f_{Epost} is 0 - 1 and a value of 0.2 - 1 is recommended. Resistance is underestimated for very dense sands, which can be counterbalanced by an increase of the f_{Epost} parameter.

The failure ratio R_f has a default value of 0.9, but it can be also estimated from the SPT test based on the original UBCSAND (Beaty & Byrne, 2011 (on page 251)):

$$R_f \approx 1.1\left((N_1)_{60}\right)^{-0.15} < 0.99 \qquad Eq.\ [210]$$

8.5.4 *Corrected SPT value $(N_1)_{60}$*

The SPT blow count N_{SPT} is affected by a number of procedural details (rod lengths, hammer energy, sampler details, borehole size). The corrected penetration resistance $(N_1)_{60}$ can be calculated as:

$$(N_1)_{60} = C_E C_R C_B C_S N_{SPT} \qquad Eq.\ [211]$$

where

C_E	=	$ER_m/60$.
ER_m	=	Measured value of the delivered energy as a percentage (%) of the theoretical free-fall hammer energy.
C_R	=	Correction factor to account for different rod lengths.
C_B	=	Correction factor for nonstandard borehole diameters.
C_S	=	Correction factor that depends on the sampler.
N_{SPT}	=	Calculated as $N_2 + N_3$ considering that N_1, N_2 and N_3 are the number of blows needed for the tube to penetrate each 15 cm.

The suggested values for C_B, C_R and C_S are given in Table 2 (on page 107).

Table 2: List of values of the different coefficient for the correction of the SPT test

Coefficient	Condition	Value
General		
Borehole diameter, C_B	65÷115 mm (standard)	1.00
	150 mm	1.05
	200 mm	1.15
Rod length, C_R	3÷4 m	0.75
	4÷6 m	0.85
	6÷10 m	0.95
	10÷30 m	1.00
	>30 m	1.00
Type of sampler, C_S	Standard	1.00
	Non standard	1.1÷1.3

If $(N_1)_{60}$ is not known, the following approximation with relative density RD (in %) can be used:

$$(N_1)_{60} = \frac{RD^2}{15^2} \qquad Eq.\ [212]$$

8.6 State parameters in the UBC3D-PLM model

In addition to the output of standard stress and strain, the UBC3D-PLM model provides output of state variables, such as the excess pore pressure ratio in terms of vertical effective stresses $r_{u,\sigma'v}$ and the mobilised peak friction

angle $\varphi_{p,reached}$. These parameters can be visualised by selecting the *State parameters* option from the *Stresses* menu. An overview of available state parameters is given below:

$sin\ \varphi_{mob}$	Sine of the mobilised friction angle (Eq. [191])	[-]
$sin\ \varphi_{mob,max}$	Sine of the maximum mobilised friction angle	[-]
$\varphi_{p,reached}$	Flag indicating whether peak friction angle has been reached (0/1)	[-]
n_{rev}	Number of half cycles	[-]
$r_{u,\sigma'v}$	Excess pore pressure ratio in terms of vertical effective stress (Eq. [213])	[-]
$r_{u,\sigma'v,max}$	Maximum excess pore pressure ratio in terms of vertical effective stress	[-]
$r_{u,p'}$	Excess pore pressure ratio in terms of mean effective stress (Eq. [214])	[-]
$r_{u,p',max}$	Maximum excess pore pressure ratio in terms of mean effective stresses	[-]
$\varepsilon_{dil,total}$	Accumulated dilative plastic deviatoric strain	[-]

$r_{u,\sigma'v}$, $r_{u,p'}$, $\varphi_{p,reached}$ are further explained in the following subsections:

8.6.1 *Excess pore pressure ratio in terms of vertical effective stresses $r_{u,\sigma'v}$*

The liquefaction potential in terms of vertical effective stress can be expressed by means of the excess pore pressure ratio $r_{u,\sigma'v}$ given by:

$$r_{u,\sigma'_v} = \frac{\sigma'_{v0} - \sigma'_v}{\sigma'_{v0}} = 1 - \frac{\sigma'_v}{\sigma'_{v0}} \qquad Eq.\ [213]$$

where σ'_v is the current vertical effective stress during the dynamic calculation and σ'_{v0} is the initial effective vertical stress prior to the seismic motion. When $r_{u,\sigma'v}$ is equal to 1, the corresponding layer is in a complete liquefied state. consider zones with a maximum $r_{u,\sigma'v}$ greater than 0.7 to be liquefied.

8.6.2 *Excess pore pressure ratio in terms of mean effective stress $r_{u,p}$*

The state variable r_{u,σ'_v} gives similar information as $r_{u,p'}$ but instead of the vertical effective stress the mean effective stress is used:

$$r_{u,p'} = \frac{p'_0 - p'}{p'_0} = 1 - \frac{p'}{p'_0} \qquad Eq.\ [214]$$

where p' is the current mean effective stress during the dynamic calculation and p'_0 is the initial mean effective stress prior to the seismic motion. When $r_{u,p'}$ equals 1, the soil is in a liquified state.

8.6.3 *Reached peak friction angle $\varphi_{p,reached}$*

The reached peak friction angle $\varphi_{p,reached}$ is a flag indicating if φ_p has been reached (0 = no, 1 = yes).

8.7 On the use of the UBC3D-PLM model in dynamic calculations

When subjected to dynamic or cyclic loading, the UBC3D-PLM model generates plastic strains when mobilising the soil's material strength (shear hardening). A Rayleigh damping can be defined to simulate the initial soil's damping characteristics.

The UBC3D-PLM model has been developed for simulating the dynamic behaviour of non-cohesive soils and it is particularly suitable for analysing the problems involving generation of pore pressure in undrained behaviour and liquefaction. For the same reason, it is less suitable for use in static analysis. This limitation can be overcome by using Hardening Soil model(The Hardening Soil model (Isotropic hardening) (on page 67))or Hardening Soil model with small-strain stiffness(The Hardening Soil model with small-strain stiffness (HSsmall) (on page 83)) instead.

The UBC3D-PLM model develops overdamping due to use of G_{max} in elastic unloading. In the problems not involving generation of pore pressure in undrained behaviour, liquefaction or softening due to dilatancy, this limitation can be overcome by using the Hardening Soil model with small-strain stiffnessmall (The Hardening Soil model with small-strain stiffness (HSsmall) (on page 83)) instead.

9 The Soft soil model

As soft soils we consider near-normally consolidated clays, clayey silts and peat. A special feature of such materials is their high degree of compressibility. This is best demonstrated by oedometer test data as reported for instance by Janbu in his Rankine lecture (1985). Considering tangent stiffness moduli at a reference oedometer pressure of 100 kPa, he reports for normally consolidated clays $E_{oed} = 1$ to 4 MPa, depending on the particular type of clay considered. The differences between these values and stiffnesses for NC-sands are considerable as here we have values in the range of 10 to 50 MPa, at least for non-cemented laboratory samples. Hence, in oedometer testing normally consolidated clays behave ten times softer than normally consolidated sands. This illustrates the extreme compressibility of soft soils.

A feature of soft soils is the linear stress-dependency of soil stiffness. According to the Hardening Soil model we have:

$$E_{oed} = E_{oed}^{ref} \left(\frac{-\sigma_1'}{p^{ref}} \right)^m \qquad \textit{Eq. [215]}$$

at least for $c = 0$ and $\sigma'_3 = K_0^{nc} \sigma_1'$ and a linear relationship is obtained for $m = 1$. Indeed, on using an exponent equal to unity, the above stiffness law reduces to:

$$E_{oed} = \frac{-\sigma_1'}{\lambda^*} \qquad \textit{Eq. [216]}$$

where

$$\lambda^* = \frac{p^{ref}}{E_{oed}^{ref}} \qquad \textit{Eq. [217]}$$

For this special case of $m = 1$, the Hardening Soil model yields $\dot{\epsilon} = \dot{\sigma}_1' / \sigma_1'$, which can be integrated to obtain the well-known logarithmic compression law $\epsilon = -\lambda^* ln\left(-\sigma_1'\right)$ for primary oedometer loading.

For many practical soft-soil studies, the modified compression index λ^* will be known and the user can compute the oedometer modulus from the relationship:

$$E_{oed}^{ref} = \frac{p^{ref}}{\lambda^*} \qquad \textit{Eq. [218]}$$

From the above considerations it would seem that the Hardening Soil model is quite suitable for soft soils. Indeed, most soft soil problems can be analysed using this model, but the Hardening Soil model is not suitable when considering very soft soils with a high compressibility, i.e $E_{oed}^{ref}/E_{50}^{ref} < 0.5$. For such soils, the Soft Soil model may be used.

Some features of the Soft Soil model are:

- Stress dependent stiffness (logarithmic compression behaviour).
- Distinction between primary loading and unloading-reloading.
- Memory for pre-consolidation stress.
- Failure behaviour according to the Mohr-Coulomb criterion.

9.1 Isotropic states of stress and strain ($\sigma'_1 = \sigma'_2 = \sigma'_3$)

In the Soft Soil model, it is assumed that there is a logarithmic relation between changes in volumetric strain, ε_v, and changes in mean effective stress, p', which can be formulated as:

$$\varepsilon_v - \varepsilon_v^0 = -\lambda^* \ln\left(\frac{p' + c\cot(\varphi)}{p^0 + c\cot(\varphi)}\right) \qquad (virgin\ \ compression) \qquad Eq.\ [219]$$

In order to maintain the validity of Eq. [275] a minimum value of p' is set equal to a unit stress. The parameter λ^* is the modified compression index, which determines the compressibility of the material in primary loading. Note that λ^* differs from the index λ as used by Burland (1965) (on page 252). The difference is that Eq. [275] is a function of volumetric strain instead of void ratio. Plotting Eq. [275] gives a straight line as shown in Figure 58 (on page 139) .

During isotropic unloading and reloading a different path (line) is followed, which can be formulated as:

$$\varepsilon_v^e - \varepsilon_v^{e0} = -\kappa^* \ln\left(\frac{p' + c\cot(\varphi)}{p^0 + c\cot(\varphi)}\right) \qquad (unloading\ \ and\ \ reloading) \qquad Eq.\ [220]$$

Again, a minimum value of p' is set equal to a unit stress. The parameter κ^* is the modified swelling index, which determines the compressibility of the material in unloading and subsequent reloading. Note that κ^* differs from the index κ as used by Burland. The ratio λ^* / κ^* is, however, equal to Burland's ratio λ/κ. The soil response during unloading and reloading is assumed to be elastic as denoted by the superscript e in Eq. [276]. The elastic behaviour is described by Hooke's law. Eq. [276] implies linear stress dependency on the tangent bulk modulus such that:

$$K_{ur} = \frac{E_{ur}}{3(1 - 2v_{ur})} = \frac{p' + c\cot(\varphi)}{k^*} \qquad Eq.\ [221]$$

in which the subscript ur denotes unloading / reloading. Note that effective parameters are considered rather than undrained soil properties, as might be suggested by the subscripts ur. Neither the elastic bulk modulus, K_{ur}, nor the elastic Young's modulus, E_{ur}, is used as an input parameter. Instead, v_{ur} and κ^* are used as input constants for the part of the model that computes the elastic strains.

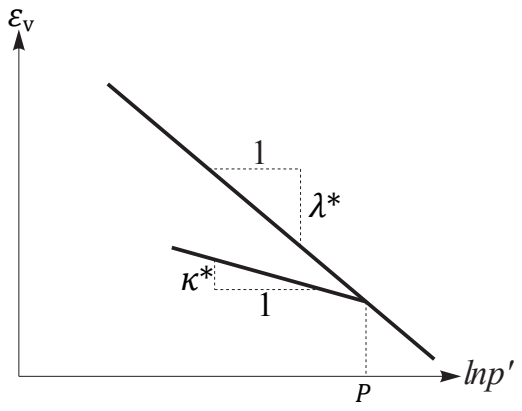


Figure 49: Logarithmic relation between volumetric strain and mean stress

An infinite number of unloading / reloading lines may exist in Figure 49 (on page 112), each corresponding to a particular value of the isotropic pre-consolidation stress p_p. The pre-consolidation stress represents the largest stress level experienced by the soil. During unloading and reloading, this pre-consolidation stress remains constant. In primary loading, however, the pre-consolidation stress increases with the stress level, causing irreversible (plastic) volumetric strains.

9.2 Yield function

The yield function of the Soft Soil model is defined as:

$$f = \bar{f} - p_p \qquad \textit{Eq. [222]}$$

where

$\bar{f}$ = Function of the stress state (p', $\tilde{q}$)

p_p = The pre-consolidation stress which is a function of plastic strain.

$$\bar{f} = \frac{\tilde{q}^2}{M^2\left(p' + c\cot(\varphi)\right)} + p' \qquad \textit{Eq. [223]}$$

$$p_p = p_p^0 \exp\left(\frac{-\varepsilon_v^p}{\lambda^* - \kappa^*}\right) \qquad \textit{Eq. [224]}$$

where

$\tilde{q}$ = similar deviatoric stress quantity as defined for the cap yield surface in the The Hardening Soil model (Isotropic hardening) (on page 67):

$$q = \sigma_1' + (\alpha - 1)\,\sigma_1' \quad \alpha = (3 + \sin(\varphi)) / (3 - \sin(\varphi)) \qquad \textit{Eq. [225]}$$

The yield function ($f = 0$) describes an ellipse in the p' - $\tilde{q}$-plane, as illustrated in Figure 50 (on page 113). The parameter M in Eq. [223] determines the height of the ellipse. The height of the ellipse is responsible for the ratio of horizontal to vertical stresses in primary one-dimensional compression.

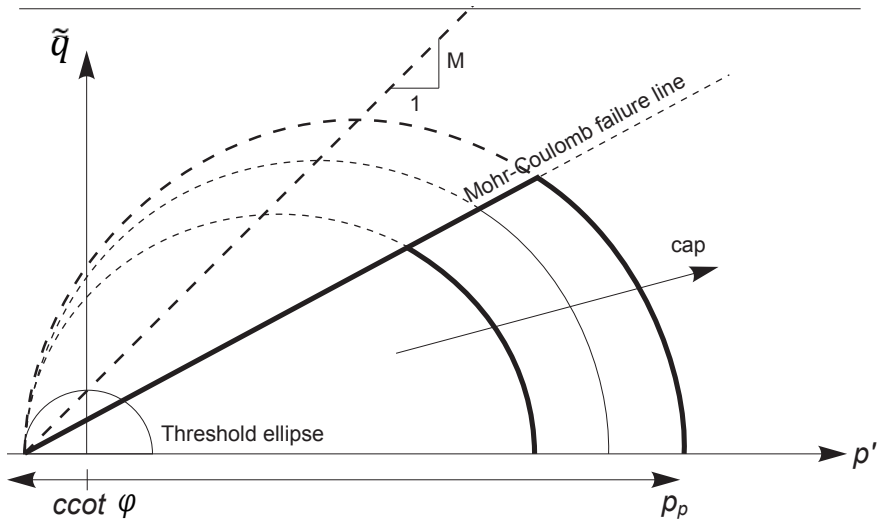


Figure 50: Yield surface of the Soft Soil model in p'- q-plane

As a result, the parameter *M* determines largely the coefficient of lateral earth pressure K_0^{nc}. In view of this, the value of *M* can be chosen such that a known value of K_0^{nc} is matched in primary one-dimensional compression. Such an interpretation and use of *M* differs from the original critical state line idea, but it ensures a proper matching of K_0^{nc}.

The tops of all ellipses are located on a line with slope *M* in the *p'* - $\tilde{q}$-plane. In Burland (1965) (on page 252) and Burland (1967) (on page 252) the *M*-line is referred to as the critical state line and represents stress states at post peak failure. The parameter *M* is then based on the critical state friction angle. In the Soft Soil model, however, failure is not necessarily related to critical state. The Mohr-Coulomb failure criterion is a function of the strength parameters *φ* and *c*, which might not correspond to the *M*-line. The isotropic pre-consolidation stress p_p determines the extent of the ellipse along *p'* axis. During loading, an infinite number of ellipses may exist (see Figure 50 (on page 113)) each corresponding to a particular value of p_p. In tension (*p'< 0*), the ellipse extends to *ccot φ* (Eq. [223] and Figure 50 (on page 113)). In order to make sure that the right hand side of the ellipse (i.e. the 'cap') will remain in the 'compression' zone (*p'> 0*) a minimum value of *ccot φ* is adopted for p_p. For *c = 0*, a minimum value of p_p equal to a stress unit is adopted. Hence, there is a 'threshold' ellipse as illustrated in Figure 50 (on page 113).

The value of p_p is determined by volumetric plastic strain following the hardening relation, Eq. [224]. This equation reflects the principle that the pre-consolidation stress increases exponentially with decreasing volumetric plastic strain (compaction). p_p^0 can be regarded as the initial value of the pre-consolidation stress. The determination of p_p^0 is treated in The initial pre-consolidation stress in advanced models (on page 28). According to Eq. [224] the initial volumetric plastic strain is assumed to be zero.

In the Soft Soil model, the yield function, Eq. [222], describes the irreversible volumetric strain in primary compression, and forms the cap of the yield contour. To model the failure state, a perfectly-plastic Mohr-Coulomb type yield function is used. This yield function represents a straight line in *p'* -$\tilde{q}$ -plane as shown in Figure 50 (on page 113). The slope of the failure line is smaller than the slope of the *M*-line.

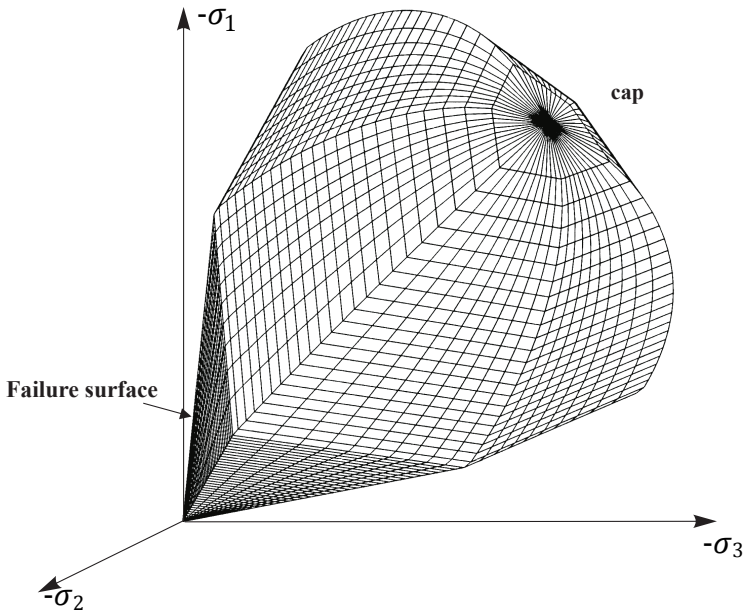


Figure 51: Representation of total yield contour of Soft Soil model in principal stress space

The total yield contour, as shown by the bold lines in Figure 50 (on page 113), is the boundary of the elastic stress area. The failure line is fixed, but the cap may increase in primary compression. Stress paths within this boundary give only elastic strain increments, whereas stress paths that tend to cross the boundary generally give both elastic and plastic strain increments.

For general states of stress $(p', \tilde{q})$, the plastic behaviour of the Soft Soil model is defined by the combination of the cap yield function and the Mohr-Coloumb yield functions. The total yield contour in principal stress space is indicated in Figure 51 (on page 114).

9.3 Parameters of the Soft Soil model

The parameters of the Soft Soil model include compression and swelling indicies, which are typical for soft soils, as well as the Mohr-Coulomb model failure parameters. In total, the Soft Soil model requires the following parameters to be determined:

Basic parameters:

λ^*	Modified compression index	[-]
κ^*	Modified swelling index	[-]
c	Effective cohesion	[kN/m^2]
φ	Friction angle	[°]
ψ	Dilatancy angle	[°]

σ_t	Tensile strength	[kN/m^2]

Advanced parameters (use default settings):

ν_{ur}	Poisson's ratio for unloading / reloading	[-]
K_0^{nc}	Coefficient of lateral stress in normal consolidation	[-]
M	K_0^{nc}-parameter	[-]

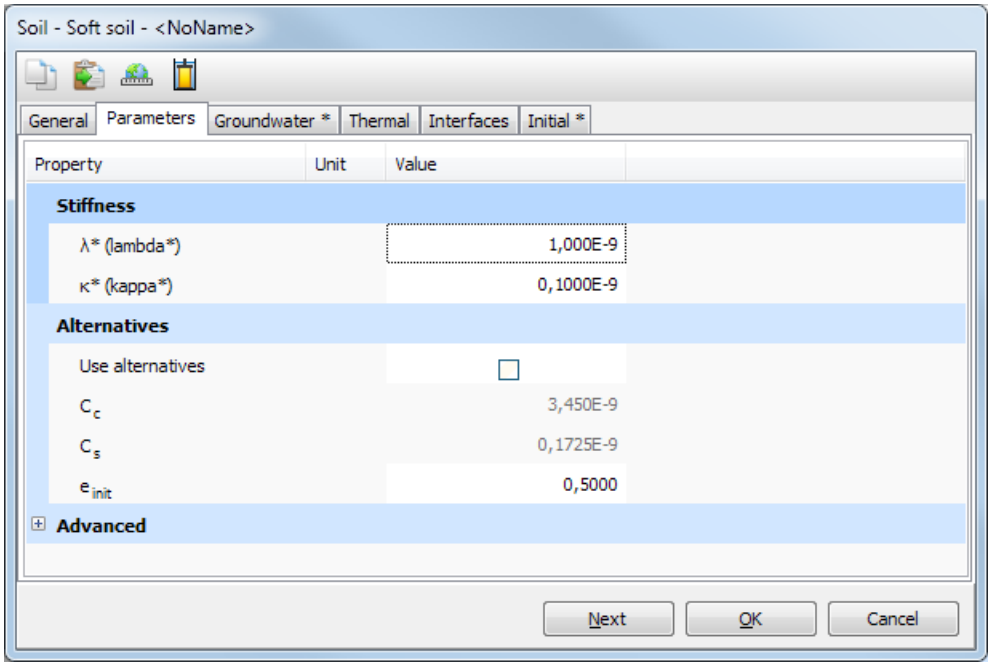


Figure 52: Parameters tabsheet for the Soft Soil model

Figure 52 (on page 115) shows the window for inputting the values of the model parameters. M is calculated automatically from the coefficient of the lateral earth pressure, K_0^{nc}, by means of Eq. [227]. Note that, physically, in the current model M differs from the same parameter in the Modified Cam-Clay model where it is related to the material friction.

9.3.1 *Modified swelling index and modified compression index*

These parameters can be obtained from an isotropic compression test including isotropic unloading. When plotting the logarithm of the mean stress as a function of the volumetric strain for clay-type materials, the plot can be approximated by two straight lines (see Figure 49 (on page 112)). The slope of the primary loading line gives the modified compression index, and the slope of the unloading (or swelling) line gives the modified swelling index. Note that there is a difference between the modified indices κ^* and λ^* and the original Cam-Clay parameters κ and λ. The latter parameters are defined in terms of the void ratio e instead of the volumetric strain ε_v.

Apart from the isotropic compression test, the parameters κ^* and λ^* can be obtained from a one-dimensional compression test. Here a relationship exists with the internationally recognised parameters for one-dimensional compression and swelling, C_c and C_s. These relationships are summarised in Table 3 (on page 116) and Table 4 (on page 116).

Table 3: Relationship to Cam-Clay parameters

1. $\lambda^* = \frac{\lambda}{1+e}$	2. $\kappa^* = \frac{\kappa}{1+e}$

Table 4: Relationship to internationally normalised parameters

3. $\lambda^* = \frac{C_c}{2.3(1+e)}$	3. $\kappa^* \approx \frac{2C_c}{2.3(1+e)}$

Note: Remarks on Table 3 (on page 116) and Table 4 (on page 116)

- In relations 1 and 2, the void ratio, *e*, is assumed to be constant. In fact, *e* will change during a compression test, but this will give a relatively small difference in void ratio. For *e* one can use the average void ratio that occurs during the test or just the initial value.
- In relation 4 there is no exact relation between κ^* and the one-dimensional swelling index C_s, because the ratio of horizontal and vertical stresses changes during one-dimensional unloading. For this approximation it is assumed that the average stress state during unloading is an isotropic stress state, i.e. the horizontal and vertical stresses are equal.
- In practice, swelling is often assumed to be equivalent to recompression behaviour, which, may not be right. Hence κ^* should be based on C_s rather than the recompression index C_r.
- The factor 2.3 in relation 3 is obtained from the ratio between the logarithm of base 10 and the natural logarithm.
- The ratio λ^* / κ^* ($=\lambda / \kappa$) ranges, in general, between 2.5 and 7.

9.3.2 *Cohesion*

The cohesion has the dimension of stresses. A small effective cohesion may be used, including a cohesion of zero. Entering a cohesion will result in an elastic region that is partly located in the 'tension' zone, as illustrated in Figure 50 (on page 113). The left hand side of the ellipse crosses the *p*'-axis at a value of *ccot φ*. In order to maintain the right hand side of the ellipse (i.e. the cap) in the 'pressure' zone of the stress space, the isotropic pre-consolidation stress p_p has a minimum value of *ccot φ*. This means that entering a cohesion larger than zero may result in a state of 'overconsolidation', depending on the magnitude of the cohesion and the initial stress state. As a result, a stiffer behaviour is obtained during the onset of loading. It is not possible to specify undrained shear strength by means of high cohesion and a friction angle of zero. Input of model parameters should always be based on effective values. The PLAXIS option to model undrained behaviour using effective parameters may be used (*Undrained (A)*. Please note that the resulting effective stress path may not be accurate, which may lead to an unrealistic undrained shear strength. Hence, when using *Undrained (A)* as drainage type, the resulting stress state must be checked against a known undrained shear strength profile.

9.3.3 *Friction angle*

The effective angle of internal friction represents the increase of shear strength with effective stress level. It is specified in degrees. Zero friction angle is not allowed. On the other hand, care should be taken with the use of high friction angles. It is often recommended to use φ_{cv}, i.e. the critical state friction angle, rather than a higher value based on small strains. Moreover, using a high friction angle will substantially increase the computational requirements.

9.3.4 *Dilatancy angle*

For the type of materials, which can be described by the Soft Soil model, the dilatancy can generally be neglected. A dilatancy angle of zero degrees is considered in the standard settings of the Soft Soil model.

9.3.5 *Poisson's ratio*

In the Soft Soil model, the Poisson's ratio ν is the well known pure elastic constant rather than the pseudo-elasticity constant as used in the linear elastic perfectly-plastic model. Its value will usually be in the range between 0.1 and 0.2. If the standard setting for the Soft Soil model parameters is selected, then $\nu_{ur} = 0.15$ is automatically used. For loading of normally consolidated materials, Poisson's ratio plays a minor role, but it becomes important in unloading problems. For example, for unloading in a one-dimensional compression test (oedometer), the relatively small Poisson's ratio will result in a small decrease of the lateral stress compared with the decrease in vertical stress. As a result, the ratio of horizontal and vertical stress increases, which is a well-known phenomenon in overconsolidated materials. Hence, Poisson's ratio should not be based on the normally consolidated K_0^{nc}-value, but on the ratio of the horizontal stress increment to the vertical stress increment in oedometer unloading and reloading test such that:

$$\frac{\nu_{ur}}{1-\nu_{ur}} = \frac{\Delta\sigma_{xx}}{\Delta\sigma_{yy}} \qquad \text{(unloading and reloading)} \qquad \textit{Eq. [226]}$$

9.3.6 K_0^{nc}-parameter

The parameter M is automatically determined based on the coefficient of lateral earth pressure in normally consolidated condition, K_0^{nc}, as entered by the user. The exact relation between M and K_0^{nc} gives (Brinkgreve, 1994) (on page 252):

$$M = \sqrt{\frac{\left(1-K_0^{nc}\right)^2}{\left(1+2K_0^{nc}\right)^2} + \frac{\left(1-K_0^{nc}\right)\left(1-2\nu_{ur}\right)\left(\lambda^*/\kappa^*-1\right)}{\left(1-2K_0^{nc}\right)\left(1-2\nu_{ur}\right)\lambda^*/\kappa^* - \left(1-K_0^{nc}\right)\left(1+\nu_{ur}\right)}} \qquad \textit{Eq. [227]}$$

The value of M is indicated in the input window. As can be seen from Eq. [228], M is also influenced by the Poisson's ratio ν_{ur} and by the ratio λ^*/κ^*. However, the influence of K_0^{nc} is dominant. Eq. [228] can be approximated by:

$$M \approx 3.0 - 2.8K_0^{nc} \qquad \textit{Eq. [228]}$$

9.4 State parameters in the Soft Soil model

In addition to the output of standard stress and strain, the Soft Soil model provides output (when being used) on state variables such as the hardening parameter γ^p and the isotropic pre-consolidation stress p_p. These parameters can be visualised by selecting the *State parameters* option from the *stresses* menu. An overview of available state parameters is given below:

p_{eq}	Equivalent isotropic stress	[kN/m^2]
p_p	Isotropic preconsolidation stress $p_{eq} = p' + \frac{q^2}{M^2(p' - c\cot(\varphi))}$	[kN/m^2]
OCR	Isotropic overconsolidation ratio $OCR = p_p / p^{eq}$	[-]
γ^p	Hardening parameter (equivalent mobilised plastic shear strain)	[-]
E_{ur}	Current stress-dependent elastic Young's modulus	[kN/m^2]
c	Current depth-dependent cohesion	[kN/m^2]

9.5 On the use of the Soft Soil model in dynamic calculations

When using the Soft Soil model in dynamic calculations, the modified swelling index κ^* needs to be selected such that the model correctly predicts wave velocities in the soil. This generally requires a smaller value than just an unloading-reloading index.

When subjected to dynamic or cyclic loading, the Soft Soil model will generate plastic strains when the preconsolidation stress is increased. However, it should be noted that stress cycles within the current hardening contour will only generate elastic strains and no (hysteretic) damping, nor accumulation of strains or pore pressure, nor liquefaction. In order to account for the soil damping in cyclic loading, Rayleigh damping may be defined.

10 Soft Soil Creep model (time dependent behaviour)

10.1 Introduction

Both the Hardening Soil model and the Soft Soil model can be used to model the behaviour of compressible soft soils, but none of these models are suitable when considering creep, i.e. secondary compression. All soils exhibit some creep, and primary compression is thus always followed by a certain amount of secondary compression. Assuming the secondary compression (for instance during a period of 10 or 30 years) to be a certain percentage of the primary compression, it is clear that creep is important for problems involving large primary compression. This is for instance the case when constructing embankments on soft soils. Indeed, large primary settlements of footings and embankments are usually followed by substantial creep settlements in later years. In such cases it is desirable to estimate the creep from FEM-computations.

Foundations may also be founded on initially overconsolidated soil layers that yield relatively small primary settlements. Then, as a consequence of the loading, a state of normal consolidation may be reached and significant creep may follow. This is a treacherous situation as considerable secondary compression is not preceded by the warning sign of large primary compression. Again, computations with a creep model are desirable.

Buisman (1936) (on page 252) was probably the first to propose a creep law for clay after observing that soft-soil settlements could not be fully explained by classical consolidation theory. This work on 1D-secondary compression was continued by other researchers including, for example, Bjerrum (1967) (on page 252), Garlanger (1972) (on page 253), Mesri & Godlewski (1977) (on page 254) and Leroueil (1977) (on page 253). More mathematical lines of research on creep were followed by, for example, Sekiguchi (1977) (on page 255), Adachi & Oka (1982) (on page 251) and Borja & Kavaznjian (1985) (on page 252). This mathematical 3D-creep modelling was influenced by the more experimental line of 1D-creep modelling, but conflicts exist.

3D-creep should be a straight forward extension of 1D-creep, but this is hampered by the fact that present 1D-models have not been formulated as differential equations. For the presentation of the Soft Soil Creep model we will first complete the line of 1D-modelling by conversion to a differential form. From this 1D differential equation an extension was made to a 3D-model. This chapter gives a full description of the formulation of the Soft Soil Creep model. In addition, attention is focused on the model parameters. Finally, a validation of the 3D model is presented by considering both model predictions and data from triaxial tests. Here, attention is focused on constant strain rate triaxial tests and undrained triaxial creep tests. For more applications of the model the reader is referred to Vermeer, Stolle & Bonnier (1998) (on page 255), Vermeer & Neher (1999) (on page 255) and Brinkgreve (2004) (on page 252).

Some basic characteristics of the Soft Soil Creep model are:

- Stress-dependent stiffness (logarithmic compression behaviour)

- Distinction between primary loading and unloading-reloading
- Secondary (time-dependent) compression
- Ageing of pre-consolidation stress
- Failure behaviour according to the Mohr-Coulomb criterion

10.2 Basics of one-dimensional creep

When reviewing previous literature on secondary compression in oedometer tests, one is struck by the fact that it concentrates on behaviour related to step loading, even though natural loading processes tend to be continuous or transient in nature. Buisman (1936) (on page 252) was probably the first to consider such a classical creep test. He proposed the following equation to describe creep behaviour under constant effective stress:

$$\varepsilon = \varepsilon_c - C_B \log\left(\frac{t}{t_c}\right) \qquad for \qquad t > t_c \qquad Eq.\ [229]$$

where

ε_c	=	The strain up to the end of consolidation.
t	=	Time measured from the beginning of loading.
t_c	=	Time to the end of primary consolidation and C_B is a material constant.

Please note that we do not follow the soil mechanics convention that compression is considered positive. Instead, compressive stresses and strains are taken to be negative. For further consideration, it is convenient to rewrite this equation as:

$$\varepsilon = \varepsilon_c - C_B \log\left(\frac{t_c + t'}{t_c}\right) \qquad for \qquad t' > 0 \qquad Eq.\ [230]$$

with $t' = t - t_c$ being the effective creep time.

Based on the work by Bjerrum on creep, as published for instance in 1967, Garlanger (1972) (on page 253) proposed a creep equation of the form:

$$e = e_c - C_a \log\left(\frac{\tau_c + \tau'}{\tau_c}\right) \quad with \quad C_a = C_B(1 + e_0) \quad for: \quad t' > 0 \qquad Eq.\ [231]$$

Differences between Garlanger's and Buisman's forms are modest. The engineering strain ε is replaced by void ratio e and the consolidation time t_c is replaced by the parameter τ_c. Eq. [230] and Eq. [231] are identical when choosing $\tau_c = t_c$. For the case that $\tau_c = t_c$, differences between both formulations will vanish when the effective creep time t' increases.

For practical consulting, oedometer tests are usually interpreted by assuming $t_c = 24h$. Indeed, the standard oedometer test is a *Multiple Stage Loading Test* with loading periods of precisely one day. Due to the special assumption that this loading period coincides to the consolidation time t_c, it follows that such tests have no effective creep time.

Hence one obtains $t' = 0$ and the log-term drops out of Eq. [231]. It would thus seem that there is no creep in this standard oedometer test, but this suggestion is false. Even highly impermeable oedometer samples need less than one hour for primary consolidation. Then all excess pore pressures are zero and one observes pure creep for the other 23 hours of the day. Therefore we will not make any assumptions about the precise values of τ_c and t_c.

Another slightly different possibility to describe secondary compression is the form adopted by Butterfield (1979) (on page 252):

$$\varepsilon^H = \varepsilon_c^H - c\ln\left(\frac{\tau_c + t'}{\tau_c}\right) \qquad for \qquad t' > 0 \qquad Eq.\ [232]$$

where ε^H is the logarithmic strain defined as:

$$\varepsilon^H = \ln\left(\frac{V}{V_0}\right) = \ln\left(\frac{1+e}{1+e_0}\right) \qquad Eq.\ [233]$$

with the subscript '0' denoting the initial values. The superscript 'H' is used to denote logarithmic strain, as the logarithmic strain measure was originally used by Hencky. For small strains it is possible to show that:

$$c = \frac{C_a}{(1+e_0)\cdot \ln 10} = \frac{C_B}{\ln 10} \qquad Eq.\ [234]$$

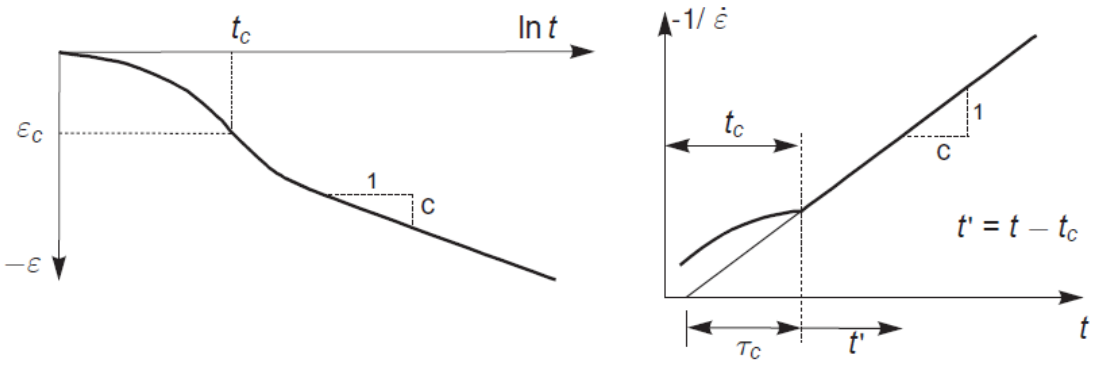
because then logarithmic strain is approximately equal to the engineering strain. Both Butterfield (1979) (on page 252) and den Haan (1994) (on page 252) showed that for cases involving large strain, the logarithmic small strain supersedes the traditional engineering strain.

10.3 On the variables τ_c and ε_c

In this section attention will first be focused on the variable τ_c. Here a procedure is to be described for an experimental determination of this variable. In order to do so we depart from Eq. [232]. By differentiating this equation with respect to time and dropping the superscript 'H' to simplify the notation, one finds:

$$-\dot{\varepsilon} = \frac{c}{\tau_c + t'} \quad or \quad inversely: \quad \frac{-1}{\dot{\varepsilon}} = \frac{\tau_c + t'}{c} \qquad Eq.\ [235]$$

which allows one to make use of the construction developed by Janbu (1969) (on page 253) for evaluating the parameters c and τ_c from experimental data. Both the traditional way, being indicated in Figure 53 (on page 121) a), as well as the Janbu method of Figure 53 (on page 121) b) can be used to determine the parameter c from an oedometer test with constant load.



a. Creep strain b. Inverse creep strain rate

Figure 53: Standard oedometer test

The use of the Janbu method is attractive, because both τ_c and c follow directly when fitting a straight line through the data. In Janbu's representation of Figure 53 (on page 121) b), τ_c is the intercept with the (non-logarithmic) time axis of the straight creep line. The deviation from a linear relation for $t < t_c$ is due to consolidation.

Considering the classical literature it is possible to describe the end-of-consolidation strain ε_c, by an equation of the form:

$$\varepsilon_c = \varepsilon_c^e + \varepsilon_c^c = -a\ln\left(\frac{\sigma'}{\sigma'_0}\right) - (b-a)\ln\left(\frac{\sigma_{pc}}{\sigma_{p0}}\right) \qquad Eq.\ [236]$$

Note that ε is a logarithmic strain, rather than a classical small strain although we conveniently omit the subscript 'H'. In the above equation σ'_0 represents the initial effective pressure before loading and σ' is the final effective loading pressure. The values σ_{p0} and σ_{pc} represent the pre-consolidation pressure corresponding to before-loading and end-of-consolidation states respectively. In most literature on oedometer testing, one adopts the void ratio e instead of ε, and *log* instead of *ln*, the swelling (recompression) index C_s instead of a, and the compression index C_c instead of b. The above constants a and b relate to C_s and C_c as:

$$a = \frac{C_s}{(1+e_0)\cdot \ln 10} \qquad b = \frac{C_c}{(1+e_0)\cdot \ln 10} \qquad Eq.\ [237]$$

Combining Eq. [232] and Eq. [236] it follows that:

$$\varepsilon = \varepsilon^e + \varepsilon^c = -a\ln\left(\frac{\sigma'}{\sigma'_0}\right) - (b-a)\ln\left(\frac{\sigma_{pc}}{\sigma_{p0}}\right) - c\ln\left(\frac{\tau_c + t'}{\tau_c}\right) \qquad Eq.\ [238]$$

where ε is the total logarithmic strain due to an increase in effective stress from σ'_0 to σ' and a time period of t_c+ t'.

In Figure 54 (on page 122) the terms of Eq. [238] are depicted in an ε - *ln* σ diagram. Notice that this figure has a division of strain increments into an elastic and a creep component. Also, for t'+ tc = 1 day, one arrives precisely on the NC-line.

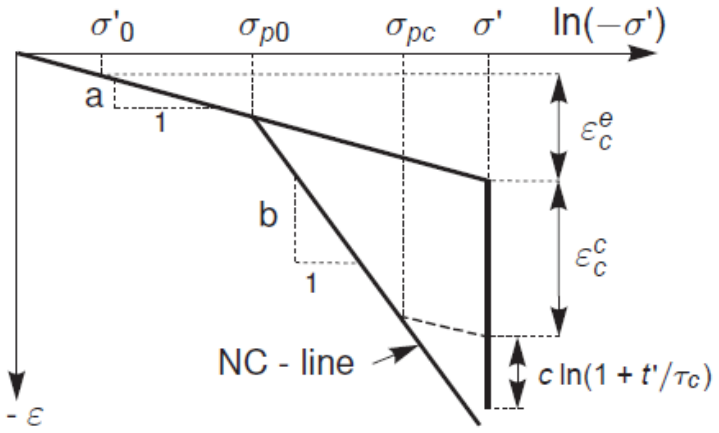


Figure 54: Idealised stress-strain curve from oedometer test with division of strain increments into an elastic and a creep component.

Up to this point, the more general problem of creep under transient loading conditions has not yet been addressed, as it should be recalled that restrictions have been made to creep under constant load. For

generalising the model, a differential form of the creep model is needed. No doubt, such a general equation may not contain t' and neither τ_c as the consolidation time is not clearly defined for transient loading conditions.

10.4 Differential law for 1D-creep

The previous equations emphasize the relation between accumulated creep and time, for a given constant effective stress. For solving transient or continuous loading problems, it is necessary to formulate a constitutive law in differential form, as will be described in this section. In a first step we will derive an equation for τ_c. Indeed, despite the use of logarithmic strain and *ln* instead of *log*, equation (Eq. [238]) is classical without adding new knowledge. Moreover, the question on the physical meaning of τ_c is still open. In fact, we have not been able to find precise information on τ_c in the literature, apart from Janbu's method of experimental determination.

In order to find an analytical expression for the quantity τ_c, we adopt the basic idea that all inelastic strains are time dependent. Hence total strain is the sum of an elastic part ε^e and a time-dependent creep part ε^c. For non-failure situations as met in oedometer loading conditions, we do not assume an instantaneous plastic strain component, as used in traditional elastoplastic modelling. In addition to this basic concept, we adopt Bjerrum's idea that the pre-consolidation stress depends entirely on the amount of creep strain being accumulated in the course of time. In addition to Eq. [238] we therefore introduce the expression:

$$\varepsilon = \varepsilon^e + \varepsilon^c = -a \ln\left(\frac{\sigma'}{\sigma'_0}\right) - (b-a)\ln\left(\frac{\sigma_{pc}}{\sigma_{p0}}\right) \qquad \textit{Eq. [239]}$$

where

$$\sigma_p = \sigma_{p0}\exp\left(\frac{-\varepsilon^c}{b-a}\right) \qquad \textit{Eq. [240]}$$

Please note that ε^c is negative, so that σ_p exceeds σ_{p0}. The longer a soil sample is left to creep the larger σ_p grows. The time-dependency of the pre-consolidation pressure σ_p is now found by combining Eq. [238] and Eq. [239] to obtain:

$$\varepsilon^c - \varepsilon^c_c = -(b-a)\ln\left(\frac{\sigma_p}{\sigma_{pc}}\right) = -c\left(\frac{\tau_c + t'}{\tau_c}\right) \qquad \textit{Eq. [241]}$$

This equation can now be used for a better understanding of τ_c, at least when adding knowledge from standard oedometer loading. In conventional oedometer testing the load is stepwise increased and each load step is maintained for a constant period of $t_c + t' = \tau$, where τ is precisely one day.

In this way of stepwise loading the so-called normal consolidation line (NC-line) with $\sigma_p = \sigma'$ is obtained. On entering $\sigma_p = \sigma'$ and $t' = \tau - t_c$ into Eq. [241] it is found that:

$$(b-a)\ln\left(\frac{\sigma'}{\sigma_{pc}}\right) = c\left(\frac{\tau_c + \tau - t_c}{\tau_c}\right) \quad for: \quad OCR = 1 \qquad \textit{Eq. [242]}$$

It is now assumed that $(\tau_c - t_c) << \tau$. This quantity can thus be disregarded with respect to τ and it follows that:

$$\frac{\tau}{\tau_c} = \left(\frac{\sigma'}{\sigma_{pc}}\right)^{\frac{b-a}{c}} \quad or: \quad \tau_c = \tau\left(\frac{\sigma_{pc}}{\sigma'}\right)^{\frac{b-a}{c}} \qquad \textit{Eq. [243]}$$

Hence τ_c depends both on the effective stress σ' and the end-of-consolidation pre-consolidation stress σ_{pc}. In order to verify the assumption $(\tau_c - t_c) << \tau$, it should be realised that usual oedometer samples consolidate for relatively short periods of less than one hour. Considering load steps on the normal consolidation line, we have

OCR=1 both in the beginning and at the end of the load step. During such a load step σ_p increases from σ_{p0} up to σ_{pc} during the short period of (primary) consolidation. Hereafter σ_p increases further from σ_{pc} up to σ' during a relatively long creep period. Hence, at the end of the day the sample is again in a state of normal consolidation, but directly after the short consolidation period the sample is under-consolidated with $\sigma_p < \sigma'$. For the usually very high ratios of $(b - a)/c \geq 15$, we thus find very small τ_c-values from Eq. [243]. Hence not only t_c but also τ_c tends to be small with respect to τ. It thus follows that the assumption $(\tau_c - t_c) << \tau$ is certainly correct.

Having derived the simple expression Eq. [243] for τ_c, it is now possible to formulate the differential creep equation. To this end Eq. [238] is differentiated to obtain:

$$\dot{\varepsilon} = \dot{\varepsilon}^e + \dot{\varepsilon}^c = -a\frac{\dot{\sigma}'}{\sigma'} - \frac{c}{\tau_c}\left(\frac{\sigma_{pc}}{\sigma_p}\right)^{\frac{b-a}{c}} \qquad \textit{Eq. [244]}$$

where $\tau_c + t'$ can be eliminated by means of Eq. [241] to obtain:

$$\dot{\varepsilon} = \dot{\varepsilon}^e + \dot{\varepsilon}^c = -a\frac{\sigma'}{\sigma'} - \frac{c}{\tau_c}\left(\frac{\sigma_{pc}}{\sigma_p}\right)^{\frac{b-a}{c}} \qquad \textit{Eq. [245]}$$

with:

$$\sigma_p = \sigma_{p0}\exp\left(\frac{-\varepsilon^c}{b-a}\right) \qquad \textit{Eq. [246]}$$

Again it is recalled that ε^c is a compressive strain, being considered negative in this manual. Eq. [243] can now be introduced to eliminate τ_c and σ_{pc} and to obtain:

$$\dot{\varepsilon} = \dot{\varepsilon}^e + \dot{\varepsilon}^c = -a\frac{\dot{\sigma}'}{\sigma'} - \frac{c}{\tau_c}\left(\frac{\sigma'}{\sigma_p}\right)^{\frac{b-a}{c}} \qquad \textit{Eq. [247]}$$

10.5 Three-dimensional-model

On extending the 1D-model to general states of stress and strain, the well-known stress invariants for isotropic stress p and deviatoric stress q are adopted. These invariants are used to define a new stress measure named p^{eq}:

$$p^{eq} = p' + \frac{\tilde{q}^2}{M^2\left(p' + c\cot(\varphi)\right)} \qquad \textit{Eq. [248]}$$

and q is a similar deviatoric stress quantity as defined in the Hardening Soil model and Soft Soil model. In Figure 55 (on page 125) it is shown that the stress measure p^{eq} is constant on ellipses in p - $\tilde{q}$-plane. In fact we have the ellipses from the Modified Cam-Clay model as introduced by Roscoe & Burland (1968) (on page 254).

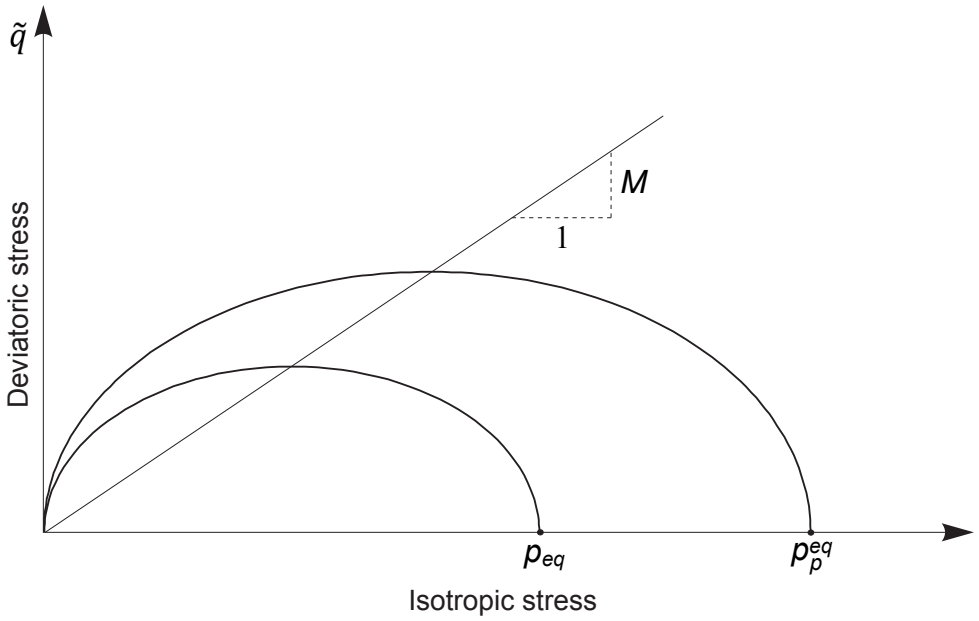


Figure 55: Diagram of p^{eq}-ellipse in a p-$\tilde{q}$-plane

The soil parameter *M* represents the slope of the so-called '*critical state line*' as also indicated inFigure 55 (on page 125). We use:

$$M = \frac{6\sin(\varphi_{cv})}{3 - \sin(\varphi_{cv})} \qquad \textit{Eq. [249]}$$

where

φ_{cv} = Critical-void friction angle, also referred to as critical-state friction angle.
p^{eq} = The equivalent pressure is constant along ellipsoids in principal stress space.

To extend the 1D-theory to a general 3D-theory, attention is now focused on normally consolidated states of stress and strain as met in oedometer testing. In such situations it yields $\sigma'_2 = \sigma'_3 = K_0^{nc}\,\sigma'_1$, and it follows from Eq. [248] that:

$$p^{eq} = \sigma_1'\left[\frac{1 + 2K_0^{nc}}{3} + \frac{3\left(1 - K_0^{nc}\right)^2}{M^2\left(1 + 2K_0^{nc}\right)}\right],$$
$$p_p^{eq} = \sigma_p\left[\frac{1 + 2K_0^{nc}}{3} + \frac{3\left(1 - K_0^{nc}\right)^2}{M^2\left(1 + 2K_0^{nc}\right)}\right] \qquad \textit{Eq. [250]}$$

where

$p^{eq}{}_p$ = Generalised pre-consolidation pressure, being simply proportional to the one-dimensional one σ_p.

For known values of K_0^{nc}, p^{eq} can thus be computed from σ'_1, and $p_p{}^{eq}$ can thus be computed from σ_p. Omitting the elastic strain in the 1D-equation (Eq. [247]), introducing the above expressions for p^{eq} and $p^{eq}{}_p$ and writing ε_v instead of ε it is found that:

$$-\dot{\varepsilon}_v^c = \frac{c}{\tau}\left(\frac{p^{eq}}{p_p^{eq}}\right)^{\frac{b-a}{c}} \quad where \quad p_p^{eq} = p_{p0}^{eq}\exp\left(\frac{-\varepsilon_v^c}{b-a}\right) \qquad Eq.\ [251]$$

For one-dimensional oedometer conditions, this equation reduces to Eq. [247], so that one has a true extension of the 1D-creep model. It should be noted that the subscript '*0*' is once again used in the equations to denote initial conditions and that $\varepsilon_v^c = 0$ for time $t = 0$.

Instead of the parameters *a*, *b* and *c* of the 1D-model, we will now change to the material parameters κ^*, λ^* and μ^*, who fit into the framework of critical-state soil mechanics. Conversion between constants follows the rules:

$$\kappa^* \approx 2a \quad b = \lambda^* \quad \mu^* = c \qquad Eq.\ [252]$$

The expression for κ^* is an approximation. This is a result of the fact that during unloading and reloading under oedometer conditions the ratio of normal stress components changes and therefore the changes of p' and σ_1' deviate.

On using these new parameters, Eq. [251] changes to become:

$$-\dot{\varepsilon}_v^c = \frac{\mu^*}{\tau}\left(\frac{p^{eq}}{p_p^{eq}}\right)^{\frac{\lambda^*-\kappa^*}{\mu^*}} \quad with \quad p_p^{eq} = p_{p0}^{eq}\exp\left(\frac{-\varepsilon_v^c}{\lambda^*-\kappa^*}\right) \qquad Eq.\ [253]$$

As yet the 3D-creep model is incomplete, as we have only considered a volumetric creep strain ε_v^c, whilst soft soils also exhibit deviatoric creep strains.

To introduce general creep strains, we adopt the view that creep strain is simply a time-dependent plastic strain. It is thus logic to assume a flow rule for the rate of creep strain, as usually done in plasticity theory. For formulating such a flow rule, it is convenient to adopt the vector notation and considering principal directions:

$$\underline{\sigma} = (\sigma_1 \quad \sigma_2 \quad \sigma_3)^T \quad and \quad \underline{\varepsilon} = (\varepsilon_1 \quad \varepsilon_2 \quad \varepsilon_3)^T \qquad Eq.\ [254]$$

where *T* is used to denote a transpose. Similar to the 1D-model we have both elastic and creep strains in the 3D-model. Using Hooke's law for the elastic part, and a flow rule for the creep part, one obtains:

$$\dot{\underline{\varepsilon}} = \dot{\underline{\varepsilon}}^e + \dot{\underline{\varepsilon}}^c = \mathbf{D}^{-1}\dot{\underline{\sigma}} + \lambda\frac{\partial g^c}{\partial \underline{\sigma}'} \qquad Eq.\ [255]$$

where the elasticity matrix and the plastic potential function are defined as:

$$\mathbf{D}^{-1} = \frac{1}{E_{ur}}\begin{bmatrix} 1 & -\upsilon_{ur} & -\upsilon_{ur} \\ -\upsilon_{ur} & 1 & -\upsilon_{ur} \\ -\upsilon_{ur} & -\upsilon_{ur} & 1 \end{bmatrix} \quad and \quad g^c = p^{eq} \qquad Eq.\ [256]$$

where E_{ur} relates to the modified swelling index (Eq. [261]). Hence we use the equivalent pressure p^{eq} as a plastic potential function for deriving the individual creep strain-rate components. The subscripts '*ur*' are introduced to emphasize that both the elasticity modulus and Poisson's ratio will determine unloading-reloading behaviour. Now it follows from the above equations that:

$$\dot{\varepsilon}_v^c = \dot{\varepsilon}_1^c + \dot{\varepsilon}_2^c + \dot{\varepsilon}_3^c = \lambda \cdot \left(\frac{\partial p^{eq}}{\partial \sigma_1'} + \frac{\partial p^{eq}}{\partial \sigma_2'} + \frac{\partial p^{eq}}{\partial \sigma_3'}\right) = \frac{\partial p^{eq}}{\partial p'} = \lambda \cdot \alpha \qquad Eq.\ [257]$$

Hence we define $\alpha = \partial p^{eq} / \partial p'$. Together with Eq. [253] and Eq. [255] this leads to:

$$\dot{\underline{\varepsilon}} = \mathbf{D}^{-1}\dot{\underline{\sigma}}' + \frac{\varepsilon_v^c}{a}\frac{\partial p^{eq}}{\partial \underline{\sigma}'} = \mathbf{D}^{-1}\dot{\underline{\sigma}}' + \frac{1}{a}\frac{\mu^*}{\tau}\left(\frac{p^{eq}}{p_p^{eq}}\right)^{\frac{\lambda^* - \kappa^*}{\mu^*}}\frac{\partial p^{eq}}{\partial \underline{\sigma}'} \qquad \textit{Eq. [258]}$$

where:

$$p_p^{eq} = p_{p0}^{eq}\exp\left(\frac{-\varepsilon_v^c}{\lambda^* - \kappa^*}\right) \qquad \textit{Eq. [259]}$$

or inversely:

$$-\varepsilon_v^c = (\lambda^* - \kappa^*)\ln\left(\frac{p_p^{eq}}{p_{p0}^{eq}}\right) \qquad \textit{Eq. [260]}$$

10.6 Formulation of elastic 3D-strains

Considering creep strains, it has been shown that the 1D-model can be extended to obtain the 3D-model, but as yet this has not been done for the elastic strains.

To get a proper 3D-model for the elastic strains as well, the elastic modulus E_{ur} has to been defined as a stress-dependent tangent stiffness according to:

$$E_{ur} = 3(1-2\nu_{ur})K_{ur} = -3(1-2\nu_{ur})\left(\frac{p' + c\cot(\varphi)}{k^*}\right) \qquad \textit{Eq. [261]}$$

Hence, E_{ur} is not a new input parameter, but simply a variable quantity that relates to the input parameter κ^*. On the other hand ν_{ur} is an additional true material constant.

Hence similar to E_{ur}, the bulk modulus K_{ur} is stress dependent according to the rule $K_{ur} = -(p' + c\cot\varphi)^* / \kappa^*$ where in this context c is again the effective cohesion rather than the creep parameter. Now it can be derived for the volumetric elastic strain that:

$$\dot{\varepsilon}_v^e = \frac{\dot{p}'}{K_{ur}} = -\kappa^*\frac{\dot{p}'}{p' + c\cot(\varphi)}$$

or by integration : *Eq. [262]*

$$-\varepsilon_v^e = \kappa^*\ln\left(\frac{p' + c\cot(\varphi)}{p_0' + c\cot(\varphi)}\right)$$

Hence in the 3D-model the elastic strain is controlled by the mean stress p', rather than by principal stress σ' as in the 1D-model. However mean stress can be converted into principal stress. For one-dimensional compression on the normal consolidation line, we have both $3p' = (1+2K^{nc}{}_0)\sigma'$ and $3p'_0 = (1+2K_0^{nc})\sigma'_0$ and it follows that $p'/p'_0 = \sigma'/\sigma'_0$. As a consequence, for $c = 0$, we derive the simple rule $-\varepsilon_v^c = \kappa^* \ln \sigma'/\sigma'_0$, whereas the 1D-model involves $-\varepsilon_v^c = a \ln \sigma'/\sigma'_0$. It would thus seem that κ^* coincides with a. Unfortunately this line of thinking cannot be extended toward overconsolidated states of stress and strain. For such situations, it can be derived that:

$$\frac{\dot{p}'}{p'} = \frac{1+\nu_{ur}}{1-\nu_{ur}}\frac{1}{1+2K_0}\frac{\dot{\sigma}'}{\sigma'} \qquad \textit{Eq. [263]}$$

and it follows that:

$$-\dot{\varepsilon}_v^e = \kappa^* \frac{\dot{p}'}{p'} = \frac{1+\nu_{ur}}{1-\nu_{ur}} \frac{\kappa^*}{1+2K_0} \frac{\dot{\sigma}'}{\sigma'} \qquad \textit{Eq. [264]}$$

where K_0 depends to a great extent on the degree of over-consolidation. For many situations, it is reasonable to assume $K_0 \approx$ and together with $\nu_{ur} \approx 0.2$ one obtains $-2\varepsilon_v^c \approx \kappa^* ln(\sigma'/\sigma'_0)$. Good agreement with the 1D-model is thus found by taking $\kappa^* \approx 2a$.

10.7 Formulation of failure condition

The creep formulation does not include failure. Therefore, a Mohr-Coulomb type failure criterion, formulated in a perfect-plasticity framework, is added to the Soft Soil Creep model, generating plastic strains as soon as the failure condition is met. As soon as the Mohr-Coulomb failure yield criterion $f(\sigma', c, \varphi) = 0$ is met, instantaneous plastic strain rates develop according to the flow rule $\dot{\varepsilon}^p = \lambda \partial g / \partial \sigma'$ with $g = g(\sigma', \psi)$. For details see Linear Elastic Perfectly Plastic Model (Mohr-Coulomb Model) (on page 32).

In each stress point, the stresses are calculated according to the creep formulation before considering the failure criterion. Subsequently, the new stress state is checked against the failure criterion and corrected, if applicable.

10.8 Parameters of the Soft Soil Creep model

In addition to the parameters of theSoft Soil Creep model, the Soft Soil Creep model involves a creep parameter in the form of the *Modified Creep index* μ^*. In total, the Soft Soil Creep model requires the following parameters to be determined:

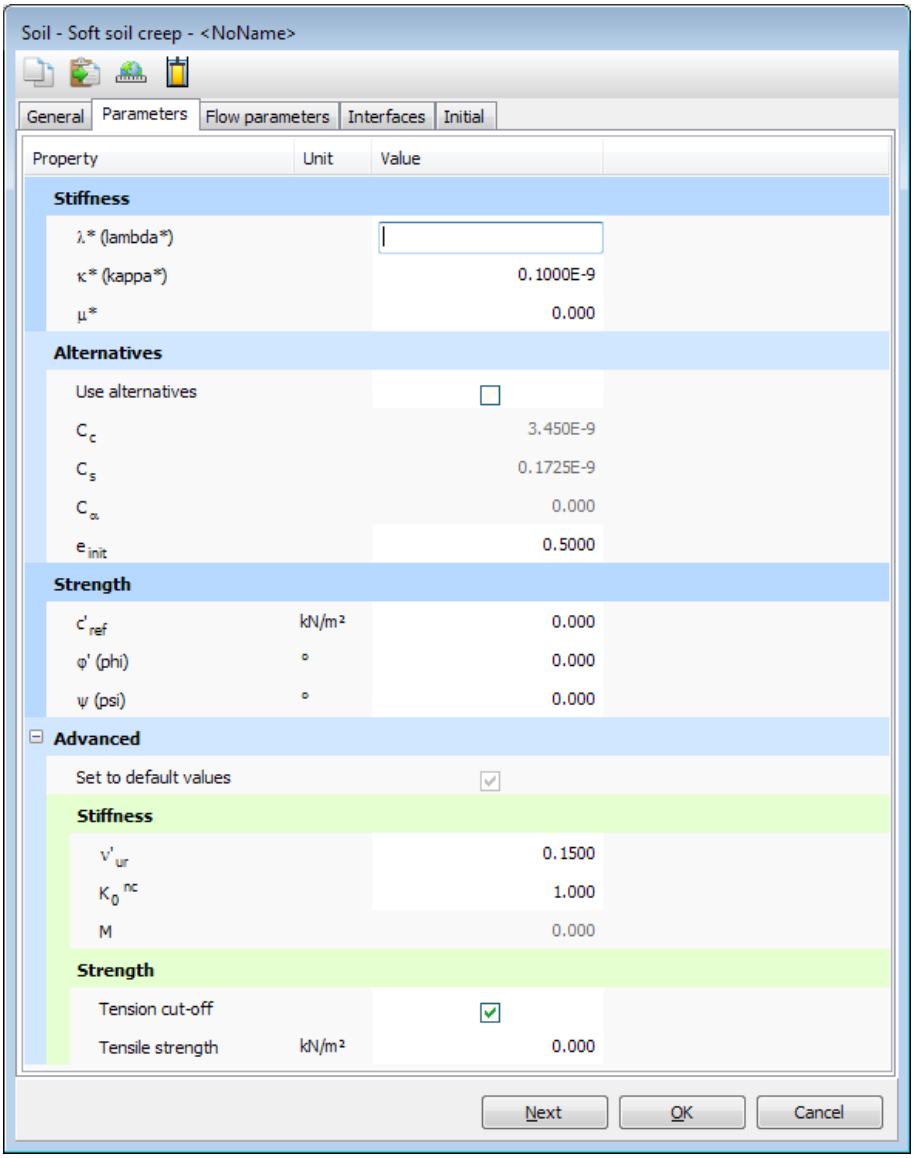


Figure 56: Parameters tabsheet for the Soft Soil Creep model

In conclusion, the Soft Soil Creep model requires the following material constants:

Failure parameters as in the Mohr-Coulomb model:

c'_{ref}	Effective cohesion	[kN/m^2]
φ'	Friction angle	[°]
ψ	Dilatancy angle	[°]

Basic stiffness parameters

κ^*	Modified swelling index	[-]

λ^*	Modified compression index	[-]
μ^*	Modified creep index	[-]

Advanced parameters (it is advised to use the default setting):

ν_{ur}	Poisson's ratio for unloading - reloading (default 0.15)	[-]
K_0^{nc}	$\sigma'_{xx} / \sigma'_{yy}$ stress ratio in a state of normal consolidation	[-]
M	K_0^{nc}-related parameter (see below)	[-]

Instead of defining the stiffness by the basic stiffness parameters, alternative stiffness parameters can be used. These material constants are given by:

C_c	Compression index	[-]
C_s	Swelling index	[-]
C_α	Creep index for secondary compression	[-]
e_{init}	Initial void ratio	[-]

10.8.1 *Modified swelling index, modified compression index and modified creep index*

These parameters can be obtained from an isotropic compression test including isotropic unloading. When plotting the logarithm of the mean stress as a function of the volumetric strain for clay-type materials, the plot can be approximated by two straight lines (see Figure 49 (on page 112)). The slope of the primary loading line gives the modified compression index, and the slope of the unloading (or swelling) line gives the modified swelling index. Note that there is a difference between the modified indices κ^* and λ^* and the original Cam-Clay parameters κ and λ. The latter parameters are defined in terms of the void ratio e instead of the volumetric strain ε_v. The parameter μ^* (Table 6 (on page 131)) can be obtained by measuring the volumetric strain on the long term and plotting it against the logarithm of time (see Figure 53 (on page 121)).

In Table 7 (on page 131), the value 2.3 is in fact ln10 and stems from the conversion from ^{10}log to natural logarithm. The alternative stiffness parameters can also be calculated from this table. Since the void ratio e is not a constant, in the conversion from the alternative parameters to the original model parameters in PLAXIS the void ratio e is defined as the initial void ratio e_{init}. Entering a particular value for one of the alternatives C_c, C_s or C_α results in a change of λ^*, κ^* or μ^* respectively.

As already indicated in Formulation of elastic 3D-strains (on page 127), there is no exact relation between the isotropic compression index κ^* and the one-dimensional swelling indices A and C_s, because the ratio of horizontal and vertical stress changes during one-dimensional unloading. For the approximation it is assumed that the average stress state during unloading is an isotropic stress state, i.e. the horizontal and vertical stresses are equal.

For a rough estimate of the model parameters, one might use the correlation $\lambda^* \approx I_p(\%)/500$, the fact that λ^* / μ^* is in the range between 15 to 25 and the general observation λ^*/κ^* is between 2.5 and 7.

Table 5: Relationship to Cam-Clay parameters

$\lambda^* = \frac{\lambda}{1+e}$	$\kappa^* = \frac{\kappa}{1+e}$	- - -

Table 6: Relationship to A,B,C parameters

$\lambda^* = b$	$\kappa^* \approx a$	$\mu^* = c$

Table 7: Relationship to internationally normalised parameters

$\lambda^* = \frac{C_c}{2.3(1+e)}$	$\kappa^* \approx \frac{2}{2.3}\frac{C_s}{(1+e)}$	$\mu^* \approx \frac{1}{2.3}\frac{C_\alpha}{(1+e)}$

For characterising a particular layer of soft soil, it is also necessary to know the initial pre-consolidation pressure σ_{p0}. This pressure may, for example, be computed from a given value of the overconsolidation ratio (OCR). Subsequently σ_{p0} can be used to compute the initial value of the generalised pre-consolidation pressure $p^{eq}{}_p$ (see The initial pre-consolidation stress in advanced models (on page 28)).

10.8.2 *Poisson's ratio*

In the case of the Soft Soil Creep model, Poisson's ratio is purely an elasticity constant rather than a pseudo-elasticity constant as used in the Mohr-Coulomb model. Its value will usually be in the range between 0.1 and 0.2. If the standard setting for the Soft Soil Creep model parameters is selected, then the value $\nu_{ur} = 0.15$ is automatically adopted. For loading of normally consolidated materials, Poisson's ratio plays a minor role, but it becomes important in unloading problems. For example, for unloading in a one-dimensional compression test (oedometer), the relatively small Poisson's ratio will result in a small decrease of the lateral stress compared with the decrease in vertical stress. As a result, the ratio of horizontal and vertical stress increases, which is a well-known phenomenon for overconsolidated materials. Hence, Poisson's ratio should not be based on the normally consolidated K_0^{nc}-value, but on the ratio of difference in horizontal stress to difference in vertical stress in oedometer unloading and reloading:

$$\frac{\nu_{ur}}{1-\nu_{ur}} = \frac{\Delta\sigma_{xx}}{\Delta\sigma_{yy}} \quad \text{(Unloading and reloading)} \qquad \textit{Eq. [265]}$$

10.8.3 K_0^{nc} - *parameter*

By default, *M* is automatically determined based on the coefficient of lateral earth pressure in normally consolidated condition, K_0^{nc}, as entered by the user. The exact relationship between *M* and K_0^{nc} can be formulated as Brinkgreve (1994) (on page 252):

$$M = \sqrt{\frac{\left(1-K_0^{nc}\right)^2}{\left(1+2K_0^{nc}\right)^2} + \frac{\left(1-K_0^{nc}\right)\left(1-2\nu_{ur}\right)\left(\lambda^*/\kappa^*-1\right)}{\left(1-2K_0^{nc}\right)\left(1-2\nu_{ur}\right)\lambda^*/\kappa^* - \left(1-K_0^{nc}\right)\left(1+\nu_{ur}\right)}} \qquad \textit{Eq. [266]}$$

Hence the user cannot enter directly a particular value of *M*. Instead he can choose values for K_0^{nc}. Note that the particular selection of *M* has an influence on lateral deformation of pseudo-vertical loading problems. For details, see Brinkgreve (2004) (on page 252).

$$M \approx 3.0 - 2.8K_0^{nc} \qquad Eq.\ [267]$$

10.9 State parameters in the Soft Soil Creep model

In addition to the output of standard stress and strain quantities, the Soft Soil Creep model model provides output (when being used) on state variables such as the isotropic pre-consolidation stress p_p. These parameters can be viewed by selecting the *State parameters* option from the *Stresses* menu. An overview of available state parameters is given below:

p_{eq}	Equivalent isotropic stress $p_{eq} = p' + q^2 / M^2\left(p' + c\cot(\varphi)\right)$	[-]
p_p	Isotropic pre-consolidation stress	[-]
OCR	Isotropic overconsolidation $OCR = p_p / p_{eq}$	[-]

10.10 On the use of the Soft Soil Creep model in dynamic calculations

When using the Soft Soil Creep model in dynamic calculations, the modified swelling index κ^* needs to be selected such that the model correctly predicts wave velocities in the soil. This generally requires a smaller value than just an unloading-reloading index.

When subjected to dynamic or cyclic loading, the Soft Soil Creep model will generate plastic strains when the preconsolidation stress is increased. However, it should be noted that stress cycles within the current creep contour will only generate elastic strains and no (hysteretic) damping, nor accumulation of strains or pore pressure, nor liquefaction. In order to account for the soil damping in cyclic loading, Rayleigh damping may be defined.

10.11 On the use of the Soft Soil Creep model in practical applications

In the Soft Soil Creep model, creep strains are generated as long as there is effective stress. In oedometer tests and other lab tests, self-weight stresses of the soil sample are negligible and the effective stress in the sample is dominated by external loading conditions. However, when it comes to practical applications, the effective stress

in the soil is generally dominated by the initial self- weight stresses. As a consequence, creep will occur without additional loading.

Following the formulation of the model, the rate at which creep strains occur highly depends on the overconsolidation ratio as well as the ratio of the (modified) compression index over the (modified) creep index. Regarding the latter, it should be considered that natural clays may involve structure (bonding) whilst the Soft Soil Creep model does not include such effects. This requires the effective stress range in the application to be taken into account when determining the compression and creep indices from one-dimensional compression tests. This may also have an effect on the pre-consolidation stress to be used in the application. Moreover, considering 'normally-consolidated' soft soil deposits in practice, it would seem logical to set the initial *OCR*-value equal to *1.0*. However, this would lead to unrealistic large creep strain rates due to the initial stresses, without even considering additional loading.

In order to avoid these unrealistic creep strain rates, it is recommended to set the initial *OCR*-value larger than *1.0*. A value in the order of *1.2*-*1.4* will generally work, but in some cases even higher values might be needed. Please keep in mind that this changes the pre-consolidation pressure, such that the material becomes lightly overconsolidated and the pre-consolidation stress may not correspond anymore to what is observed in compression tests.

The above may be validated from a practical viewpoint by considering that the layer has aged since its deposition in geological history. Moreover, in particular the top few metres of an existing soft soil layer have been subjected to various possible external influences (traffic, weather, temperature changes, changes in saturation, etc.). Accurate measurements of the pre-consolidation pressure on soil samples that are assumed to be 'normally-consolidated' would typically show a pre-consolidation pressure that is noticeably larger than the initial effective stress. However, lab tests are often performed on soil samples that have been disturbed to a certain extent, and therefore the measurement of the pre-consolidation stress in practice is often inaccurate.

In conclusion, the determination of model parameters for the Soft Soil Creep model requires a cautious interpretation of test data, in view of the envisioned practical application. It is recommended, before commencing any 2D or 3D analysis, to perform a careful calibration of model parameters. This can be done by performing simulations using the PLAXIS Soil Test facility in combination with an analysis of a one-dimensional soil column (based on the in-situ soil layering), in which a realistic time interval is considered.

11 Modified Cam-Clay model

The Modified Cam-Clay model is described in several textbooks on critical state soil mechanics (for example Muir Wood (1990) (on page 254)). In this chapter a short overview is given of the basic equations.

11.1 Formulation of the Modified Cam-Clay model

In the Modified Cam-Clay model, a logarithmic relation is assumed between void ratio e and the mean effective stress p' in virgin isotropic compression, which can be formulated as:

$$e - e^0 = -\lambda \ln\left(\frac{p'}{p^0}\right) \text{ (virgin isotropic compression)} \qquad \textit{Eq. [268]}$$

The parameter λ is the Cam-Clay isotropic compression index, which determines the compressibility of the material in primary loading. When plotting relation (Eq. [268]) in a e - $ln\ p'$ diagram one obtains a straight line. During unloading and reloading, a different line is followed, which can be formulated as:

$$e - e^0 = -\kappa \ln\left(\frac{p'}{p^0}\right) \text{ (isotropic unloading and reloading)} \qquad \textit{Eq. [269]}$$

The parameter κ is the Cam-Clay isotropic swelling index, which determines the compressibility of material in unloading and reloading. In fact, an infinite number of unloading and reloading lines exists in p' - e-plane each corresponding to a particular value of the pre-consolidation stress p_p.

The yield function of the Modified Cam-Clay model is defined as:

$$f = \frac{q^2}{M^2} + p'(p' - p_p) \qquad \textit{Eq. [270]}$$

The yield surface ($f = 0$) represents an ellipse in p' - q-plane as indicated in Figure 57 (on page 135). The yield surface is the boundary of the elastic stress states. Stress paths within this boundary only give elastic strain increments, whereas stress paths that tend to cross the boundary generally give both elastic and plastic strain increments.

In p'-q - plane, the top of the ellipse intersects a line that we can be written as:

$$q = M p' \qquad \textit{Eq. [271]}$$

This line is called the critical state line (*CSL*) and gives the relation between p' and q in a state of failure (i.e. the critical state). The constant M is the tangent of the critical state line and determines the extent to which the ultimate deviatoric stress, q, depends on the mean effective stress, p'. Hence, M can be regarded as a friction constant. Moreover, M determines the shape of the yield surface (height of the ellipse) and influences the

coefficient of lateral earth pressure K_0^{nc} in a normally consolidated stress state under conditions of one-dimensional compression.

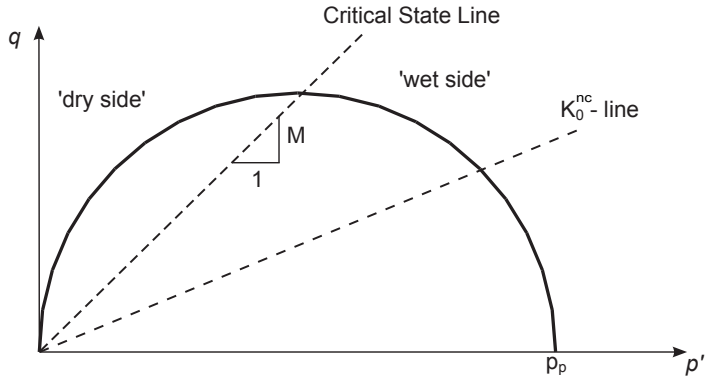


Figure 57: Yield surface of the of the Modified Cam-Clay model in p'-q - plane

The preconsolidation stress, p_p, determines the size of the ellipse. In fact, an infinite number of ellipses exist, each corresponding to a particular value of p_p.

The left hand side of the yield ellipse (often described as the 'dry side' of the critical state line) may be thought of as a failure surface. In this region plastic yielding is associated with softening, and therefore failure. The values of q can become unrealistically large in this region.

For more detailed information on Cam-Clay type models, the reader is referred to Muir Wood (1990) (on page 254).

Note:

Note that the Modified Cam-Clay model model as implemented in PLAXIS gives a Druger-Prager failure state instead of a Mohr-Coulomb model type of failure.

11.2 Parameters of the Modified Cam-Clay model

The Modified Cam-Clay model is based on the following parameters:

- Parameters for stiffness:

λ	Cam-Clay compression index	[-]
κ	Cam-Clay swelling index	[-]
ν_{ur}	Poisson's ratio	[-]
e_{init}	Initial void ratio for loading/unloading	[-]

- Parameters for strength:

M	Tangent of the critical state line	[-]
K_0^{nc}	Coefficient of lateral stress in normal consolidation derived from M. The relationship between M and K_0^{nc} is given in the Material Models Manual *Chapter 10- Parameters of the soft soil creep model.*	[-]

11.2.1 Compression index and swelling index

These parameters can be obtained from an isotropic compression test including isotropic unloading. When plotting the natural logarithm of the mean stress as a function of the void ratio for clay-type materials, the plot can be approximated by two straight lines. The slope of the primary loading line gives the compression index and the slope of the unloading line gives the swelling index. These parameters can be obtained from a one-dimensional compression test, as discussed in Parameters of the Soft Soil model (on page 114).

11.2.2 Poisson's Ratio

Poisson's ratio ν_{ur} is a real elastic parameter and not a pseudo-elasticity constant as used in the Mohr-Coulomb model. Its value will usually be in the range between 0.1 and 0.2.

11.2.3 Tangent of the critical state line

In order to obtain the correct shear strength, the parameter M should be based on the friction angle φ. The critical state line is comparable with the Drucker-Prager failure line, and represents a (circular) cone in principal stress space. Hence, the value of M can be obtained from φ:

$$M = \frac{6sin\varphi}{3 - sin\varphi} \quad \text{(for initial compression stress states)} \quad (\sigma_1' \leq \sigma_2' = \sigma_3') \qquad \textit{Eq. [272]}$$

$$M = \frac{6sin\varphi}{3 + sin\varphi} \quad \text{(for initial compression stress states)} \quad (\sigma_1' = \sigma_2' \leq \sigma_3') \qquad \textit{Eq. [273]}$$

$$M \approx \sqrt{3}sin\varphi \quad \text{(for plane strain stress states)} \qquad \textit{Eq. [274]}$$

In addition to determining the shear strength, the parameter M has an important influence on the value of the coefficient of lateral earth pressure, K_0^{nc}, in a state of normal consolidation. In general, when M is chosen such that the model predicts the correct shearing strength, the resulting value of K_0^{nc} is too high.

11.3 State parameters in the Modified Cam-Clay model

In addition to the output of standard stress and strain, the Modified Cam-Clay model provides output (when being used) on state variables such as the isotropic pre-consolidation stress p_p and the isotropic overconsolidation ration *OCR*. These parameters can be visualised by selecting the *State parameters* option from the *Stresses* menu. An overview of available state parameters is given below:

p_{eq}	Equivalent isotropic stress. $P_{eq} = p' + \frac{q^2}{M^2 p'}$	[kN/m^2]
p_p	Isotropic preconsolidation stress	[kN/m^2]
OCR	Isotropic overconsolidation ratio ($OCR = p^p/p^{eq}$)	[-]

11.4 On the use of the Modified Cam-Clay model in dynamic calculations

When using the Modified Cam-Clay model in dynamic calculations, the swelling index κ needs to be selected such that the model correctly predicts wave velocities in the soil. This generally requires a smaller value than just an unloading-reloading index.

When subjected to dynamic or cyclic loading, the Modified Cam-Clay model will generate plastic strains when the preconsolidation stress is increased. However, it should be noted that stress cycles within the current creep contour will only generate elastic strains and no (hysteretic) damping, nor accumulation of strains or pore pressure, nor liquefaction. In order to account for the soil damping in cyclic loading, Rayleigh damping may be defined.

11.5 Warning

The Modified Cam-Clay model may allow for extremely large shear stresses. This is particularly the case for stress paths that cross the critical state line. Furthermore, the Modified Cam-Clay model may give softening behaviour for particular stress paths. Without special regularization techniques, softening behaviour may lead to mesh dependency and convergence problems of iterative procedures. Moreover, the Modified Cam-Clay model cannot be used in combination with *Safety analysis* by means of phi-c reduction. The use of the Modified Cam-Clay model in practical applications is not recommended.

12 The Sekiguchi-Ohta model

The Sekiguchi-Ohta model has been developed to formulate a constitutive law for normally consolidated clay. Particular emphasis is placed on taking the effect of time and stress-induced anisotropy into consideration. A complete description of the model has been presented in Sekiguchi & Ohta (1977) (on page 255) and Iizuka & Ohta (1987) (on page 253).

12.1 Formulation of the Sekiguchi-Ohta model

The Sekiguchi-Ohta model combines the concepts lying behind the well known Cam Clay model (Roscoe, Schofield & Thurairajah (1963) (on page 254)) and the rheological model developed by Murayama & Shibata (1966) (on page 254). The Cam Clay model was further developed by Ohta & Hata (1973) (on page 254) counting for the stress induced anisotropy for anisotropically consolidated clays. However due to the fact that this model deals with the stress-strain behaviour of the soil in equilibrium, the time effect is not considered. The rheological model is further developed by Sekiguchi (1977) (on page 255) to describe the time-dependent and elastoplastic behaviour for normally consolidated clays.

12.1.1 Isotropic states of stress and strain ($\sigma'_1 = \sigma'_2 = \sigma'_3$)

In the Sekiguchi-Ohta model, it is assumed that there is a logarithmic relation between changes in volumetric strain, ε_v, and changes in mean effective stress, p', which can be formulated as:

$$\varepsilon_v - \varepsilon_v^0 = -\lambda^* ln\left(\frac{p'}{p^0}\right) \qquad \text{(virgin compression)} \qquad Eq.\ [275]$$

The parameter λ^* is the modified compression index, which determines the compressibility of the material in primary loading. Note that λ^* differs from the index λ as used by Burland (1965) (on page 252). The difference is that Eq. [275] is a function of volumetric strain instead of void ratio. Plotting Eq. [275] gives a straight line as shown in Figure 58 (on page 139).

During isotropic unloading and reloading a different path (line) is followed, which can be formulated as:

$$\varepsilon_v^e - \varepsilon_v^{e0} = -\kappa^* ln\left(\frac{p'}{p^0}\right) \qquad \text{(unloading and reloading)} \qquad Eq.\ [276]$$

The parameter κ^* is the modified swelling index, which determines the compressibility of the material in unloading and subsequent reloading. Note that κ^* differs from the index κ as used in the Cam-Clay models. The

ratio λ^*/κ^* is, however, equal to the ratio λ/κ. The soil response during unloading and reloading is assumed to be elastic as denoted by the superscript *e* in Eq. [276]. The elastic behaviour is described by Hooke's law. Eq. [276] implies linear stress dependency on the tangent bulk modulus such that:

$$K_{ur} \equiv \frac{E_{ur}}{3(1 - 2\nu_{ur})} = \frac{p'}{\kappa^*} \qquad \textit{Eq. [277]}$$

in which the subscript *ur* denotes unloading/reloading. Neither the elastic bulk modulus, K_{ur}, nor the elastic Young's modulus, E_{ur}, is used as an input parameter. Instead, ν_{ur} and κ^* are used as input constants for the part of the model that computes the elastic strains.

An infinite number of unloading/reloading lines may exist in Figure 58 (on page 139), each corresponding to a particular value of the isotropic pre-consolidation stress p_p. The pre-consolidation stress represents the largest stress level experienced by the soil. During unloading and reloading, this pre-consolidation stress remains constant. In primary loading, however, the pre-consolidation stress increases with the stress level, causing irreversible (plastic) volumetric strains.

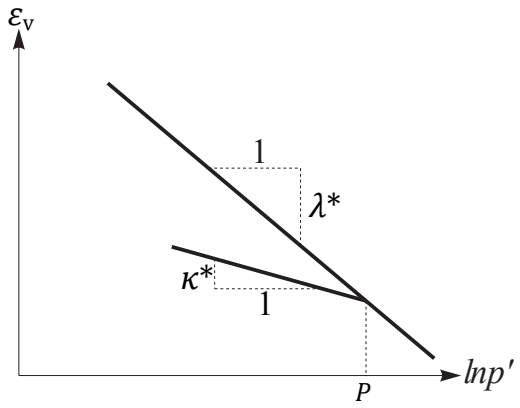


Figure 58: Logarithmic relation between volumetric strain and mean stress

12.1.2 Inviscid (time-independent) formulation

The yield function of the inviscid model in triaxial space is expressed by the following equation:

$$f = MD \ln\left(\frac{p'}{p_p}\right) + D\frac{\bar{q}}{p'} \qquad \textit{Eq. [278]}$$

where

M	=	Critical state frictional parameter.
D	=	Coefficient of dilatancy.
p'	=	Mean effective stress.
p_p	=	Isotropic hardening stress parameter.
$\bar{q}$	=	Relative deviatoric stress

The isotropic hardening stress parameter of the model is defined as:

$$p_p = p_{p0} e^{\frac{\left(\varepsilon_v^p - \varepsilon_{v0}^p\right)}{MD}} \qquad \textit{Eq. [279]}$$

where

MD = $\lambda^* - \kappa^*$
ε^p_{v0} = Initial plastic volumetric strain

Hence, the parameter D is an auxiliary parameter implicitly defined as $D = (\lambda^*-\kappa^*)/M$.

12.1.3 Viscid (time-dependent) formulation

The flow function of the visco-plastic (viscid) model is written as:

$$F = \alpha^* \ln\left(1 + \frac{\dot{v}_0 t}{\alpha^*} \exp\left(\frac{f(\sigma)}{\alpha^*}\right)\right) - \varepsilon_v^{vp} = 0 \qquad \textit{Eq. [280]}$$

where

$$f(\sigma) = MD \ln \frac{p'}{p'_0} + D\frac{\dot{q}}{p'} \qquad \textit{Eq. [281]}$$

The flow function F can be transformed to a function of stress and hardening parameter g as follows:

$$g(\sigma', h) = f(\sigma') - h\left(\varepsilon_v^{vp}, t\right) = 0 \qquad \textit{Eq. [282]}$$

where the hardening parameter h is defined as:

$$h\left(\varepsilon_v^{vp}, t\right) = \alpha^* \ln\left\{\frac{\alpha^*}{\dot{v}_0 t}\left[\exp\left(\frac{\varepsilon_v^{vp}}{\alpha^*}\right) - 1\right]\right\} \qquad \textit{Eq. [283]}$$

The initial time to calculate the hardening parameter h should not be zero, because it is not determined due to $1/t$ in Eq. [283]. To be able to calculate the initial volumetric visco-plastic strain, it is assumed that the hardening parameter h is equal to zero. Hence, the initial visco-plastic volumetric strain can be calculated as follows:

$$h\left(\varepsilon_v^{vp}, t\right) = \alpha^* \ln\left\{\frac{\alpha^*}{\dot{v}_0 t}\left[\exp\left(\frac{\varepsilon_v^{vp}}{\alpha^*}\right) - 1\right]\right\} = 0 \qquad \textit{Eq. [284]}$$

$$\varepsilon_{v0}^{vp} = \alpha^* \ln\left\{\frac{\dot{v}_0 t}{\alpha^*} + 1\right\} = 0 \qquad \textit{Eq. [285]}$$

ε_{v0}^{vp} is used as the initial visco-plastic volumetric strain to calculate the current visco-plastic volumetric strain.

12.2 Parameters of the Sekiguchi-Ohta model

12.2.1 Model parameters of the inviscid model

- *Basic parameters for soil stiffness*:

λ^*	Modified compression index	[-]
κ^*	Modified swelling index	[-]

- *Alternative parameters can be used to define soil stiffness*:

C_C	Compression index	[-]
C_s	Swelling index or reloading index	[-]
e_{init}	Initial void ratio	[-]

- *Advanced parameters for soil stiffness*:

ν_{ur}	Poisson's ratio for unloading-reloading	[-]
K_0^{nc}	Coefficient of lateral stress in normal consolidation	[-]

- *Parameters for soil strength*:

M	Tangent of the critical state line	[-]

Modified compression index and modified swelling index (λ^* and κ^*)

These parameters can be obtained from an isotropic compression test including isotropic unloading. When plotting the logarithm of the mean effective stress as a function of the volumetric strain for clay type materials, the plot can be approximated by two straight lines, see Figure 59 (on page 141). The slope of the primary loading line gives the modified compression index λ^*, and the slope of the unloading (or swelling) line gives the modified swelling index κ^*.

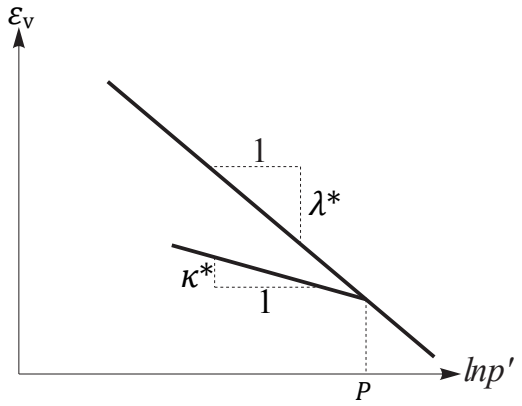


Figure 59: Logarithmic relation between volumetric strain and mean stress

Poisson's ratio (ν_{ur})

The poisson's ratio ν_{ur} is a real elastic parameter and not a pseudo-elasticity constant as used in the Mohr-Coulomb model. Its value will usually be in the range between 0.1 and 0.2.

Earth pressure coefficient at rest (K_0^{nc})

The K_0^{nc} parameter is defined as the stress ratio in one-dimensional compression in a state of normal consolidation:

$$K_0^{nc} = \frac{\sigma'_{xx}}{\sigma'_{yy}}$$

The K_0^{nc} -parameter determines the singular point in the Sekiguchi-Ohta model yield contour. Hence, K_0^{nc} relates to the inclination of the stress path in one-dimensional compression where α, as described in the Eq. [286] is the slope of the K_0^{nc} line in the p - q plane.

$$\alpha = \frac{3\left(1 - K_0^{nc}\right)}{1 + 2K_0^{nc}} \qquad \textit{Eq. [286]}$$

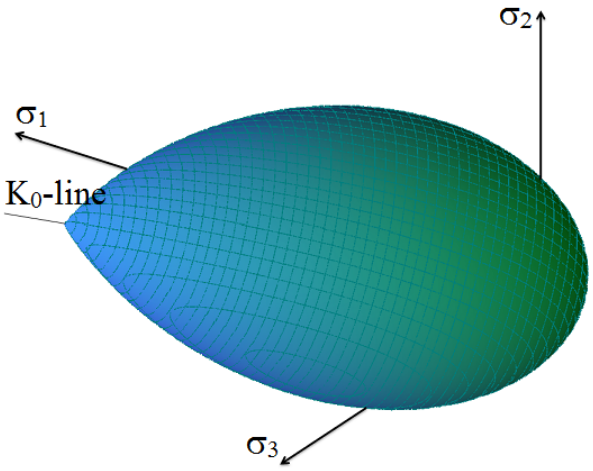


Figure 60: The Sekiguchi-Ohta model yield surface in triaxial stress space

Slope of the critical state line (M)

In order to obtain the correct shear strength, the parameter M should be based on the friction angle φ. The critical state line is comparable with the Drucker-Prager failure criteria, and represents a (circular) cone in the principal stress space. Hence, the value of M can be obtained from φ in a similar way as the Drucker-Prager friction constant α is obtained from φ. For details see also the Modified Cam-Clay model (on page 134).

Initial overconsolidation ratio (OCR_0)

The initial overconsolidation ratio OCR_0 is defined as the highest vertical effective stress experienced in the past, σ'_p, divided by the current stress σ'_{yy}. A soil which is currently experiencing its highest stress is said to be normally consolidated and to have an OCR of 1.

Initial pre-overburden pressure (POP_0)

The initial pre-overburden pressure POP_0, expressed in the unit of stress, is defined as:

$$POP_0 = \sigma'_p - \sigma'_{yy}$$

where

σ'_p = vertical pre-consolidation stress (the greatest vertical stress reached previously)

σ'_{yy} = In-situ effective vertical stress.

12.2.2 Model parameters of the viscid model

Compared to the inviscid Sekiguchi-Ohta model, the viscid Sekiguchi-Ohta model requires the coefficient of secondary compression α^* and the initial volumetric strain rate $\dot{v}_0$ as two additional parameters of input. All other parameters remain the same as in the inviscid Sekiguchi-Ohta model.

- *Basic parameters for soil stiffness*:

λ^*	Modified compression index	[-]
κ^*	Modified swelling index	[-]
α^*	Coefficient of secondary compression	[-]
$\dot{v}_0$	Initial volumetric strain rate	[day^{-1}]

- *Alternative parameters can be used to define soil stiffness*:

C_C	Compression index	[-]
C_s	Swelling index or reloading index	[-]
C_{α^*}	Secondary compression index	[-]
e_{init}	Initial void ratio	[-]

- *Parameters for soil strength*:

M	Tangent of the critical state line	[-]

- *Advanced parameters for soil stiffness*:

ν_{ur}	Poisson's ratio for unloading-reloading	[-]
K_0^{nc}	Coefficient of lateral stress in normal consolidation	[-]

Coefficient of secondary compression (α^*)

The coefficient of secondary compression α^* is defined as:

$$\alpha^* = \frac{d\varepsilon_v}{d(\ln t)} \qquad \textit{Eq. [287]}$$

at time t_c (the end of primary consolidation).

Initial volumetric strain rate ($\dot{v}_0$)

The initial volumetric strain rate $\dot{v}_0$ at reference state is expressed as:

$$\dot{v}_0 = \frac{\alpha^*}{t_c} \qquad \textit{Eq. [288]}$$

12.3 State parameters in the Sekiguchi-Ohta model

In addition to the output of standard stress and strain, the Sekiguchi-Ohta model provides output (when being used) on state variables such as the isotropic pre-consolidation stress p_p and the isotropic overconsolidation ration *OCR*. These parameters can be visualised by selecting from the *Stresses* menu in the *State parameters* option. An overview of available state parameters is given below:

p_{eq}	Equivalent isotropic stress $P_{eq} = \frac{p'}{\exp\left(-\frac{\tilde{q}}{Mp'}\right)}$	[kN/m^2]
p_p	Isotropic preconsolidation stress	[kN/m^2]
OCR	Isotropic over-consolidation ratio ($OCR = p^p/p^{eq}$)	[-]

13 The NGI-ADP model (anisotropic undrained shear strength)

The NGI-ADP model may be used for capacity, deformation and soil-structure interaction analyses involving undrained loading of clay. The basis of the material model is:

- Input parameters for (undrained) shear strength for three different stress paths/ states (Active, Direct Simple Shear, Passive).
- A yield criterion based on a translated approximated Tresca criterion.
- Elliptical interpolation functions for plastic failure strains and for shear strengths in arbitrary stress paths.
- Isotropic elasticity, given by the unloading/reloading shear modulus, G_{ur}.

13.1 Formulation of the NGI-ADP model

The NGI-ADP model is formulated for a general stress state, matching both undrained failure shear strengths and strains to that of selected design profiles (Andresen & Jostad, 1999 (on page 251) ; Andresen, 2002 (on page 251); Grimstad, Andresen & Jostad, 2010 (on page 253)). The model formulation is presented in steps, starting with 1D anisotropy in triaxial test condition. In The NGI-ADP model in plane strain (on page 146)a simplified expression for plane strain is presented. Thereafter the formulation is extended to full 3D stress state. In this formulation compressive stresses are positive.

In the NGI-ADP model the Tresca approximation after Billington (1988) (on page 252) together with a modified von Mises plastic potential function (von Mises, 1913 (on page 255)) is used to circumvent the possible corner problems. The yield and plastic potential function are independent of the mean stress hence zero plastic volume strain develops.

13.1.1 1D model presentation

Under triaxial tests condition two undrained shear strengths can be determined, i.e. $s_u{}^C$ and $s_u{}^E$. The test measures the response in vertical stress σ'_v and horizontal stress σ'_h for applied shear strain γ. The Tresca yield criteria can be modified, Eq. [289], to account for the difference in undrained shear strength in compression and extension:

$$f = \left| \tau - (1 - \kappa)\tau_0 - \kappa \frac{s_u^C - s_u^E}{2} \right| - \kappa \frac{s_u^C + s_u^E}{2} = 0 \qquad \textit{Eq. [289]}$$

where

$\boldsymbol{\tau}$	=	Shear stress defined as $\tau = 0.5(\sigma'_v - \sigma'_h)$
τ_0	=	Initial in situ maximum shear stress. Defined as $\tau_0 = 0.5(\sigma'_{v0}-\sigma'_{h0}) = 0.5\sigma'_{v0}(1-K_0)$

To account for difference in failure shear strain a stress path dependent hardening parameter is introduced. The stress path dependent hardening is made possible by different plastic failure shear strain γ_f^p in compression and extension. The hardening function is given by:

$$\kappa = 2\frac{\sqrt{\gamma^p / \gamma_f^p}}{1 + \gamma^p / \gamma_f^p}; \quad \text{when} \quad \gamma^p < \gamma_f^p; \ \textit{else} \ \kappa = 1 \qquad \textit{Eq. [290]}$$

where

γ^p	=	Plastic shear strain.
γ_f^p	=	The failure (peak) plastic shear strain.

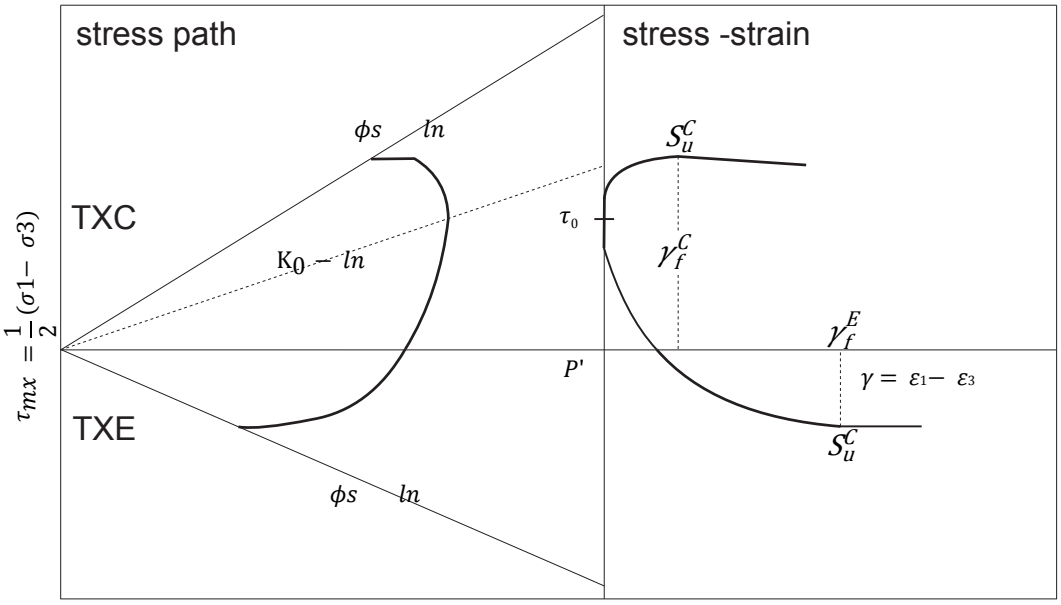


Figure 61: Typical stress paths and stress strain curves for triaxial compression and triaxial extension

13.1.2 The NGI-ADP model in plane strain

The yield criterion for the NGI-ADP model in plane strain is defined by:

$$f = \sqrt{\left(\frac{\sigma_{yy} - \sigma_{xx}}{2} - (1 - \kappa)\tau_0 - \kappa\frac{s_u^A - s_u^P}{2}\right)^2 + \left(\tau_{xy}\frac{s_u^A + s_u^P}{2s_u^{DSS}}\right)^2} - \kappa\frac{s_u^A + s_u^P}{2} = 0 \qquad \textit{Eq. [291]}$$

Restriction to clays with horizontal surfaces are made to simplify the presentation. Further *y* is taken as the vertical (depositional) direction. For isotropy in hardening (i.e. κ independent of stress orientation) Eq. [291]

plots as an elliptical shaped curve in a plane strain deviatoric stress plot. When κ equals 1.0, the criterion in Eq. [291] reduces to the formulation given by Davis & Christian (1971) (on page 252). While hardening the yield curves are characterised by slightly distorted elliptical shapes. The shape is dependent on the interpolation function used and values of failure strain. The NGI-ADP model uses elliptical interpolation between failure strain in passive stress state, direct simple shear and active stress state. In the implementation of the NGI-ADP model the yield surface is ensured to remain convex by restricting the input.

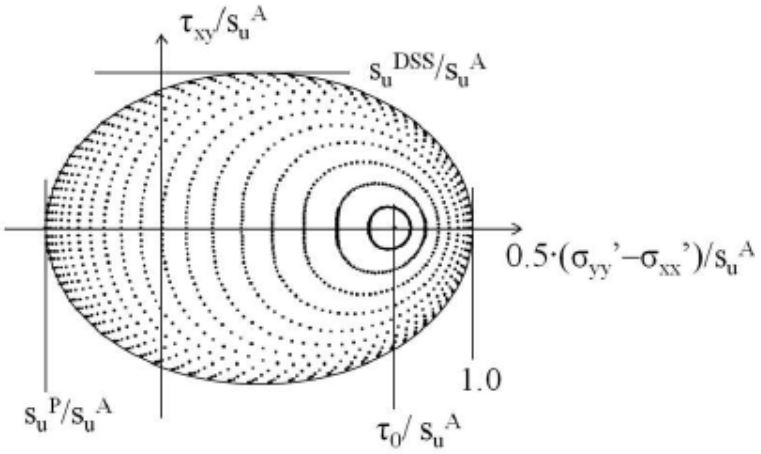


Figure 62: Typical deviatoric plane strain plot of equal shear strain contours for the NGI-ADP model

13.1.3 The NGI-ADP model in 3D stress space

This section describes the actual implementation of the NGI-ADP model in PLAXIS, whereas the previous sections should be regarded as an introduction using simplified formulation. For the general stress condition a modified deviatoric stress vector is defined as:

$$\begin{bmatrix} \hat{s}_{xx} \\ \hat{s}_{yy} \\ \hat{s}_{zz} \\ \hat{s}_{xy} \\ \hat{s}_{xz} \\ \hat{s}_{yz} \end{bmatrix} = \begin{bmatrix} \sigma'_{xx} - \sigma'_{xx0}(1-\kappa) + \kappa\frac{1}{3}\left(s_u^A - s_u^P\right) - \hat{p} \\ \sigma'_{yy} - \sigma'_{yy0}(1-\kappa) - \kappa\frac{2}{3}\left(s_u^A - s_u^P\right) - \hat{p} \\ \sigma'_{zz} - \sigma'_{zz0}(1-\kappa) + \kappa\frac{1}{3}\left(s_u^A - s_u^P\right) - \hat{p} \\ \tau_{xy}\dfrac{s_u^A + \dfrac{s_u^P}{2s_u^{DSS}}}{} \\ \tau_{xz} \\ \tau_{yz}\dfrac{s_u^A + s_u^P}{2s_u^{DSS}} \end{bmatrix} \qquad \textit{Eq. [292]}$$

where

σ'_{xx0}, σ'_{yy0} and σ'_{xx0} = Initial stresses.

$\hat{p}$ = the modified mean stress. The modified mean stress is defined as:

$$\hat{p} = \frac{\left(\sigma'_{xx} - \sigma'_{xx0}(1-\kappa)\right) + \left(\sigma'_{yy} - \sigma'_{yy0}(1-\kappa)\right) + \left(\sigma'_{zz} - \sigma'_{zzx0}(1-\kappa)\right)}{3} = p' - (1-\kappa)p'_0 \qquad \textit{Eq. [293]}$$

where

p' = Mean stress

Modified second and third deviatoric invariants are defined accordingly in Eq. [294] and Eq. [295].

$$\hat{J}_2 = -\hat{s}_{xx}\hat{s}_{yy} - \hat{s}_{xx}\hat{s}_{zz} - \hat{s}_{yy}\hat{s}_{zz} + \hat{s}_{xz}^2 + \hat{s}_{xz}^2 + \hat{s}_{yz}^2 \qquad \textit{Eq. [294]}$$

$$\hat{J}_3 = \hat{s}_{xx}\hat{s}_{yy}\hat{s}_{zz} + 2\hat{s}_{xy}\hat{s}_{yz}\hat{s}_{xz} - \hat{s}_{xx}\hat{s}_{yz}^2 - \hat{s}_{yy}\hat{s}_{xz}^2 - \hat{s}_{zz}\hat{s}_{xy}^2 \qquad \textit{Eq. [295]}$$

The yield criterion is expressed as:

$$f = \sqrt{H(\omega)\hat{J}_2} - \kappa\frac{s_u^A + s_u^P}{2} = 0 \qquad \textit{Eq. [296]}$$

where, to approximate the Tresca criterion, the term $H(\omega)$ is defined as:

$$H(\omega) = \cos^2\left(\frac{1}{6}\arccos\left(1 - 2a_1\omega\right)\right) \quad \text{with} \quad \omega = \frac{27}{4}\frac{\hat{J}_3^2}{\hat{J}_2^3} \qquad \textit{Eq. [297]}$$

By letting the value of a_1 go to *1.0* an exact Tresca criterion is obtained. The parameter a_1 can be directly linked to the rounding ratio s_u^C/s_u^A. This ratio takes typically a value just below 1.0 and a value of 0.99 is chosen as an appropriate default. Figure 63 (on page 148) shows the failure criterion of the NGI-ADP model in the ϖ-plane (for Cartesian stresses) with default rounding ratio. This criterion is continuous and differentiable and it is described by a single function.

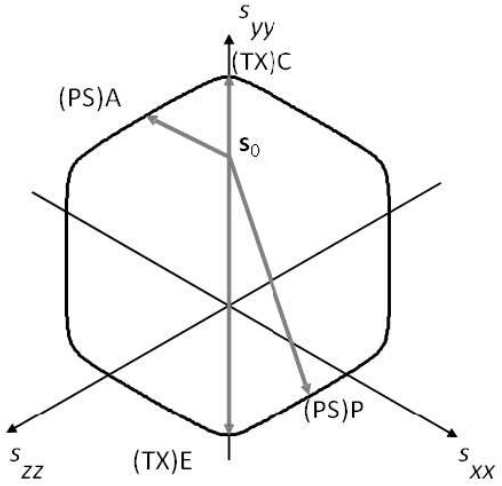


Figure 63: Failure criterion of the NGI-ADP model in the ϖ-plane

The combinations of strength ratios are limited by lower limit for combinations of s_u^C/s_u^A and s_u^P/s_u^A.

The value of γ_f^p is given by elliptical interpolation:

$$\gamma_f^p(\hat{\theta}) = \frac{\hat{R}_B\hat{R}_D\sqrt{\left(\hat{R}_D^2 - \hat{R}_C^2\right)\cos^2\hat{\theta} + \hat{R}_C^2} - \hat{R}_D^2\hat{R}_A\cos\left(2\hat{\theta}\right)}{\hat{R}_B^2 - \left(\hat{R}_B^2 - \hat{R}_D^2\right)\cos^2\left(2\hat{\theta}\right)} \qquad \textit{Eq. [298]}$$

where

$$\hat{R}_A = \frac{\gamma^p_{f,E} - \gamma^p_{f,C}}{2} \qquad \textit{Eq. [299]}$$

$$\hat{R}_B = \frac{\gamma^p_{f,E} + \gamma^p_{f,C}}{2} \qquad \textit{Eq. [300]}$$

$$\hat{R}_C = \sqrt{\gamma^p_{f,E}\gamma^p_{f,C}} \qquad \textit{Eq. [301]}$$

$$\hat{R}_D = \frac{\gamma^p_{f,DSS}\hat{R}_B}{\hat{R}_C} \qquad \textit{Eq. [302]}$$

and $\gamma_{f,C}^p$, $\gamma_{f,DSS}^p$ and $\gamma_{f,E}^p$ are the failure plastic maximum shear strain in triaxial compression, direct simple shear and triaxial extension respectively. Note that $\hat{\theta}$ is not the Lode angle, but is defined as:

$$cos\left(2\hat{\theta}\right) = \frac{\sqrt{3}}{2}\frac{\hat{s}_{yy}}{\sqrt{\hat{J}_2}} \qquad \textit{Eq. [303]}$$

A non-associated flow rule is used such that the derivative of the plastic potential g is:

$$\frac{\partial g}{\partial \sigma'} = \frac{1}{2}\left(\hat{I} + \frac{\partial p}{\partial \sigma'}\left(\frac{\partial \hat{s}}{\partial p}\right)^T\right)\frac{\partial \hat{J}_2}{\partial \hat{s}}\sqrt{\frac{1}{\hat{J}_2}} \qquad \textit{Eq. [304]}$$

where $\hat{i}$ is a modified unit vector:

$$\hat{I} = \begin{bmatrix} 1 & & & & & \\ & 1 & & & & \\ & & 1 & & & \\ & & & \frac{s_u^A + s_u^P}{2s_u^{DSS}} & & \\ & & & & 1 & \\ & & & & & \frac{s_u^A + s_u^P}{2s_u^{DSS}} \end{bmatrix} \qquad \textit{Eq. [305]}$$

The increment in plastic shear strain is defined as:

$$\partial\gamma^p = \sqrt{H(\omega)}\left(\frac{2}{3}\left(\left(d\varepsilon^p_{xx} - d\varepsilon^p_{yy}\right)^2 + \left(d\varepsilon^p_{xx} - d\varepsilon^p_{zz}\right)^2 + \left(d\varepsilon^p_{yy} - d\varepsilon^p_{zz}\right)^2\right) + \left(d\gamma^p_{xy}\right)^2 + \left(d\gamma^p_{xz}\right)^2 + \left(d\gamma^p_{yz}\right)^2\right)^{1/2}$$

Eq. [306]

where the plastic strains are defined as:

$$d\varepsilon^p = d\lambda\frac{\partial g}{\partial \sigma'} \qquad \textit{Eq. [307]}$$

with $d\lambda$ being the plastic multiplier. Hence, Eq. [306] gives the relation between the hardening parameter γ^p and the plastic multiplier $d\lambda$.

13.1.4 The NGI-ADP model traction criterion for interfaces in 2D

For plane strain conditions a traction criterion, corresponding to the plane strain failure criterion is formulated. This criterion is intended to be used on interface elements in finite element calculations. The interface strength is controlled by a lower and upper limit, which are dependent on the direction of the interface, β.

Let a plane being oriented by the direction β to the horizontal. The plane has a tangential direction t and a normal direction n and the adjacent continuum defines the stresses σ_{nn}, σ_{tt} and τ_n by:

$$\begin{bmatrix} \sigma_{tt} \\ \sigma_{nn} \\ \tau_{nn} \end{bmatrix} = A \begin{bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \tau_{xy} \end{bmatrix} \qquad \textit{Eq. [308]}$$

where

A = Transformation matrix.

In a local coordinate system three strains ε_{nn}, ε_{tt} and γ_{tn} are defined in the plane strain condition. Due to the requirement of no volume change for a perfect plastic mechanism with shearing in tangential direction, will give that $\varepsilon_{nn} = \varepsilon_{tt} = 0$, resulting in:

$$\frac{\partial f}{\partial (\sigma_{nn} - \sigma_{tt})} = 0 \qquad \textit{Eq. [309]}$$

The plane strain formulation for the NGI-ADP model is defined as follows:

$$f = \sqrt{\left(\frac{\sigma_{nn} - \sigma_{tt}}{2} cos(2\beta) - \tau_{tn} sin(2\beta) - R_A\right)^2 + \left(\frac{R_B}{R_D}\left(\frac{\sigma_{nn} - \sigma_{tt}}{2} sin(2\beta) + \tau_{tn} cos(2\beta)\right)\right)^2} - R_B$$

Eq. [310]

where

$$R_A = \frac{s_u^A - s_u^P}{2} \qquad \textit{Eq. [311]}$$

$$R_B = \frac{s_u^A - s_u^P}{2} \qquad \textit{Eq. [312]}$$

$$R_D = s_u^{DSS} \qquad \textit{Eq. [313]}$$

Note:

In PLAXIS 3D the NGI-ADP tension failure criterion for interfaces is simplified with the general undrained condition approach (Reference Manual - Chapter 6 - *Modelling soil and interface behaviour*), where $s_{u,soil}$ is equal to s_u^{DSS}.

13.2 Parameters of the NGI-ADP model

The NGI-ADP model requires a total of eleven parameters.

- *Parameters for stiffness:*

G_{ur} / s_u^A	Ratio unloading/reloading shear modulus over (plane strain) active shear strength	[-]
γ_f^C	Shear strain in triaxial compression ($\lvert\gamma_f^C = 3/2\ \varepsilon_1^C\rvert$)	[%]
γ_f^E	Shear strain in triaxial extension	[%]
γ_f^{DSS}	Shear strain in direct simple shear	[%]

- *Parameters for strength:*

$s_u^{A,ref}$	Reference (plane strain) active shear strength	[kN/m^2]
$s_u^{C,TX}/s_u^A$	Ratio triaxial compressive shear strength over (plane strain) active shear strength (default = 0.99)	[-]
	Reference level	[m]
$s_{u,inc}^A$	Increase of shear strength with depth	[kN/m^2/m]
s_u^P/s_u^A	Ratio of (plane strain) passive shear strength over (plane strain) active shear strength	[-]
τ_0/s_u^A	Initial mobilization (default = 0.7)	[-]
s_u^{DSS}/s_u^A	Ratio of direct simple shear strength over (plane strain) active shear strength	[-]

- *Advanced parameters:*

ν'	Effective Poisson's ratio	[-]
ν_u	Undrained Poisson's ratio	[-]

13.2.1 Ratio unloading / reloading shear modulus over plane strain active shear strength (G_{ur} / S_u^A)

Ratio unloading / reloading shear stiffness as a ratio of the plane strain active shear strength. If the shear strength is increasing with depth the constant ratio for G_{ur}/s_u^A gives a shear stiffness increasing linearly with depth.

13.2.2 Shear strain at failure in triaxial compression (γ_f^C)

This parameter γ_f^C (%) defines the shear strain at which failure is obtained in undrained triaxial compression mode of loading, i.e. $\gamma_f^C = 3/2\ \varepsilon_1^C$ from triaxial testing.

13.2.3 Shear strain at failure in triaxial extension (γ_f^E)

This parameter γ_f^E (%) defines the shear strain at which failure is obtained in undrained triaxial extension mode of loading, i.e. $\gamma_f^E = 3/2\varepsilon_1^E$ from triaxial testing.

13.2.4 Shear strain at failure in direct simple shear (γ_f^{DSS})

This parameter γ_f^{DSS} (%) defines the shear strain at which failure is obtained in undrained direct simple shear mode of loading (DSS device).

For near normally consolidated clays, the failure strain in compression loading γ_f^C is generally the lowest value and the failure strain in extension loading γ_f^E is the highest value. The failure strain from direct simple shear loading takes an intermediate value, i.e. $\gamma_f^C < \gamma_f^{DSS} < \gamma_f^E$. From laboratory test results reported in literature one find typically γ_f^E in the range 3-8 %, γ_f^{DSS} in the range 2-8 % and γ_f^C in the range 0.5 - 4 %.

If stress-strain curves from undrained triaxial and/or DSS laboratory tests are available it is recommended to choose the elastic shear modulus and failure strains such that a good fit to the curves are obtained. This is in particular important for deformation and SLS assessments. However, for pure capacity and stability (e.g. factor of safety) analyses the values for shear strains at failure is not important and one may set all three values equal to e.g. 5 % for simplicity.

Note that it is the failure strains from triaxial loading that is input because they are the most readily available. When the NGI-ADP model is used for plane strain conditions the failure strains will automatically be slightly adjusted for that loading condition. See Grimstad, Andresen & Jostad (2010) (on page 253) for more details.

13.2.5 Reference active shear strength ($s_{u,ref}^A$)

The reference active shear strength is the shear strength obtained in (plane strain) undrained active stress paths for the reference depth y_{ref}, expressed in the unit of stress.

13.2.6 Ratio triaxial compressive shear strength over active shear strength ($s_u^{C,TX} / s_u^A$)

This ratio $s_u^{C,TX} / s_u^A$ defines the shear strength in undrained triaxial compression mode of loading in relation to the shear strength in plane strain undrained active mode of loading. The value cannot be changed by the user and is predefined at 0.99 giving practically the same strengths in triaxial and plane strain conditions.

13.2.7 Reference depth (y_{ref})

This is the reference depth y_{ref} at which the reference active shear strength $s_{u,ref}^A$ is defined. Below this depth the shear strength and stiffness may increase linearly with increasing depth. Above the reference depth the shear strength is equal to $s_{u,ref}^A$.

13.2.8 Increase of shear strength with depth ($s_{u,inc}^A$)

This parameter $s_{u,ref}^A$ defines the increase (positive) or decrease (negative) of the undrained active shear strength with depth, expressed in the unit of stress per unit of depth. Above the reference depth the shear strength is equal to $s_{u,ref}^A$, below the reference depth the shear strength is defined as:

$$s_u^A(y) = s_{u,ref}^A + (y_{ref} - y)s_{u,inc}^A \qquad Eq.\ [314]$$

13.2.9 Ratio of passive shear strength over active shear strength (s_u^p / s_u^A)

This ratio s_u^p / s_u^A defines the undrained shear strength for (plane strain) passive mode of loading.

13.2.10 Ratio of direct simple shear strength over active shear strength (s_u^{DSS} / s_u^A)

This ratio s_u^{DSS} / s_u^A defines the undrained shear strength for direct simple shear mode of loading. Please note that active / passive strength input is defined for plane strain conditions. However, it is generally acceptable and only slightly conservative to use the strength obtained from a triaxial compression test as input for the active plane strain condition (i.e. $s_u^A = s_u^{C,TX}$) and the strength obtained from a triaxial extension test as input for the passive plane strain condition (i.e. $s_u^P = s_u^{E,TX}$). More control over the strength difference between triaxial and plane strain loading conditions can be obtained by using the advanced parameter $s_u^{C,TX} / s_u^A$.

For near normally consolidated clays, the passive strength s_u^P is generally the lowest strength value, while the direct simple shear strength takes an intermediate value, i.e. $s_u^P < s_u^{DSS} < s_u^A$. From laboratory results reported in literature one find typically s_u^P / s_u^A in the range 0.2 - 0.5 and s_u^{DSS} / s_u^A in the range 0.3 - 0.8. If direct simple shear strengths are not available s_u^{DSS} can be estimated from:

Shear strain at failure in direct simple shear (γ_f^{DSS})

$$s_u^{DSS} / s_u^A = \left(1 + s_u^p / s_u^A\right) / 2 \qquad \textit{Eq. [315]}$$

13.2.11 Initial mobilization (T_0 / s_u^A)

The initial mobilization T_0 / s_u^A is clearly defined for nearly horizontally deposited normally consolidated or lightly overconsolidated clay layers where the vertical stress is the major principle stress σ'_1. As defined in Figure 64, the initial mobilization can be calculated from the earth pressure coefficient at rest K_0 by the following equation:

$$T_0 / s_u^A = -0.5(1 - K_0)\sigma'_{yy0} \qquad \textit{Eq. [316]}$$

where

σ'_{yy0} = Initial (in situ) vertical effective stress (compression negative)

A default value 0.7 of s_u^P / s_u^A is given which represent a typical value for a near normally consolidated clay deposit (e.g. $K_0 = 0.55$ and $-\sigma'_{yy0} = s_u^P / s_u^A = 3.11$ or $K_0 = 0.6$ and $-\sigma'_{yy0} = s_u^P / s_u^A = 3.5$).

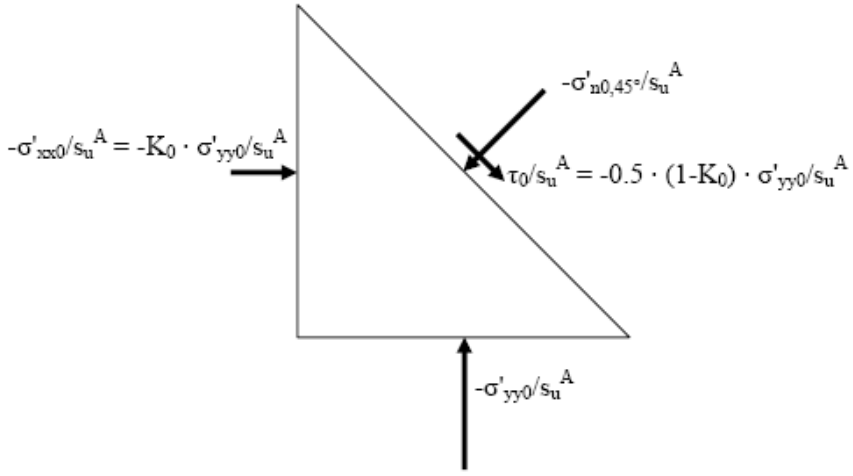


Figure 65: Definition of initial mobilised maximum shear stress $\tau_0 = 1/2\ |\sigma'_{yy0} - \sigma'_{xx0}|$ for a soil element in a horizontal deposited layer.

A more detailed evaluation of the initial (in situ) mobilization can be done by assessing the in situ K_0 value and use the relationship: $\tau_0/s_u^A = -0.5\ (1-K_0)\ \sigma'_{v0}/s_u^A$. Changing the default value for the initial mobilization should be considered in particular for overconsolidated materials where K_0 generally is higher than 0.6, however the NGI-ADP model is not intended used for heavily overconsolidated clays and should be used with care for $K_0 > 1.0$ (i.e. negative τ_0/s_u^A).

For non-horizontal layering (e.g. sloping ground) a *K0 procedure* is normally not recommended. In such cases it is recommended to establish the initial stress condition by gravity loading using a material model suited for such a purpose (e.g. drained behavior with the Mohr-Coulomb model or the Hardening Soil model). After the equilibrium initial stresses are established for gravity loading in the first phase, one should switch to the NGI-ADP model in the relevant clusters for the next phase and run a NIL step (i.e. without changing the external loads). The hardening parameter of the NGI-ADP model will then be adjusted such that equilibrium is obtained (f=0). Then in the third phase the external loading can be applied.

13.2.12 Poisson's ratio (ν')

Similar as in the Mohr-Coulomb model, Poisson's ratio is generally between 0.3 and 0.4 for loading conditions considering effective stress analysis. For unloading conditions a lower value is more appropriate. For more information about the Poisson's ratio, see Basic parameters of the Mohr-Coulomb model (on page 35)

When the *Undrained (C)* drainage option is used a pure total stress analysis is carried out where no distinction between effective stresses and pore pressures is made and all stress changes should be considered as changes in total stress. A Poisson's ratio close to 0.5 should be entered. $\nu = 0.495$ is given as default.

13.3 State parameters in the NGI-ADP model

In addition to the output of standard stress and strain quantities, the NGI-ADP model provides output (when being used) on state variables such as plastic shear strain γ_p and the hardening function r_κ. These parameters

can be visualised by selecting the *State parameters* option from the *Stresses* menu. An overview of available state parameters is given below:

γ^p	Plastic shear strain : $\gamma^p = \sum d\gamma^p$	[-]
$d\gamma^p$	Described in Eq. [306].	[-]
r_κ	Hardening function: $r_\kappa = 2\frac{\sqrt{\gamma^p / \gamma_f^p}}{1 + \gamma^p / \gamma_f^p}$	[-]

14 The UDCAM-S model

For the design of offshore structures under a design storm (i.e. a combination of wave, wind and current loading), the stiffness and the bearing capacity of the foundation have to be calculated accounting for the effect of cyclic loading. The response of saturated soils under cyclic loading is different from the case of the static loading. It may be increased due to strain rate effects and reduced due to the degradation process, pore pressure build-up and destructuration.

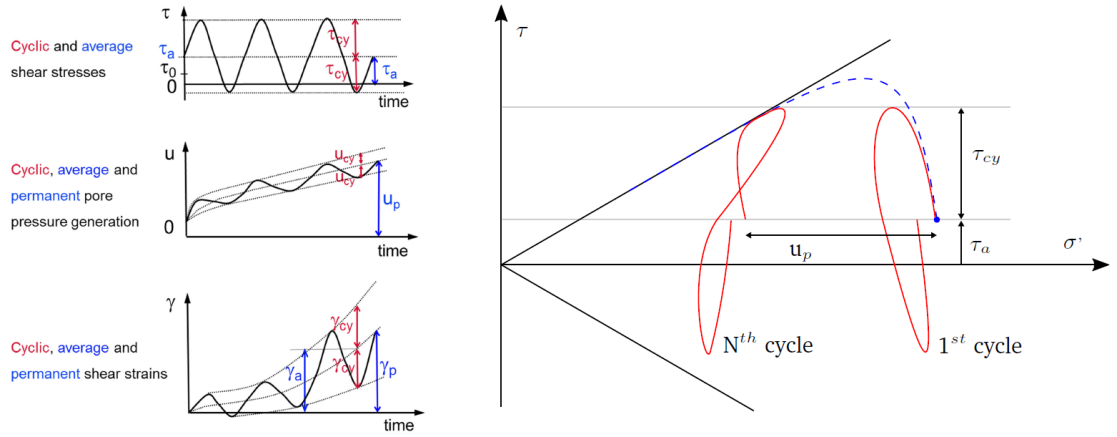
The soil strength in static undrained conditions can be described by the undrained shear strength of the soil s_u, which is dependent on the effective stress level, stress path and the material. However, by cyclic loading of the soil, the soil strength depends in addition on the value of the combination of the average and cyclic stresses in the soil. The shear strength is therefore written as $\tau_{f,cy}$ instead of the static undrained shear strength s_u. The undrained cyclic shear strength is described by Andersen, Kleven & Heien (1988) (on page 251), as:

$$\tau_{f,cy} = (\tau_a + \tau_{cy})_f \qquad Eq.\ [317]$$

where

τ_a = Average shear stress at failure.
$\tau_{f,cy}$ = The cyclic undrained shear strength.

The two aforementioned stress components are shown in Figure 65 (on page 158)(Andersen & Jostad, 2009 (on page 251)), where the process of excess pore pressure build-up in cyclic loading is depicted. The shear stress, the pore pressure and the shear strain are divided into two components: the average component and the cyclic component. In a cyclic triaxial test the stress is varying with the cyclic shear stress τ_{cy} with respect to the average shear stress τ_a. The effective stress decreases due to the increase in pore pressure and the stress paths move to the left, generally defined as either *15%* average shear strain or *15%* cyclic shear strain. After a certain number of cycles *N* the soil reaches a failure strength. The same soil can thus fail at a lower shear stress in cyclic loading than in monotonic loading.



(a) Pore pressure built up and shear strain accumulation during cyclic loading

(b) Decrease in effective stress due to cyclic loading (red line) and monotonic loading (blue line)

Figure 66: Generation of pore pressures and strains in a cyclic triaxial test

Stress anisotropy (or stress path dependent behaviour) is an important aspect regarding the stability of a system. This means that the stress state is varying in the soil, and thus have to be accounted for. As shown in Figure 66 (on page 158) (Andersen, 2015 (on page 251)), the soil behaviour along a potential failure surface, indicated by the dashed line, can be interpolated between by three undrained cyclic laboratory tests:

- Direct Simple Shear test (DSS).
  - Symmetric loading ($\tau_a = 0$).
  - Asymmetric loading ($\tau_a \neq 0$).
- Anisotropically consolidated Triaxial Compression test (TXC).
- Anisotropically consolidated Triaxial Extension test (TXE).

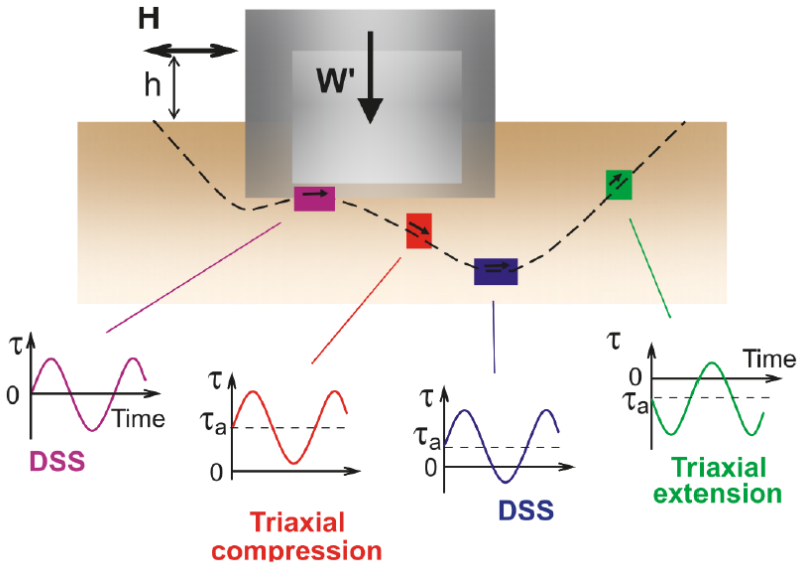


Figure 67: Ideal stress conditions along a potential failure surface in the soil beneath a gravity base structure under cyclic loading

The Simplified UnDrained Cyclic Accumulation Model (UDCAM-S) is an advanced model to deal with undrained soil behaviour and degradation of the strength and stiffness in cyclic loading of clay or low permeable silty soils. The UDCAM-S model is derived from the UDCAM model by NGI (Andresen & Jostad, 2009 (on page 251)) with simplifications in order to be more suitable for engineering practice. The material model is based on the NGI-ADP model (Andresen & Jostad, 1999 (on page 251)) for the undrained behavior of clays, implementing a pre-processing procedure called cyclic accumulation tool (Reference Manual - Chapter 6 - *Cyclic accumulation and optimisation tool*) to obtain the adjusted parameter set based on the type of analysis the user has to perform:

- Cyclic: to calculate cyclic displacements or stiffness to be used in dynamic analysis of the structure.
- Average: to calculate accumulated (permanent) displacements of the foundation.
- Total: to calculate total (*average + cyclic*) displacements, capacity or stiffnesses to be used in pseudo-static analysis of the structure.

Except from the calculation of the degraded parameter set with the cyclic accumulation tool, the UDCAM-S model inherits the same formulation and implementation of the NGI-ADP model. For more information about the formulation of the NGI-ADP model, reference is made to The NGI-ADP model (anisotropic undrained shear strength) (on page 145).

14.1 Parameters of the UDCAM-S model

The UDCAM-S model requires a total of ten parameters.

The actual components can be cyclic, average or total (average + cyclic):

- *Parameters for stiffness:*

G_{max}/τ^C	Ratio unloading/reloading shear modulus over (plane strain) active shear strength	[-]
γ_f^C	Shear strain in triaxial compression	[%]
γ_f^E	Shear strain at failure in triaxial extension	[%]
γ_f^{DSS}	Shear strain at failure in direct simple shear	[%]

- *Parameters for strength:*

τ_{ref}^C	Degraded reference shear strength in triaxial compression	[kN/m^2]
	Reference level	[m]
τ_{inc}^C	Increase of degraded triaxial compression shear strength with depth	[kN/m^2/m]
τ^E/τ^C	Ratio of degraded triaxial compression shear strength triaxial extension over degraded triaxial compression shear strength	[-]
τ_0/τ^C	Initial mobilisation	[-]
τ^{DSS}/τ^C	Ratio of degraded direct simple shear strength over degraded triaxial compression shear strength	[-]

- *Advanced parameters:*

ν'	Effective Poisson's ratio	[-]
ν_u	Undrained Poisson's ratio	[-]

Note:

The model should be only used for undrained conditions.

14.1.1 Ratio of the initial shear modulus to the degraded TXC shear strength (G_{max}/τ^C)

Ratio of the initial shear modulus to the degraded shear strength at failure in the triaxial compression test. If the shear strength is increasing with depth the constant ratio for G_{max}/τ^C gives a shear stiffness increasing linearly with depth.

14.1.2 Shear strain at failure in triaxial compression (γ_f^C)

This parameter γ_f^C (%) defines the shear strain at which failure is obtained in undrained triaxial compression mode of loading.

14.1.3 Shear strain at failure in triaxial extension (γ_f^E)

This parameter γ_f^E (%) defines the shear strain at which failure is obtained in undrained triaxial extension mode of loading.

14.1.4 Shear strain at failure in direct simple shear (γ_f^{DSS})

This parameter γ_f^{DSS} (%) defines the shear strain at which failure is obtained in undrained simple shear mode of loading.

14.1.5 Reference degraded TXC shear strength (τ_{ref}^C)

The reference degraded TxC shear strength at failure in the triaxial compression test is the shear strength obtained in triaxial compression stress paths at the reference depth y_{ref}, expressed in the unit of stress.

14.1.6 Reference depth (y_{ref})

This is the reference depth y_{ref} at which the reference TXC shear strength τ^C is defined. Below this depth the shear strength and stiffness may increase linearly with increasing depth. Above the reference depth the shear strength is equal to τ^C.

14.1.7 Increase of degraded TXC shear strength with depth ($\tau_{inc}{}^C$)

The parameter $\tau_{inc}{}^C$ defines the increase (positive) or decrease (negative) of the undrained TXC shear strength with depth, expressed in the unit of stress per unit of depth. Above the reference depth the shear strength is equal to $\tau_{ref}{}^C$, below the reference depth the shear strength is defined as:

$$\tau^C(y) = \tau^C_{ref} + (y_{ref} - y)\tau^C_{inc} \qquad \textit{Eq. [318]}$$

14.1.8 Ratio of the degraded TXE shear strength to the undrained TXC shear strength (τ^E/τ^C)

The ratio τ^E/τ^C defines the degraded undrained shear strength for triaxial extension mode of loading in relation to the degraded undrained shear strength in triaxial compression mode of loading. Please note that active / passive strength input is defined for plane strain conditions. However, it is generally acceptable and only slightly conservative to use the strength obtained from a triaxial compression test as input for the active plane strain condition (i.e. $\tau_c{}^A = \tau^C$) and the strength obtained from a triaxial extension test as input for the passive plane strain condition (i.e. $\tau^P = \tau^E$).

14.1.9 Ratio of the degraded DSS shear strength to the undrained TXC shear strength (τ^{DSS} / τ^c)

The ratio τ^{DSS}/τ^C defines the degraded undrained shear strength in direct simple shear mode of loading in relation to the degraded undrained shear strength in triaxial compression mode of loading.

14.1.10 Initial mobilization (τ_0/τ^C)

The initial mobilization τ_0/τ^C is clearly defined for nearly horizontally deposited normally consolidated or lightly overconsolidated clay layers where the vertical stress is the major principle stress σ'_1. As defined in Figure 67, the initial mobilization can be calculated from the earth pressure coefficient at rest K_0 by the following equation:

$$\tau_0/\tau^C = -0.5(1 - K_0)\sigma'_{yy0}/\tau^C \qquad \textit{Eq. [319]}$$

where

σ'_{yy0} = initial (in situ) vertical effective stress (compression negative).

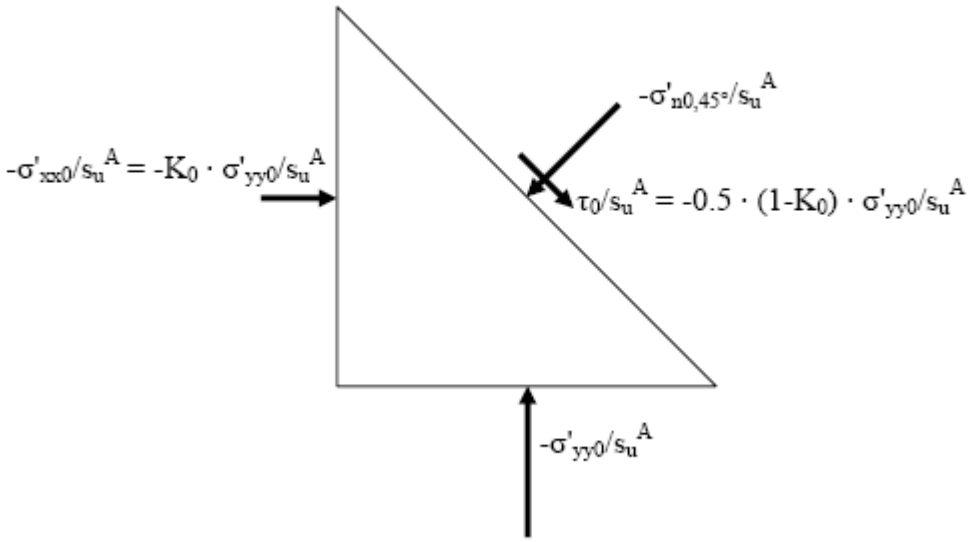


Figure 68: Definition of initial mobilised maximum shear stress $\tau_0 = 1/2\ |\sigma'_{yy0} - \sigma'_{xx0}|$ for a soil element in a horizontal deposited layer.

Changing the default value for the initial mobilization should be considered in particular for overconsolidated materials where K_0 generally is higher than 0.6, however the UDCAM-S model (like NGI-ADP model) is not intended used for heavily overconsolidated clays and should be used with care for $K_0 > 1.0$ (i.e. negative τ_0/τ^C).

14.1.11 Poisson's ratio (ν')

Only *Undrained (C)* drainage option should be used as a pure total stress analysis is carried out where no distinction between effective stresses and pore pressures is made and all stress changes should be considered as changes in total stress. A Poisson's ratio of.$\nu = 0.495$ should be used for the calculation.

14.2 State parameters in the UDCAM-S model

γ_p	Plastic shear strain	[-]
r_κ	Hardening function	[-]

$$r_\kappa = 2\frac{\sqrt{\gamma^p / \gamma_f^p}}{1+\gamma^p / \gamma_f^p} \qquad Eq.\ [320]$$

14.3 On the use of the UDCAM-S model in dynamic calculations

The model should not be used in dynamic calculations.

15 The Concrete model

Generally, for concrete structure elements, a linear elastic material model is adopted due to their strength compared to the one of the soil. However, in some kind of geotechnical problems, the complex non-linear behaviour of the concrete structures must be inspected for a reliable redistribution of stress-strain in the continuum and a correct design. Distinction can be made between the main features of the complex concrete behaviour: limited strength in compression and tension, time-dependent strength and stiffness, strain hardening/softening, creep and shrinkage.

The Concrete model was originally developed to model the behaviour of shotcrete, but it is also useful for soil reinforcement (e.g. concrete columns), soil improvements (e.g. jet grouting columns) and concrete structures (e.g. beams). The current engineering approach to model shotcrete linings in numerical simulations assumes a linear elastic material with a stepwise increase of the (artificially low) Young's modulus in subsequent excavation stages. While realistic lining deformations may be obtained with this method, lining stresses are usually too high, in particular if the lining is subjected to significant bending. With the Concrete model more realistic stress distributions can be obtained, as the non-linearity of the material behaviour is taken into account. Furthermore, the stability of the tunnel can be checked at all intermediate stages without the need for additional capacity checks of the lining cross section.

The Concrete model is an elastoplastic model for simulating the time-dependent strength and stiffness of concrete, strain hardening-softening in compression and tension as well as creep and shrinkage (Schadlich & Schweiger, 2014 (on page 254)). Hence, differently from what is seen in Eq. [69] , the total strain ε is not only decomposed into elastic strain ε^e and plastic strain ε^p but also considers creep strain ε^{cr} and shrinkage strain ε^{shr}:

$$\varepsilon = \varepsilon^e + \varepsilon^p + \varepsilon^{cr} + \varepsilon^{shr} \qquad Eq.\ [321]$$

When subjected to deviatoric loading, concrete shows different behaviours: in compression, the strength increases non-linearly up to a peak value and then softens to a residual one; in tension, it's considered linear elastic until reaching the tensile strength and then softens to the residual value. The Concrete model employs a Mohr-Coulomb yield surface for deviatoric loading, combined with a Rankine yield surface in the tensile regime.

Most of the input parameters for the Concrete model can be derived from standard uniaxial tension and compression tests. Some basic characteristics of the Concrete model and their relevant input parameters are:

Limited strength in compression and tension.	$f_{c,28}, f_{t,28}$
Time-dependent strength and stiffness.	$f_{c,1} / f_{c,28}, E_1 / E_{28}, \varepsilon^p{}_{cp}, t_{hydr}$
Strain hardening in compression	f_{c0n}
Strain softening in compression and tension	$f_{cfn}, f_{cun}, G_{c,28}, f_{tun}, G_{t,28}$
Stress- and stiffness-dependent creep strains	$\varphi^{cr}, t^{cr}{}_{50}$

Stress-independent shrinkage strains	$\varepsilon^{shr}{}_{\infty}$, $t^{shr}{}_{50}$

The stress-strain approach for hardening and softening is proposed by Schütz, Potts & Zdravkovi´c (2011) (on page 254), involving mobilised compression and tensile strength through the uniaxial plastic peak strain $\varepsilon^{p}{}_{cp}$ at 1h, 8h, 24h and the fracture energy of the material both in compression, G_c, and in tension, G_t. Furthermore, thanks to the time-dependent internal laws of the Concrete model for f_c, f_t, G_c and G_t, the hardening-softening of the yield surfaces completely follows the evolution of the material in time. The time-dependency of elastic stiffness, compressive and tensile strength is taken into account following an approach similar to the recommendation of CEB-FIP model code (1990) as well as EN 14487-1. The ability of young concrete to withstand large deformations at early age, thanks to its initial high plastic ductility, is represented by a time-dependent plastic peak strain $\varepsilon^{p}{}_{cp}$ (Meschke, Kropik & Mang, 1996 (on page 254)).

15.1 Formulation of the Concrete model

The Concrete model employs a composite yield surface; Mohr-Coulomb surface for deviatoric loading and Rankine surface in the tensile regime with isotropic compression softening (Figure 68 (on page 165)). In the Concrete model formulation, the yield function is named with capital *F* in order to distinguish it from the yield stress *f*. The sign convention is strictly tension-positive and σ_1 is the major (tensile) principle stress and σ_3 is the minor (compressive) principle stress.

The yield functions can be formulated in terms of principal stresses in relation to the uniaxial compressive and tensile yield stresses, f_{cy} and f_t, as:

$$F_c = \frac{\sigma_1 - \sigma_3}{2} + \frac{\sigma_1 + \sigma_3 - 2\ \sigma_{rot}}{2}\ \frac{f_{cy}}{2\ \sigma_{rot} + f_{cy}} \qquad \textit{Eq. [322]}$$

$$F_t = \sigma_1 - f_t \qquad \textit{Eq. [323]}$$

where

σ_{rot} = Intersection of the Mohr-Coulomb failure envelope and the isotropic axis.

For a given maximum inclination of the Mohr-Coulomb envelope, σ_{rot} can be written as:

$$\sigma_{rot} = \frac{f_c}{2}\left(\frac{1}{\sin(\varphi_{max})} - 1\right) \qquad \textit{Eq. [324]}$$

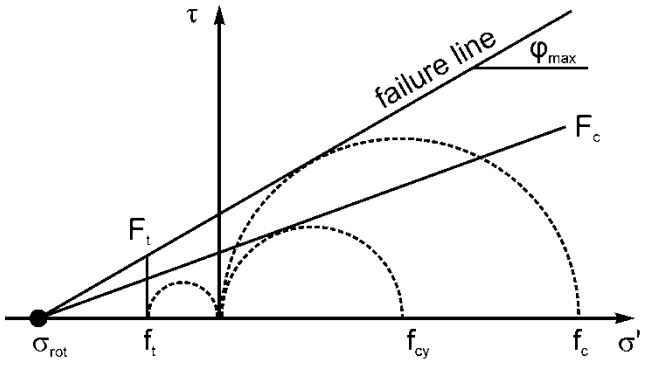


Figure 69: Yield surfaces and failure envelope for Concrete model

15.2 Strain hardening and softening

15.2.1 *Compression*

In compression, the Concrete model follows the approach proposed by Schütz, Potts & Zdravkovi´c (2011) (on page 254). The stress-strain curve is divided in four parts (Figure 69 (on page 166)):

- Part I - quadratic strain hardening
- Part II - linear strain softening
- Part III - linear strain softening
- Part IV - constant residual strength

Due to the time-dependency of the involved material parameters, a normalised hardening/softening parameter $H_c = \varepsilon^p{}_3 / \varepsilon^p{}_{cp}$ is used, with $\varepsilon^p{}_3$ = minor plastic strain (calculated from F_c) and $\varepsilon^p{}_{cp}$ = plastic peak strain in uniaxial compression.

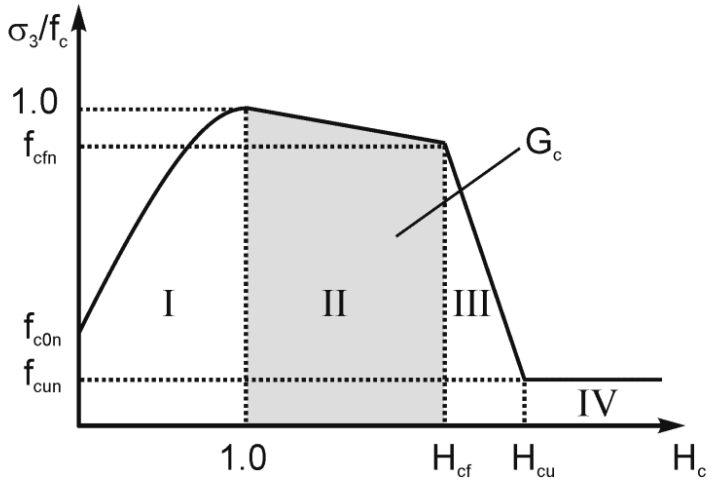


Figure 70: Normalised stress-strain curve in compression

In part I, the uniaxial yield stress f_{cy} is mobilised with H_c according to a quadratic function:

$$f_{cy,I} = f_c \left(f_{c0n} + (1 - f_{c0n}) \left(2H_c - H_c^2 \right) \right) \qquad Eq.\ [325]$$

where f_{c0n} is the initial ratio f_{cy} / f_c. During mobilisation the yield surface F_c rotates around the anchor point σ_{rot} on the isotropic axis, activating the shear isotropic hardening.

Full mobilisation of f_c coincides with $H_c = 1$, after witch (i.e. part II) linear softening takes place, until the failure strength $f_{cf} = f_{cfn} f_c$ is reached at $H_{cf} = \varepsilon^p_{cf} / \varepsilon^p_{cf}$. Strength reduction is assumed to be caused by the destruction of inter-particle bonds, and consequently a parallel shift of the fully mobilised Mohr-Coulomb failure envelope:

$$f_{cy,II} = f_c \left(1 + (f_{cfn} - 1)\left(\frac{H_c - 1}{H_{cf} - 1}\right)\right) \qquad \textit{Eq. [326]}$$

where ε^p_{cf} is derived from the fracture energy in compression, G_c, and the characteristic length of the finite element, L_{eq}, which provides the necessary regularisation to avoid mesh dependent numerical results:

$$\varepsilon^p_{cf} = \varepsilon^p_{cp} - \frac{2G_c}{(1 + f_{cfn})\ f_c\ L_{eq}} \qquad \textit{Eq. [327]}$$

L_{eq} is calculated by PLAXIS from the size of the finite element, A_{el}, and the number of stress points per element n_{GP}, (Polling, 2000 (on page 254)):

$$L_{eq} = 2\sqrt{\frac{A_{el}}{\sqrt{3}\ n_{GP}}} \qquad \textit{Eq. [328]}$$

Note: When using the **SoilTest** with the Concrete Model, since there is no mesh, $L_{eq} = 1$.

In part III the linear strain softening is governed by the condition that the energy in elastic unloading must not be greater than the plastic strain energy absorbed by the crack (no span-back of stress-strain curve on stress point level). That delivers the plastic ultimate strain ε^p_{cu} as:

$$\varepsilon^p_{cu} = \varepsilon^p_{cf} - \frac{2 f_c\ (f_{cfn} - f_{cun})}{E} \qquad \textit{Eq. [329]}$$

with f_{cun} = residual strength level = f_{cu} / f_c and E = elastic Young's modulus. The yield stress F_{cy} follows as:

$$f_{cy,III} = f_c \left(f_{cfn} + (f_{cun} - f_{cfn})\left(\frac{H_c - H_{cf}}{H_{cu} - H_{cf}}\right)\right) \qquad \textit{Eq. [330]}$$

where $H_{cu} = \varepsilon^p{}_{cu} / \varepsilon^p{}_{cp}$. In part IV, there is no further softening of the stress-strain curve, which yields:

$$f_{cy,IV} = f_c\ f_{cun} \qquad \textit{Eq. [331]}$$

To account for the increasing ductility with increasing confining pressure, the total peak strain $\varepsilon_{cp} = \varepsilon^p{}_{cp} + \varepsilon^e{}_{cp}$ increases with the confining pressure, σ_1, as in a triaxial compression test, governed by the input parameter a:

$$\varepsilon_{cp} = \varepsilon_{cp,UC}\left(1 + a\ \frac{\sigma_1}{-f_c}\right) \qquad \textit{Eq. [332]}$$

For instance, $a = 1$ and $\sigma_1 = -f_c$ yield a 100% increase of total peak strain ε_{cp} compared to the uniaxial compression test. Internally, the increase of ε_{cp} is translated into an increase of $\varepsilon^p{}_{cp}$, which is assumed to be governed by the mean stress $p = (\sigma_1 + \sigma_2 + \sigma_3) / 3$ according to:

$$\varepsilon^p_{cp} = \varepsilon^p_{cp,UC}\left(1 + b\ \frac{p + f_c/3}{-f_c}\right) \qquad \textit{Eq. [333]}$$

$$b = \frac{2\sin(\varphi_{max})\frac{f_c}{E} + a(1 - \sin(\varphi_{max}))\ \left(\varepsilon^p_{cp} - \frac{f_c}{E}\right)}{\varepsilon^p_{cp}\ (1 - \sin(\varphi_{max})/3)} \qquad \textit{Eq. [334]}$$

15.2.2 *Tension*

The Concrete model behaviour in tension is linear elastic until the tensile strength f_t is reached, then softens with a linear strain softening (Figure 70 (on page 168)). The strain softening is governed by the normalised tension softening parameter $H_t = \varepsilon^p{}_1 / \varepsilon^p{}_{tu}$ with $\varepsilon^p{}_1$ = major principal plastic strain (calculated from F_t) and $\varepsilon^p{}_{tu}$ = Plastic ultimate strain in uniaxial tension as:

$$f_{ty} = f_t \left(1 + \left(f_{tun} - 1\right) H_t\right) \qquad Eq.\ [335]$$

Similar to softening in compression, $\varepsilon^p{}_{tu}$ is derived from the fracture energy in tension, G_t:

$$\varepsilon^p_{tu} = \varepsilon_{tp} + \frac{2G_t}{\left(1 + f_{tun}\right) f_t \; L_{eq}} \qquad Eq.\ [336]$$

where

ε_{tp} = Elastic peak strain in uniaxial extension.

Once the residual strength $f_{tu} = f_{tun} f_t$ is reached, no further softening takes place.

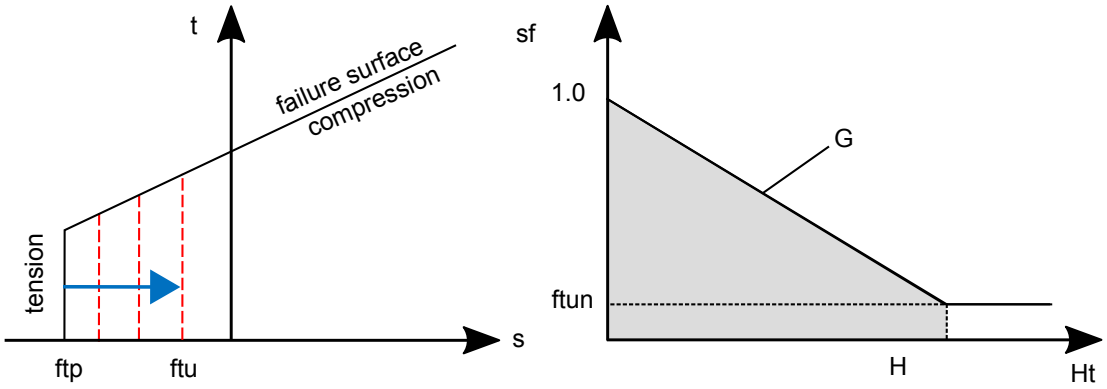


Figure 71: Tension softening

15.3 Time-dependency of the Concrete model

15.3.1 *Strength and Stiffness*

The Concrete model takes into account the time-dependent behaviour of material parameters. The stiffness and strength of concrete increase rapidly with time due to the hydration of the cement paste. The increase of Young's modulus E in the model follows an approach similar to the recommendation of CEB-FIP model code (1990) (on page 251):

$$E(t) = E_{28} \; e^{s_{stiff}\left(1-\sqrt{t_{hydr}/t}\right)} \qquad Eq.\ [337]$$

where

E_{28} = Young's modulus of cured concrete.
t_{hydr} = Time until full curing (e.g. usually taken as 28 days).

t = time (days).
s_{stiff} = Parameter governing stiffness evolution with time.

s_{stiff} is related to the stiffness ratio at 1 day, E_1 / E_{28}, and t_{hydr}, as:

$$s_{stiff} = -\frac{ln(E_1 / E_{28})}{\sqrt{t_{hydr} / t_{1d}} - 1} \qquad Eq.\ [338]$$

where t_{1d} is the duration of one day in the unit time. The Young's modulus is constant for $t<1h$ and for $t>t_{hydr}$.

For the uniaxial compressive strength f_c, the Concrete model implements two different approaches. The first, as for E, is similar to the recommendation of CEB-FIP model code (1990) for concrete. The relations are the same as before but exchanging s_{stiff} with $s_{strength}$, which depends now on the strength ratio at 1 day, $f_{c,1} / f_{c,28}$, and t_{hydr} (equations Eq. [339] and Eq. [340]). A lower limit of $f_c = 0.005\, f_{c,28}$ is used at very early age. The CEB-FIP type approach yields very low concrete strength at ages <2h.

$$f_c(t) = f_{c,28}\, e^{s_{strength}\left(1-\sqrt{t_{hydr}/t}\right)} \qquad Eq.\ [339]$$

$$s_{strength} = -\frac{ln(f_{c,1} / f_{c,28})}{\sqrt{t_{hydr} / t_{1d}} - 1} \qquad Eq.\ [340]$$

Alternatively, the strength evolution can be modelled in accordance to the shotcrete strength classes J1, J2 and J3 of EN 14497-1, which define ranges of shotcrete strength at different shotcrete ages up to 24h. Mean values of these ranges have been assumed for class J1 and J2 in the Concrete model with class J3 lying 50% above the boundary between classes J2 and J3 (Table 8 (on page 169)). Between 24h and t_{hyd}, an approach proposed by Oluokun, Burdette & Deatherage (1991) (on page 254) is adopted:

$$f_c = \alpha_c e^{-b_c / t} \qquad Eq.\ [341]$$

$$\alpha_c = \frac{f_{c,28}}{e^{ln(\kappa) / \{t_{hydr} - t_{1d}\}}} \quad b_c = \left(-t_{hydr} / (t_{hydr} - t_{1d})\right) ln(\kappa) \quad \kappa = f_{c,24h} \Big/ f_{c,28} \qquad Eq.\ [342]$$

where f_c is the time-dependent compressive strength and $f_{c,24h}$ is the compressive strength at 24h (Table 8 (on page 169)).

Table 8: Mean uniaxial compressive strength of J1, J2 and J3 strength classes

Time[hr]	J1[MPa]	J2[MPa]	J3[MPa]
<0.1	0.15	0.35	0.75
0.5	0.23	0.715	1.65
12	2.0	5.5	12.0
24	3.5	12.0	28.5

The ratio of f_t / f_c and the values of f_{cfn}, f_{cun} and f_{tun} are assumed to be constant in curing for both approaches.

15.3.2 *Plastic Deformability*

The ability of young concrete to withstand large deformations is not only a result of its low elastic modulus at this age, but also due to its high plastic ductility. With concrete aging this ductile behaviour decreases.

In the Concrete model this behaviour is represented by a time-dependent plastic peak strain $\varepsilon^p{}_{cp}$. Similar to the approach proposed by Meschke, Kropik & Mang (1996) (on page 254), a tri-linear function in time is adopted. Input values are the plastic peak strains at t = 1h, 8h and 24h. Beyond 24h, $\varepsilon^p{}_{cp}$ is assumed to be constant (Figure 71 (on page 170)).

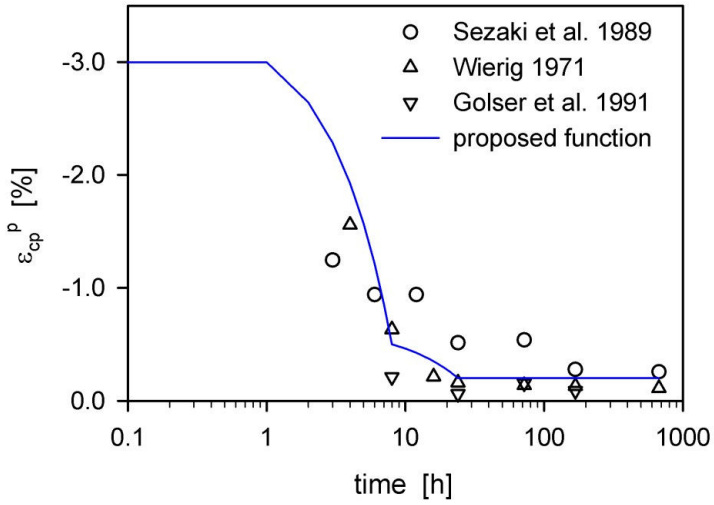


Figure 72: Reduction of ε_{cp}^{p} with aging in the Concrete model compared to experimental data from uniaxial compression tests. The chosen ε_{cp}^{p} values are -3%, -0.5% and -0.2%.

15.3.3 *Fracture energy*

The plastic time-dependency during softening is taken into account with the change of fracture energies with time, which is automatically computed by PLAXIS. In tension, the tensile failure strain $\varepsilon^p{}_{tu}$ is derived from the tensile fracture energy and tensile strength of the cured concrete, regardless of the current concrete age. Since the tensile strength f_t increases with time, but $\varepsilon^p{}_{tu}$ remains constant, the current fracture G_t increases proportionally with the increase of f_t.

The plastic failure strain in compression, $\varepsilon^p{}_{cf}$, is coupled to the plastic peak strain $\varepsilon^p{}_{cp}$ such that the ratio $\varepsilon^p{}_{cf}$ / $\varepsilon^p{}_{cp}$ remains constant. As $\varepsilon^p{}_{cp}$ decreases with time (Figure 71 (on page 170)), $\varepsilon^p{}_{cf}$ and hence G_c reduce. On the other hand, the compressive strength f_c increases with time, which results in higher values of G_c. The influence of these counteracting trends brings high values of the fracture energy at early age, a sharp drop at ≈12h and a linear increase of G_c with f_c afterward (Figure 72 (on page 171)). The high fracture energy at very early age is a consequence of the desired ductile behaviour at this stage. As very young concrete effectively does not fail at all in compression, the fracture energy theoretically should be infinite.

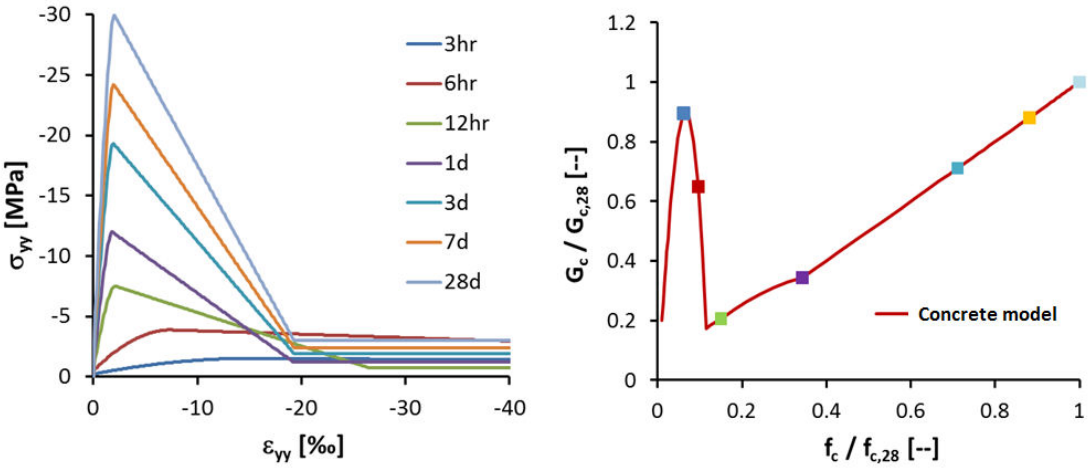


Figure 73: Stress-strain curves in uniaxial compression at different ages and development of compressive fracture energy with compressive strength

15.3.4 *Viscoelastic Creep*

The Concrete model employs a viscoelastic approach for creep. Creep strains, ε^{cr}, increase linearly with stress σ and are related to elastic strains via the creep factor φ^{cr}:

$$\varepsilon^{cr}(t) = \frac{\varphi^{cr}\ \underline{\sigma}}{\mathbf{D}^{e}}\ \frac{t - t_0}{t + t^{cr}_{50}} \qquad \textit{Eq. [343]}$$

The evolution of creep with time t is governed by the start of loading at time t_0 and the parameter t^{cr}_{50}. For instantaneous loading ($t_0 = 0$), t^{cr}_{50} equals the time until 50% of the creep strains have evolved. For concrete utilization higher than 45% of f_c, non-linear creep effects are accounted for by replacing φ^{cr} with the following equation from Eurocode 2:

$$\varphi^{cr}_{k} = \varphi^{cr} e^{1.5(k_\sigma - 0.45)} \qquad \textit{Eq. [344]}$$

with $k_\sigma = \sigma_c / f_{cm}$ being the degree of concrete utilisation in compression. Due to the time-dependency of the linear elastic stiffness matrix $\mathbf{D}^e$, the creep history is stored as normalised values of $\underline{\varepsilon}^{cr}(t) \cdot E(t)$.

Note:

The creep history is adjusted for the stress state at first activation of the concrete cluster, such that no creep strains are produced by initial stresses. The state variables are taken over if the previous material was also defined with the Concrete model, in which case creep will also continue. If a reset of state variables is desired, a nil step with a different material (e.g. linear elastic) is required.

15.3.5 *Shrinkage*

The Concrete model refers to shrinkage as the isotropic loss of volume with time, which is independent of the stress state. Shrinkage strains ε^{shr} are calculated according to the recommendation of ACI (1992) (on page 251) as:

$$\varepsilon^{shr}(t) = \varepsilon_{\infty}^{shr} \frac{t}{t + t_{50}^{shr}} \qquad Eq.\ [345]$$

with $\varepsilon_{\infty}^{shr}$ being the final axial shrinkage strain and t_{50}^{shr} the time when 50% of shrinkage has occurred.

15.4 Parameters of the Concrete model

The Concrete model involves a number of parameters which are generally familiar to structural engineers. These parameters with their standard units are listed below.

- *Parameters for stiffness:*

E_{28}	Young's modulus for rock as a continuum	[kN/m^2]
ν	Poisson's ratio	[-]

- *Parameters for strength:*

Compression parameters		
$f_{c,28}$	Young's modulus for rock as a continuum	[kN/m^2]
f_{c0n}	Normalised failure strength	[-]
f_{cfn}	Normalised initially mobilised strength	[-]
f_{cun}	Normalised residual strength	[-]
$G_{c,28}$	Compressive fracture energy of cured concrete at t_{hydr}	[kN/m]
φ_{max}	Maximum friction angle	[°]
ψ	Dilatancy angle	[°]
γ_{fc}	Safety factor for compressive strength	[-]

Tension parameters		
$f_{t,28}$	Uniaxial tensile strength of cured concrete at t_{hydr}	[kN/m^2]
f_{tun}	Ratio of residual vs. peak tensile strength	[-]

$G_{t,28}$	Tensile fracture energy of cured concrete at t_{hydr}	[kN/m]
γ_{ft}	Safety factor for tensile strength	[-]

- *Parameters for ductility:*

$\varepsilon_{cp}{}^{p}$	Uniaxial plastic failure strain	[-]
a	Increase ε_{cp} with increase of p	[-]

- *Time-dependent parameters:*

t_{hydr}	Time for full hydration	[day]
Stiffness parameters		
E_1 / E_{28}	Time-dependency ratio of elastic stiffness	[-]
Strength parameters		
$f_{c,1} / f_{c,28}$	Time-dependency of compressive strength	[-]
Ductility		
$\varepsilon^{p}{}_{cp,1h}$	Uniaxial plastic failure strain at 1h (negative value)	[-]
$\varepsilon^{p}{}_{cp,8h}$	Uniaxial plastic failure strain at 8h (negative value)	[-]
$\varepsilon^{p}{}_{cp,24h}$	Uniaxial plastic failure strain at 24h (negative value)	[-]
Shrinkage		
$\varepsilon^{shr}{}_{\infty}$	Final shrinkage strain (negative value)	[-]
$t^{shr}{}_{50}$	Time for 50% of shrinkage strains	[day]
Creep		
ϕ^{cr}	Ratio between creep and elastic strains	[-]
$t^{cr}{}_{50}$	Time for 50% of creep strains	[day]

The Concrete model allows two drainage types: non-porous, which is the general approach for concrete structural elements, and drained, in case of semi-permeable walls or tunnel linings.

15.4.1 Recommended values for the parameters of the Concrete model

Elastic parameters

Differently from the Mohr-Coulomb model, the Concrete model employs time-dependent stiffness. If *Time dependent strength and stiffness* is turned off then the editing of E_1 / E_{28} is disabled and it's set to 1. If *Time dependent strength and stiffness* is turned on, a E_1 / E_{28} is defined, generally a range of 0.5 - 0.7 is recommended with E_{28} between 25 GPa and 30 GPa.

Strength in compression

The uniaxial compressive strength of cured concrete $f_{c,28}$ can be derived from uniaxial compressive test results. The time-dependency of compressive strength *expressed as* $f_{c,1} / f_{c,28}$ is recommended in the range of 0.2-0.3 for cast concrete, whilst it depends on the strength class (i.e. J1, J2 and J3) for shotcrete. The stress-strain curve in compression (Figure 69 (on page 166)) is defined through the normalised strength values. The normalised mobilised strength f_{c0n} contributes to the part I hardening, a value in the range of 0.1 - 0.25 is recommended. The normalised failure strength f_{cfn} rules the part II softening, a value of 0.1 is recommended. The normalised residual strength f_{cun} rules the part III softening and the residual strength, a value of 0.1 is recommended. f_{cfn} must be greater or almost equal to f_{cun} in order to avoid input error. f_{cfn} or f_{cun} = 1 implies no softening in the respective regions.

Time-dependency of compressive strength

The uniaxial compressive strength is defined at the time t_{hydr}, time for full hydration (usually 28 days). If *Time dependent strength and stiffness* is turned off then $f_{c,1} / f_{c,28}$ is set automatically equal to 1 and the editing is disabled. If *Time dependent behaviour* is turned on, then the user can choose in the combo box *Strength functions* among:

- *CEB-FIP model code (1990)*: the user can define $f_{c,1} / f_{c,28}$. The default value = 1 corresponds to no time-dependency. For cast concrete a value of [0.2, 0.3] is recommended.
- *Shotcrete strength class J1*: $f_{c,1} / f_{c,28}$ is automatically computed in accordance with the selected strength class (Table 8 (on page 169)).
- *Shotcrete strength class J3*: $f_{c,1} / f_{c,28}$ is automatically computed in accordance with the selected strength class (Table 8 (on page 169)).

Strength in tension

The tensile strength $f_{t,28}$ can in principle be derived from uniaxial tensile test results. Due to the experimental difficulties involved in these tests, however, indirect tests or direct correlations with the compressive strength are more common. Both for concrete and shotcrete, a value of $f_{t,28} = 0.1\, f_c$ is recommended. The ratio of residual vs. peak tensile strength f_{tun} is recommended to be 0.

Note:

In shotcrete linings the tensile strength is essential for tunnel stability. Neglecting or considering low values of it could result in unrealistic failure.

Parameters φ_{max}, ψ and a

Determination of φ_{max}, ψ and a requires triaxial tests on cured concrete. The impact of these parameters in typical tunnelling calculations, however, is small, as at least one of the major principal stresses in the lining is close to 0. Furthermore, not all of these will be typically available, so values in the range of 35°- 43°, 0°- 10° and 16 - 20 are respectively suggested for φ_{max}, ψ and a.

Fracture energy

The compressive fracture energy of cured concrete $G_{c,28}$ can be estimated from the stress-strain curve of uniaxial compression tests. However a value in the range of 30kN/m - 70kN/m is recommended. The tensile fracture energy of cured concrete $G_{t,28}$ can be estimated from the stress-strain curve of uniaxial tensile tests. Due to the experimental difficulties involved in these tests, the fracture energy can be estimated as following. For plain shotcrete, a value in the range of 0.05kN/m - 0.15kN/m is recommended. However, the shotcrete can be reinforced using steel fibres, in this case $G_{t,28}$ can be estimated with the correlation proposed by Barros & Figueiras (1999) (on page 251):

$$G_{t,28} = \left(1 + 13.159 W_f^{1.827}\right) G_{t0} \qquad Eq.\ [346]$$

where

G_{t0} = The fracture energy of plain shotcrete
W_t = fibre percentage in weigh [kg/m^3]

For plain concrete, the value is strictly dependent on the strength class and the maximum aggregate size d_{max} (Table 9 (on page 175), CEB-FIP model code (1990) (on page 251)).

Table 9: Fracture energy $G_{t,28}$ for plain concrete

d_{max}(mm)	$G_{t,28}$ (N/m)							
	C12	C20	C30	C40	C50	C60	C70	C80
8	26.91	34.06	42.18	49.67	56.71	63.39	69.78	75.93
16	32.30	40.87	50.61	59.61	68.05	76.07	83.73	91.11
32	62.44	79.02	97.86	115.24	131.56	147.06	161.88	176.15

Ductility

If *Time dependent behaviour* is turned off then a single peak parameter ε^p_{cp} is available instead of $\varepsilon^p_{cp1,h}$, $\varepsilon^p_{cp8,h}$ and $\varepsilon^p_{cp24,h}$ and no-dependency of ductility in time is considered. If *Time dependent behaviour* is turned on, then the user can define $\varepsilon^p_{cp,1h}$, $\varepsilon^p_{cp,8h}$ and $\varepsilon^p_{cp,24h}$. Values in the range of -0.03 - -0.01, -0.0015 - -0.001 and -0.0012 - -0.0007 are respectively suggested for $\varepsilon^p_{cp,1h}$, $\varepsilon^p_{cp,8h}$ and $\varepsilon^p_{cp,24h}$.

Creep

Creep properties of concrete can be derived from uniaxial multistage creep tests. Deriving creep properties from such a test requires additional information about strength, stiffness and ductility development with time. The user can follow the recommendation of Eurocode 2 for cast concrete, instead values in the range of 2 - 3 for φ^{cr} are suggested for shotcrete tunnel linings. t^{cr}_{50} is recommended in a range of 1d - 5d. If *Creep behaviour* is inactive, φ^{cr} and t^{cr}_{50} are disabled for editing and both set to 0. If *Creep behaviour* is active, the parameters can be defined.

Shrinkage

Concrete shrinkage is strongly influenced by environmental conditions and water-cement-ratio, such that low air humidity and high water-cement ratios amplify it. Due to less aggregate content and higher water-cement

ratio, shrinkage of shotcrete is more pronounced than for conventional cast concrete (Austin & Robins, 1995 (on page 251)). If *Shrinkage behaviour* is inactive, $\varepsilon^{shr}{}_{\infty}$ and $t^{shr}{}_{50}$ are disabled. If *Shrinkage behaviour* is active, the user can set the parameters.

Eurocode 2 recommends final shrinkage strains, $\varepsilon^{shr}{}_{\infty}$, for cast concrete of -0.0002 to -0.0006 depending on air humidity, concrete class and the effective size of the structural element. For tunnel linings values in the range of -0.0015 - -0.0005 for $\varepsilon^{shr}{}_{\infty}$ and of 28d - 100d for $t^{shr}{}_{50}$ are suggested.

Safety factors

To facilitate calculations based on design values of concrete strength, the Concrete model implements the possibility to use separate safety factors γ_{fc} and γ_{ft} for compressive and tensile strength. In fact PLAXIS design approach is not advisable for these two parameters, because:

- In case the user defines the time-dependency of strength through the classes J1, J2 and J3, the shotcrete strength values at 0.5h, 12h and 24h are not related to $f_{c,28}$. Using a lower value of $f_{c,28}$ therefore does not affect the shotcrete strength at early age, if the early strength classes are used.
- If lower concrete strength is used due to safety considerations, also the fracture energy should be reduced to obtain similar stress-strain curves.
- The creep factor increases for concrete utilisation *>0.45* f_c. Using design values for f_c would therefore overestimate creep effects.

For these reasons input safety factors γ_{fc} and γ_{ft} have been introduced. The characteristic, time-dependent compressive and tensile strengths f_c and f_t as well as the corresponding fracture energies G_c and G_t, are divided by γ_{fc} and γ_{ft} in each calculation step, but concrete utilization always refers to the characteristic values of f_c and f_t.

15.4.2 Summary of recommended parameters for Concrete model

Table 10 (on page 176) groups the Concrete model parameters as a function of the material properties and the time dependency.

Table 10: Recommended parameters and values for the Concrete model

Parameter	Recommended values	Unit
1. Stiffness parameters (non-time dependent)		
E_{28}	[25, 30]	[GPa]
ν	[0.15, 0.25]	[-]
2. Strength parameters		
a) Strength in compression		
$f_{c,28}$	Depending on strength class	[kN/m^2]
f_{c0n}	[0.10, 0.25]	[-]

Parameter	Recommended values	Unit
f_{cfn}	[0.1]	[-]
f_{cun}	[0.1]	[-]
$G_{c,28}$	[30, 70]	[kN/m]
φ_{max}	[35, 43]	[º]
ψ	[0, 10]	[º]
γ_{fc}	Safety factor depending on design standard	[-]
b) Strength in tension		
$f_{t,28}$	Depending on strength class	[kN/m]
f_{tun}	[0]	-
$G_{t,28}$	[0.05, 0.15] plain shotcrete, [Table 9 (on page 175)] cast concrete	[kN/m^2]
γ_{ft}	Safety factor depending on design standard	[-]
c) Ductility		
$\varepsilon^p{}_{cp}$		[-]
a	[16, 20]	[-]
3. Time dependent parameters		
t_{hydr}	[28]	[day]
a) Stiffness		
E_1 / E_{28}	[0.5, 0.7]	[-]
b) Strength		
$f_{c,1} / f_{c,28}$	[J1, J2, J3] shotcrete, [0.2, 0.3] cast concrete	[-]
c) Ductility		
$\varepsilon^p{}_{cp,1h}$	[-0.01, -0.03]	[-]
$\varepsilon^p{}_{cp,8h}$	[-0.001, -0.0015]	[-]

Parameter	Recommended values	Unit
$\varepsilon^{p}_{cp,24h}$ -	[-0.0007, -0.0012]	[-]
a	[16, 20]	[-]
d) Shrinkage		
$\varepsilon^{shr}_{\infty}$	[-0.0005, -0.0015] shotcrete tunnel lining, [-0.0002, -0.0006] cast concrete	[-]
t^{shr}_{50}	[28, 100]	[day]
e) Creep		
φ^{cr}	[2, 3] shotcrete tunnel lining, [Eurocode 2] cast concrete	[°]
t^{cr}_{50}	[1, 5]	[day]

15.5 State parameters in the Concrete model

In addition to the output of standard stress and strain, the Concrete model provides an output on state variables such as the current elastic modulus $E(t)$ and the current compressive yield stress f_{cy}. These parameters can be visualised by selecting the ***State parameters*** option from the **Stresses** menu. An overview of available state parameters is given below:

Δt	Age of concrete	day
E	Average Young's modulus in current step	[kN/m^2]
f_c	Uniaxial compressive strength at the end of the current step	[kN/m^2]
f_{cy}	Current compressive yield stress	[kN/m^2]
H_c	Normalised compressive strain hardening parameter	[-]
H_t	Normalised tensile strain hardening parameter	[-]
UtilFC	Concrete utilisation factor in compression	[-]
UtilFT	Concrete utilisation factor in tension	[-]
$\varepsilon^{cr}_{xx} \cdot E(t)$	Normalised creep history strain in xx direction	[-]
$\varepsilon^{cr}_{yy} \cdot E(t)$	Normalised creep history strain in yy direction	[-]

$\varepsilon^{cr}_{zz} \cdot E(t)$	Normalised creep history strain in zz direction	[-]
$\varepsilon^{cr}_{xy} \cdot E(t)$	Normalised creep history strain in xy direction	[-]
$\varepsilon^{cr}_{yz} \cdot E(t)$	Normalised creep history strain in yz direction	[-]
$\varepsilon^{cr}_{xz} \cdot E(t)$	Normalised creep history strain in xz direction	[-]

Some parameters are further explained in the following two sections:

15.5.1 Concrete utilisation factor in compression *UtilFC*

The concrete utilisation factor in compression *UtilFC* is defined as:

$$UtilFC = \sigma_{rot}\left(\frac{\sigma_3 - \sigma 1}{\sigma_1 - \sigma_{rot}}\right)\Big/\left(\gamma_{fc} f_c\right) \quad (Hardening) \qquad Eq.\ [347]$$

$$UtilFC = \sigma_{rot}\left(\frac{\sigma_3 - \sigma 1}{\sigma_1 - \sigma_{rot}}\right)\Big/\left(\gamma_{fc} f_{cy}\right) \quad (Softening) \qquad Eq.\ [348]$$

The utilisation factor is constant in hardening and is related to the maximum uniaxial compressive strength at the end of the current step f_c. After the peak value is reached and the softening is taking place, the utilisation factor is related to the current compressive yield stress f_{cy} and follows the stress-strain curve in softening (Figure 69 (on page 166)).

15.5.2 Concrete utilisation factor in tension *UtilFT*

The concrete utilisation factor in tension *UtilFT* is defined as:

$$UtilFT = \frac{\sigma_1}{f_t \gamma_{ft}} \quad (Softening) \qquad Eq.\ [349]$$

The utilisation factor is constant during the linear softening in tension and is related to the maximum uniaxial tensile strength at the end of the current step f_t. When the residual value is reached, then $f_t = f_{tun}$.

15.6 On the use of the Concrete model in dynamic calculations

Generally the time steps and the time interval for the usual dynamic calculations are in the range of seconds. However, the time scale in concrete hardening is in the range of hours to days. For this reason, in dynamic analysis, the use of the Concrete model with time-dependency of the parameters is not recommended unless the concrete elements are not totally cured in the previous construction stages. Otherwise, in dynamic analysis the ***Time dependent strength and stiffness***, the ***Creep behaviour*** and the ***Shrinkage behaviour*** should be disabled, nevertheless the Concrete model continues to take into account the stress-strain hardening and softening.

15.7 Warning

The problems involving tension softening with low fracture energy could affect the convergence of the FE-calculation, even though the model itself can never fail physically. The crack initiation massively increases the global error, even though the step size is gradually reduced by the global iteration procedure.

A structure made of strain softening material behaves in a brittle or ductile manner, not only depending on the material behaviour formulated at stress point level, but also on the size of the structure, with the response becoming ever more brittle the larger the structure is. This is due to the increase of energy released by the unloading part of the structure compared to the fracture energy dissipated in the crack. If the energy in unloading is larger than the fracture energy of the crack, both forces and displacements need to decrease in order to reach equilibrium.

However, in tunnelling the shotcrete never involves failure with low fracture energy. The problem could occur in other applications regarding rigid inclusions in the ground.

16 Application of advanced soil models (PLAXIS 2D)

In this chapter, advanced soil models will be utilised in various applications in order to illustrate the particular features of these models.

16.1 Hardening Soil model: Response in drained and undrained triaxial tests

In this section, the Hardening Soil model is utilised for the simulations of drained and undrained triaxial tests. Arbitrary sets of model parameters, Table 11 (on page 181), representing sands of different properties, are considered.

Table 11: Arbitrary Hardening Soil parameters for sands of different densities

Parameter	Loose	Medium	Dense	Unit
E_{50}^{ref} (for $p_{ref} = 100$ kPa)	20000	30000	40000	[kN/m^2]
E_{ur}^{ref} (for $p_{ref} = 100$ kPa)	60000	90000	120000	[kN/m^2]
E_{oed}^{ref} (for $p_{ref} = 100$ kPa)	20000	30000	40000	[kN/m^2]
Cohesion c	0.0	0.0	0.0	[kN/m^2]
Friction angle φ	30	35	40	°
Dilatancy angle ψ	0	5	10	°
Poisson's ratio ν_{ur}	0.2	0.2	0.2	-
Power m	0.5	0.5	0.5	-
K_0^{nc} (using Cap)	0.5	0.43	0.36	-
Tensile strength	0.0	0.0	0.0	[kN/m^2]

Parameter	Loose	Medium	Dense	Unit
Failure ratio	0.9	0.9	0.9	-

A triaxial test can simply be modelled by means of an axisymmetric geometry of unit dimensions (1m x 1m), that represent a quarter of the soil specimen, Figure 73 (on page 182). These dimensions are not realistic, but they are selected for simplicity. The dimension of the model does not influence the results, provided that the soil weight is not taken into account. In this configuration the stresses and strains are uniformly distributed over the geometry. The deformation magnitudes in *x*- and *y*-direction of the top right hand corner correspond to the horizontal and vertical strains respectively.

The left hand side and the bottom of the geometry are axes of symmetry. At these boundaries the displacements normal to the boundary are fixed and the tangential displacements are kept free to allow for 'smooth' movements. The remaining boundaries are fully free to move.

The value of the applied loads can be controlled by the load multipliers such as *ΣMloadA* and *ΣMloadB*. However, in PLAXIS 2D, and as described in the *Reference Manual*, the load configurations and magnitudes can be specified in the Input program. Then in the calculation program these loads can be activated or deactivated by means of the ***Staged construction*** option. For this case, and to simulate the confining pressure *p*', distributed loads of *-100* kN/m$_2$representing the principal stresses σ'_1 (load A) and σ'_3 (load B) are applied in the **Input**, as shown in Figure 73 (on page 182).

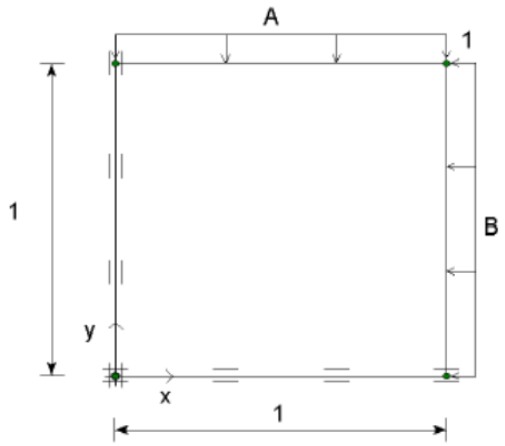


Figure 74: Simplified configuration of a triaxial test

A very course mesh is sufficient for this simple geometry. Initial stresses and steady pore pressures are not taken into account.

In the calculation program, the calculation of all phases can be done by means of the **Staged construction** process. In the first phase, the confinement pressure *p*' is applied by activating load A and B. In the second phase the displacements are reset to zero and the sample is vertically loaded up to failure while the horizontal load is kept constant. This implies modification of load A by double clicking the load in the geometry model. As a result a **load** window appears in which the input values of the load can be changed. (Details of the procedure can be found in the *Reference* and *Tutorial manuals*) The latter phase is carried out for drained as well as undrained conditions.

These calculations are performed for the three different sets of material parameters, Table 11 (on page 181). The computational results are presented in the figures on the following pages.

Figure 74 (on page 183)shows the principal stress difference versus the axial strain for the drained condition. This shows a hyperbolic relationship between the stress and the strain, which is typical for the Hardening Soil model. Obviously, the failure level is higher when the sand is denser. The Hardening Soil model does not include softening behaviour, so after reaching failure the stress level does not reduce, at least in the drained tests.

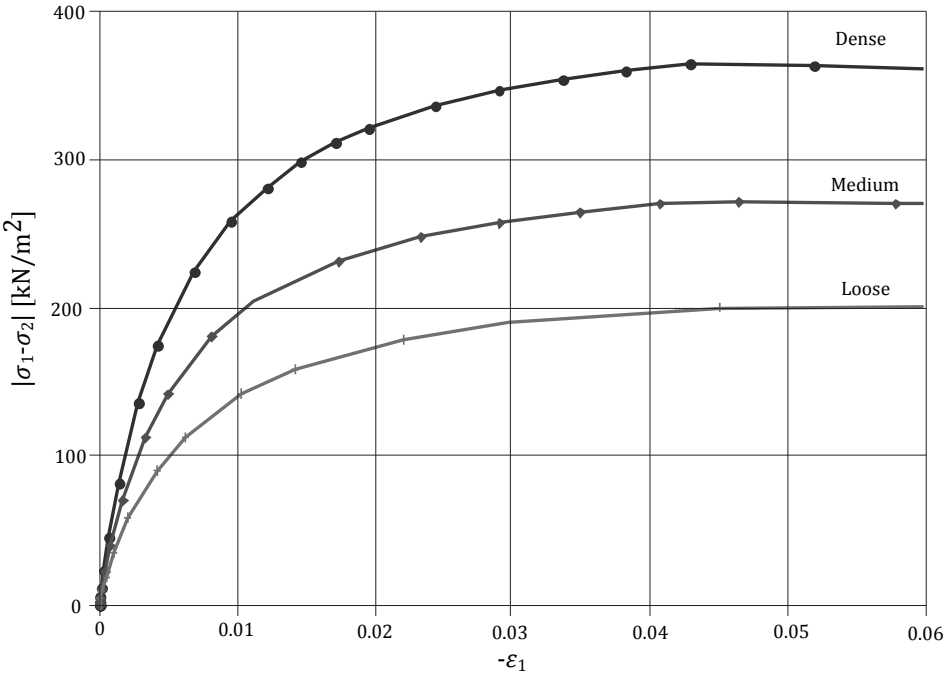


Figure 75: Results of drained triaxial tests using the Hardening Soil model, Principal stress difference versus axial strain.

Figure 75 (on page 183) shows the axial strain versus the volumetric strain for the drained test. This graph clearly shows the influence of dilatancy in the denser sands. In contrast to the Mohr-Coulomb model, the transition from elastic behaviour to failure is much more gradual when using the Hardening Soil model. In fact, in the Hardening Soil model, plastic strain occurs immediately after load application.

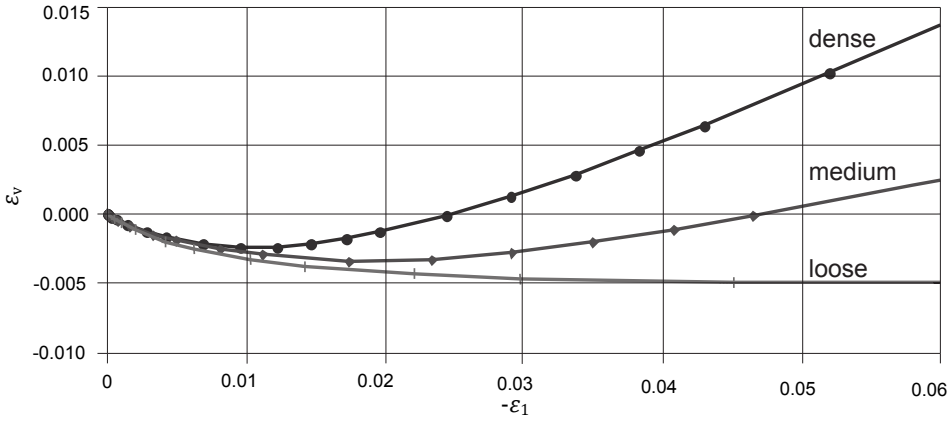


Figure 76: Results of drained triaxial tests using the Hardening Soil model, Volumetric strain versus axial strain

In the undrained tests, Figure 76 (on page 184), the failure level is, in principle, lower than that of the drained tests. However, for the medium and dense sands the stress level continues to increase after reaching the failure level due to the fact that dilatancy occurs which causes reduction of excess pore pressures and thus increase of the effective stresses. This can be seen in Figure 77 (on page 184).

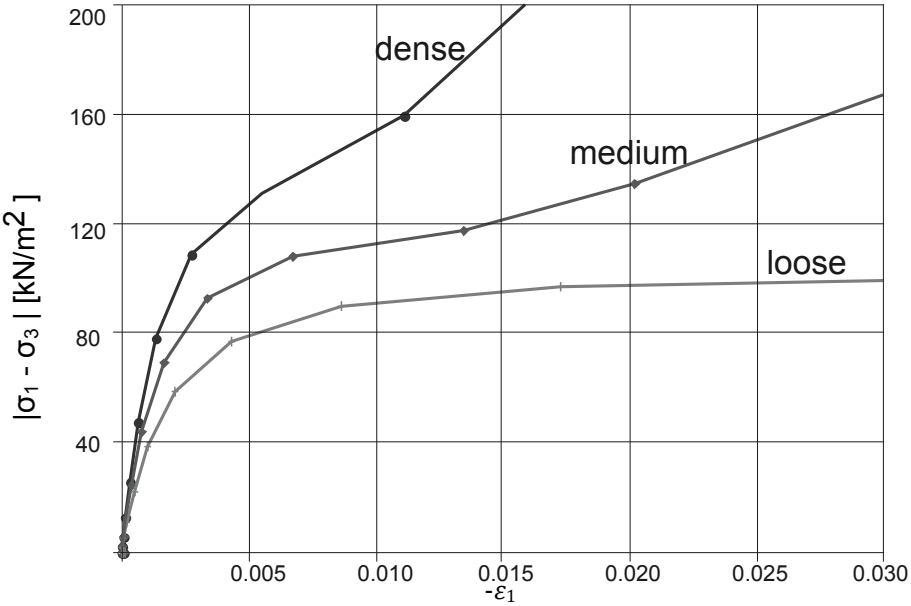


Figure 77: Results of undrained triaxial tests using the Hardening Soil model, Principal stress difference versus axial strain

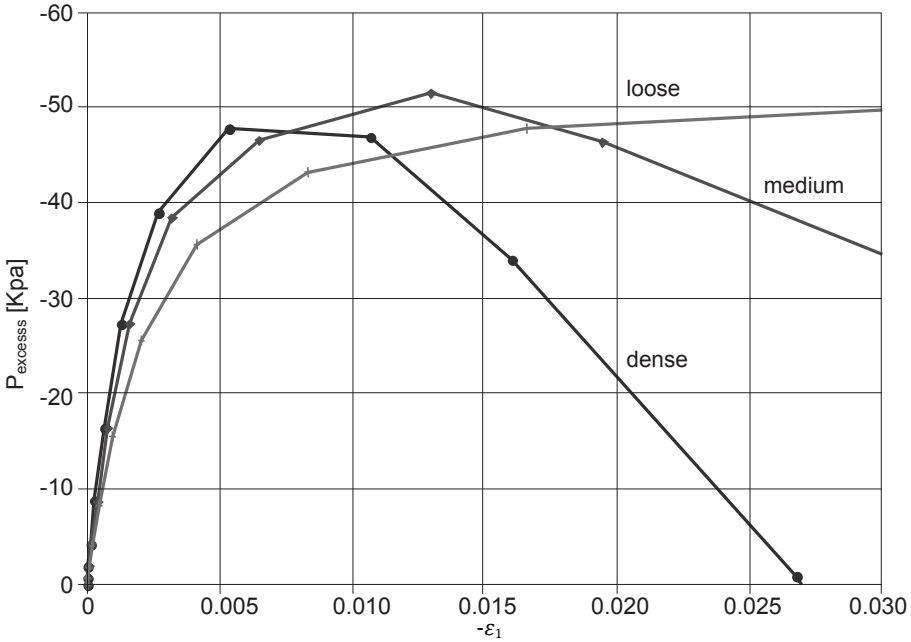


Figure 78: Results of undrained triaxial tests using the Hardening Soil model, Excess pore pressure vs axial strain

Figure 78 (on page 185) shows the effective stress paths, for the medium sand, during both the drained and undrained tests. During first phase (isotropic loading), both tests were drained. In the second phase there is a clear distinction between the two tests. In the undrained test the effective horizontal stress reduces while the vertical stress increases due to the development of excess pore pressures. The decrease in horizontal effective stress is more than when if the Mohr-Coulomb model would have been used. This is attributed to the plastic compaction (Cap hardening) that occurs in the Hardening Soil model.

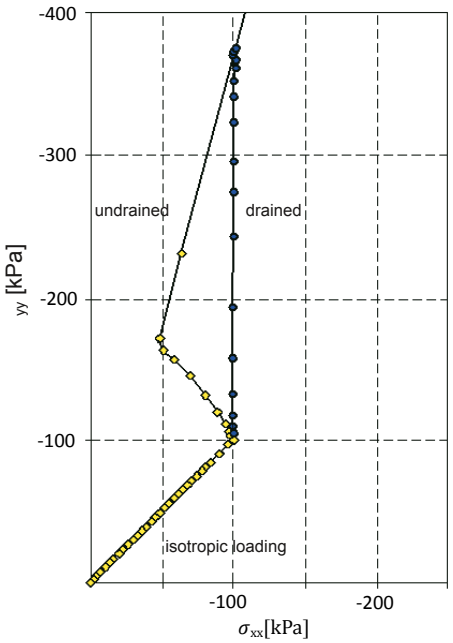


Figure 79: Stress paths for drained and undrained triaxial tests using the Hardening Soil model

16.2 Application of the Hardening Soil model on real soil tests

In this section the ability of the Hardening Soil model to simulate laboratory tests on sand is examined by comparing PLAXIS calculation results with those obtained from laboratory tests provided by Prof. J. Desrues (University Joseph Fourier, Grenoble, France). Extensive laboratory tests were conducted on loose and dense Hostun sand. On the basis of these tests the model parameters for the Hardening Soil model were determined and they are presented in Table 12 (on page 185).

Table 12: Hardening Soil parameters for loose and dense Hostun sand

Parameter	Loose sand	Dense sand	Unit
Unit weight γ	17	17.5	kN/m^3
E_{50}^{ref} (p_{ref} = *100* kPa)	20000	37000	kN/m^2
E_{ur}^{ref} (p_{ref} = *100* kPa)	60000	90000	kN/m^2

Parameter	Loose sand	Dense sand	Unit
E_{oed}^{ref} (p_{ref} = *100* kPa)	16000	29600	kN/m^2
Cohesion c'	0.0	0.0	kN/m^2
Friction angle φ'	34.0	41.0	°
Dilatancy angle ψ	0.0	14.0	°
Poisson's ratio ν_{ur}	0.2	0.2	-
Power m	0.65	0.5	-
K_0^{nc}	0.44	0.34	-
Tensile strength	0.00	0.00	kN/m^2
Failure ratio	0.9	0.9	-

16.2.1 *Triaxial Test*

Standard drained triaxial tests were performed on loose and dense sand specimens. The procedure for the simulation of the triaxial tests in PLAXIS has been described in Hardening Soil model: Response in drained and undrained triaxial tests (on page 181). In the first phase the sample is isotropically compressed up to a confining pressure of p' = -300 kN/m^2. In the second phase the sample is vertically loaded up to failure while the horizontal stress (confining pressure) is kept constant. The computational results and the measured data are presented in Figure 79 (on page 186) to Figure 82 (on page 188).

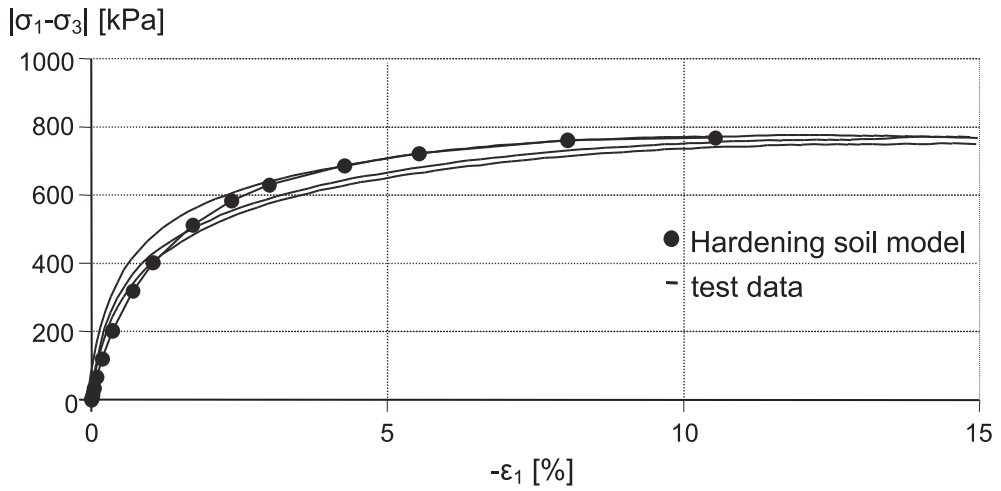


Figure 80: Results of drained triaxial tests on loose Hostun sand, deviatoric stress versus axial strain

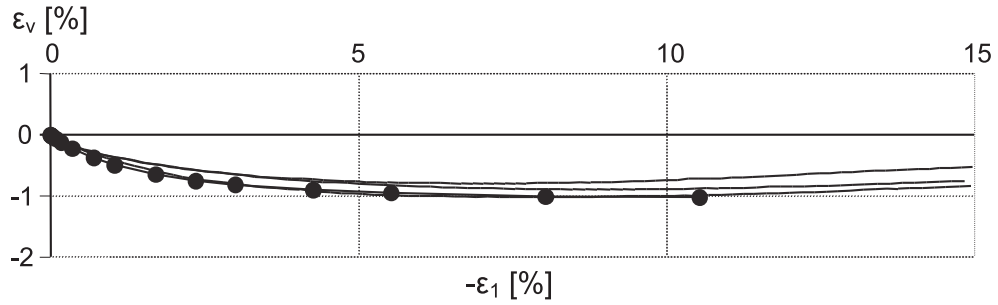


Figure 81: Results of drained triaxial tests on loose Hostun sand, volumetric strain versus axial strain

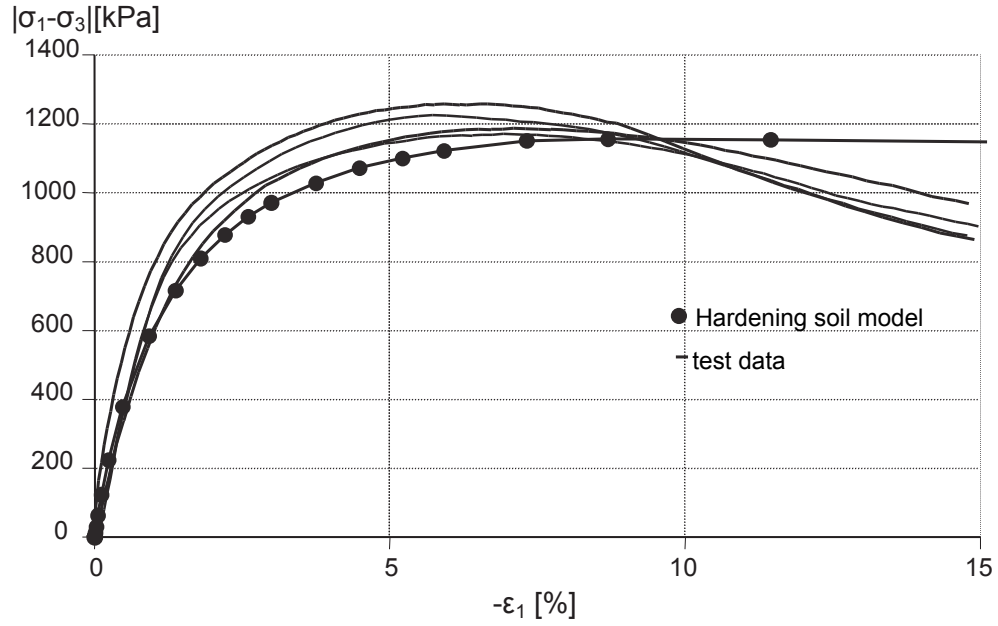


Figure 82: Results of drained triaxial tests on dense Hostun sand, deviatoric stress versus axial strain

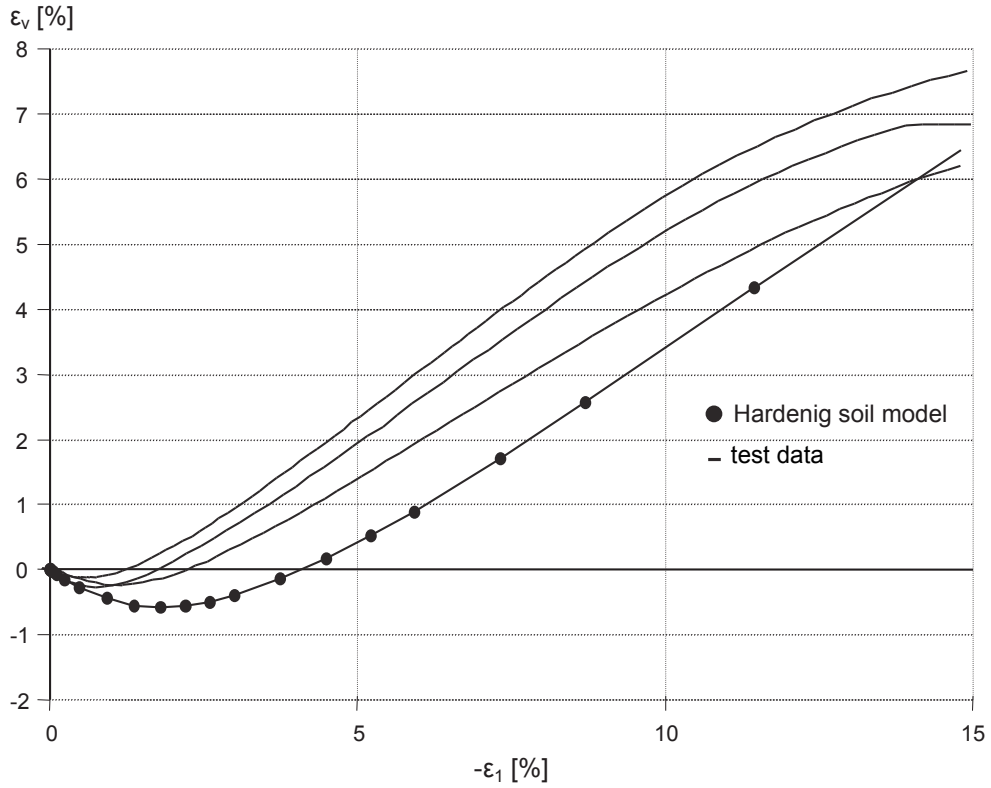


Figure 83: Results of drained triaxial tests on dense Hostun sand, volumetric strain versus axial strain

The figures show that the computational results match reasonably with the test data. It can be seen that the material response (measured and computed) show gradual transition from elastic to plastic behaviour. As such the relation between the deviatoric stress and the axial strain can be approximated by a hyperbola.

The failure level is fully controlled by the friction angle (the cohesion is zero). The test results on dense sand show softening behaviour after the peak load has been reached. Modelling of the softening behaviour, however, is not incorporated in the Hardening Soil model, and thus, the deviatoric stress remains constant. It can also be seen from the test data that the dilatancy reduces during softening. However, in the Hardening Soil model the dilatancy continues to infinity, unless the dilatancy cut-off option has been used.

16.2.2 *Oedometer test*

As for the triaxial tests, a set of oedometer tests on both loose and dense sands (Table 12 (on page 185)) was conducted. In PLAXIS the oedometer test is simulated as an axisymmetric geometry with unit dimensions (Figure 83 (on page 189)). A coarse mesh is sufficient for this case.

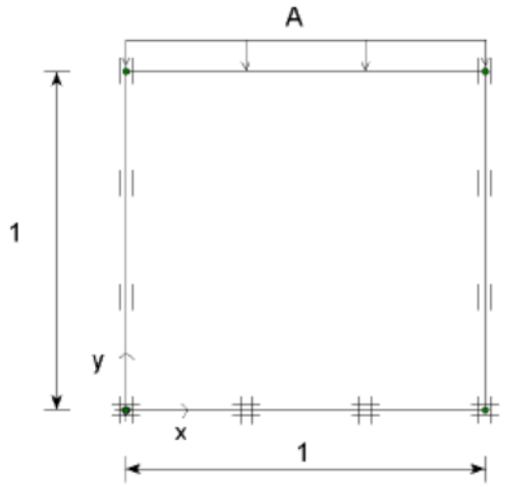


Figure 84: Simplified configuration of an oedometer test

The computational results as compared with those obtained from the laboratory tests are shown in Figure 84 (on page 189) and Figure 85 (on page 190).

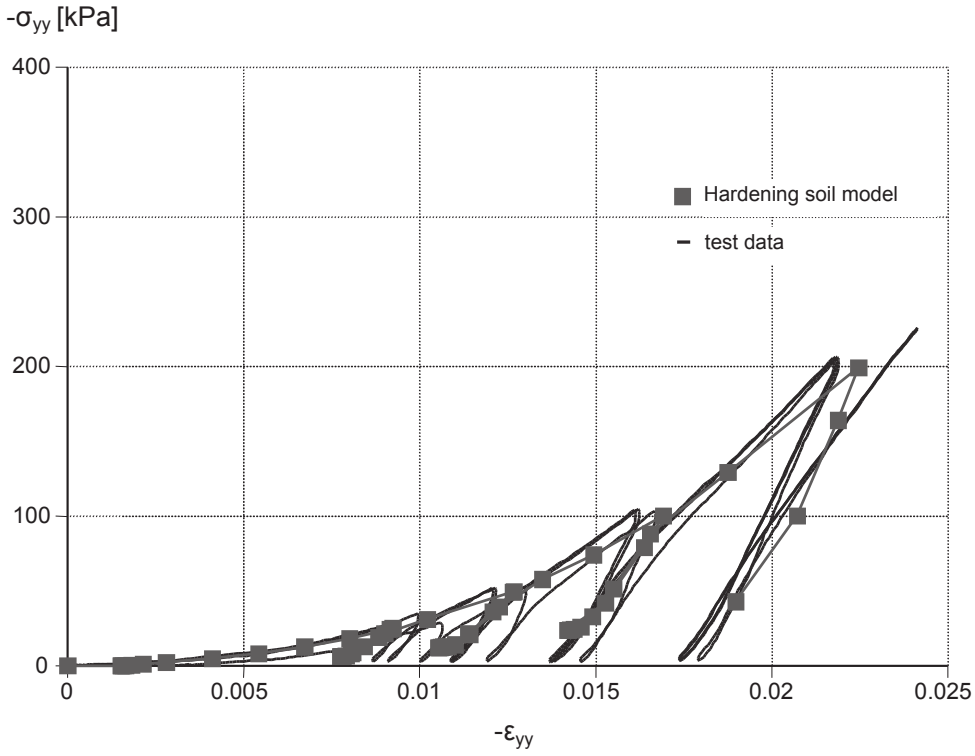


Figure 85: Results of oedometer test on loose Hostun sand, axial stress versus axial strain

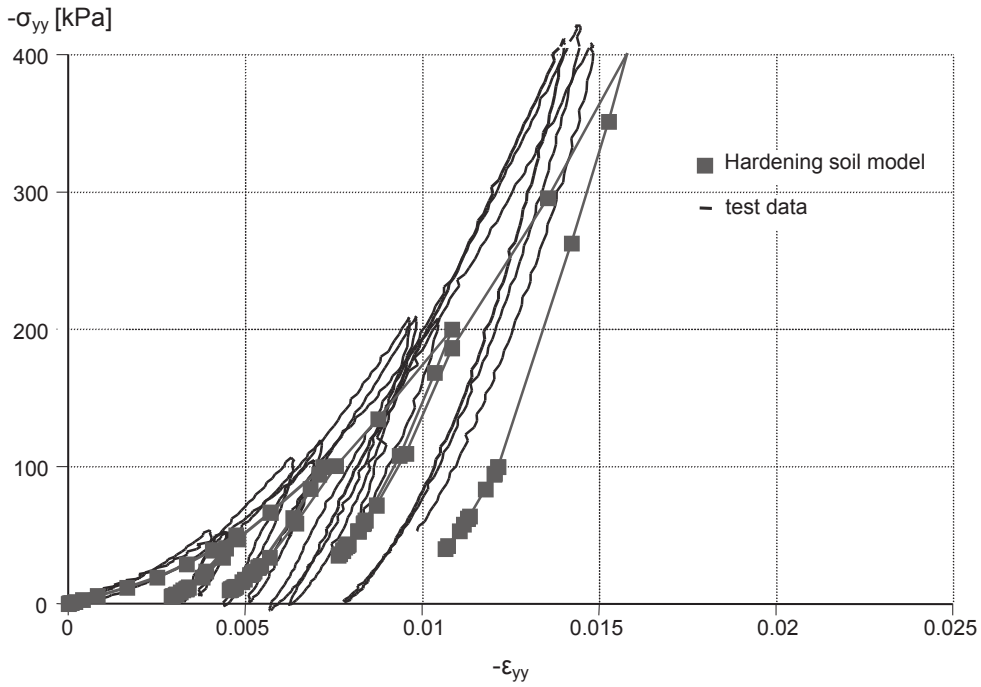


Figure 86: Results of oedometer test on dense Hostun sand, axial stress versus axial strain

From a stress free state the loose sand sample is loaded consecutively to 25 kPa, 50 kPa, 100 kPa and 200 kPa with intermediate unloading. The dense sand sample is loaded to 50 kPa, 100 kPa, 200 kPa and 400 kPa with intermediate unloading.

As it can be seen, the computational results show a reasonable agreement with the test data. No doubt, distinction should be made between loose and dense soil, but it seems that for a soil with a certain density the stiffness behaviour under different stress paths can be well captured with a single set of model parameters. (A small offset of 0.15% has been applied to the computational results of the loose sample in order to account for the relative soft response at the beginning of the test.)

16.2.3 *Pressiometer test*

In this section the Pressiometer test is simulated and results from PLAXIS 2D and laboratory tests (Branque, 1997 (on page 252)) are compared. Laboratory testing results on dense sand with material parameters listed in Table 12 (on page 185) are used.

In the field, the pressiometer of 0.044 m diameter covered with a membrane of 0.16 m height is attached to the Cone penetration shaft. In the laboratory, the pressiometer is attached to a 0.044 m pipe (r_0 = 0.022 m) and placed in a circular calibration chamber with a diameter of 1.2 m and a height of 1.50 m. A high overburden pressure of 500 kPa is applied to the surface to simulate the stress state at larger depths.

In PLAXIS 2D a quarter of the geometry is simulated by an axisymmetric model (Figure 86 (on page 191)). The left boundary is placed 0.022 m away from the vertical axis of symmetry. A line displacement is generated at the left model boundary, set to be *free* in vertical direction and *fixed* in horizontal direction. The overburden pressure is simulated by the load A, and the volumetric expansion of the pressiometer is simulated by imposing

a horizontally distributed load, load B (Figure 86 (on page 191)). Therefore the initial boundary conditions have to be changed at the level of the pressiometer in order to allow for horizontal displacements.

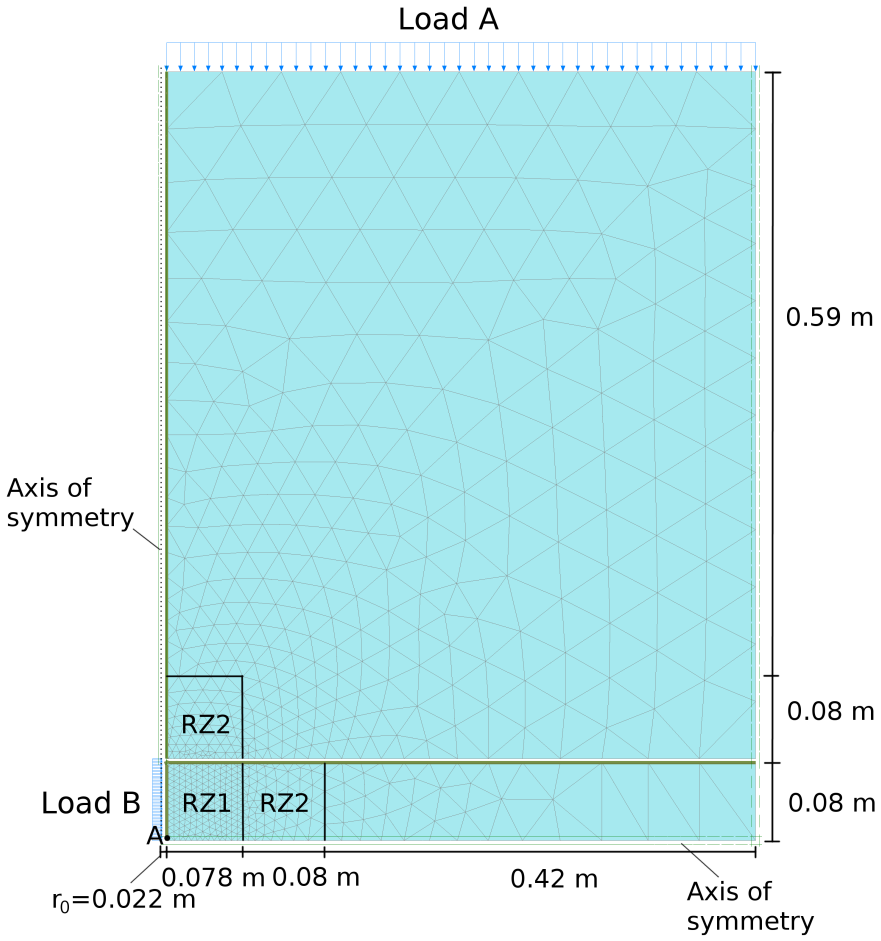


Figure 87: Model geometry and generated mesh

To allow for a discontinuity in horizontal displacements, a vertical interface along the shaft of the pressiometer borehole and a horizontal interface just above the pressiometer are introduced. Both interfaces are set rigid ($R_{inter} = 1.0$). Extra geometry lines are created around the pressiometer to locally generate a finer mesh (Figure 86 (on page 191)). A *Coarseness factor* equal to 0.1 is used for the refinement zone 1 (RZ1) and a ***Coarseness factor*** of 0.3 is used for the refinement zone 2 (RZ2). For the ***Element distribution*** the ***Medium*** option is selected .

After the generation of initial stresses in the Initial Phase, the vertical overburden load (load A) is applied in ***Phase 1***. The left model boundary is horizontally fixed via the line displacement as discussed above, while the bottom and right model boundaries are set to ***Normally fixed*** via the Deformations option in the **Model explorer** window. A plastic calculation is performed. For the subsequent calculation phases, the left model boundary should be set to **Free** via the **Deformations** option in the **Model explorer** window.

In ***Phase 2***, the line displacement which is placed at the level of the pressiometer, at the left boundary, is deactivated. The Load B is activated in order to maintain equilibrium, i.e. zero deformation. The magnitude of this load increases linearly with depth and it is calculated based on the vertical stress and Jaky's formula (for normally consolidated soils). Thus the horizontal load acting on the node located at the top of the pressiometer

equals 176.0 kPa and the horizontal load acting on the node located at the bottom model boundary equals 176.5 kPa. A plastic calculation is performed in Phase 2 as well.

In both Phases 1 and 2, the ***Tolerated error*** is set equal to 0.0001 and the ***Max load fraction per step*** is set to 0.01 to increase the accuracy of the numerical calculation. This is important in order to meticulously replace the horizontal fixity with the horizontal load at the level of the pressiometer in Phase 2.

Note:

Note that the values at the edges of the horizontal load mentioned above are calculated analytically and may slightly differ from the numerical results at the corresponding nodes, at the end of Phase 1. This is because the numerically obtained values depend on the selected number of mesh elements (mesh discretization) and on the used numerical settings for the plastic calculation in Phase 1. The user may check this discrepancy and if necessary use the numerical values to maintain equilibrium.

In the following calculation ***Phase 3***, the pressure (load B) is further increased by use of *Staged construction*. Thus the load B is set equal to 2500 kPa. An *Updated mesh analysis* is used. The *Tolerated error* is 0.01 (default value) and the ***Max load fraction per step*** is set to 0.1. The results of this calculation are presented in Figure 87 (on page 192) and Figure 88 (on page 193).

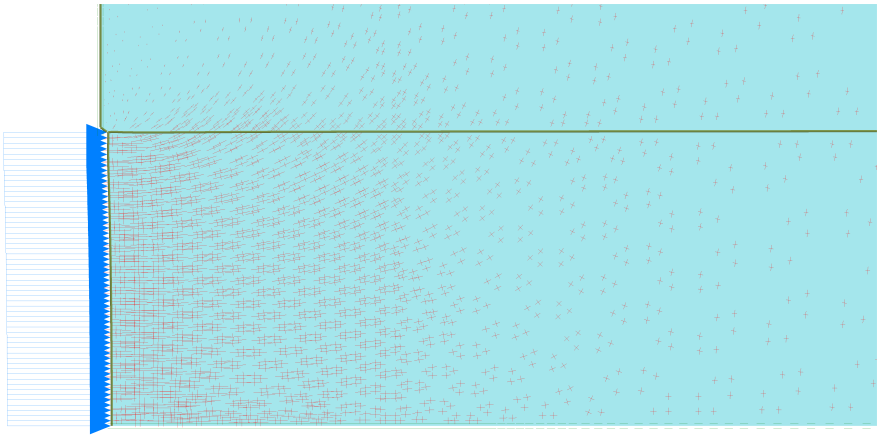


Figure 88: Effective principal stress distribution at the vicinity of the pressiometer, for a pressure of 2427 kPa (scaled up 4x10-6 times)$^{-6}$ times)

Figure 87 (on page 192) shows details of effective principal stress distribution when the pressure in the pressiometer is 2427 kPa. The high passive stresses appear very locally near the pressiometer. Just above the pressiometer the vertical stress is very low due to arching effects. Away from the pressiometer, a K_0-like stress state exists.

Figure 88 (on page 193) depicts a comparison of the numerical results with those obtained from the laboratory test. A Node *A* at the interface, at the bottom left corner of the model, is selected to illustrate the results (Figure 86 (on page 191)). In Figure 88 (on page 193) the pressiometer pressure *P* is plot against volumetric deformation $\Delta V/V_0$. Because the calculation in Phase 3 was run by accounting for large deformations (updated mesh analysis), the pressure P in the pressiometer is calculated by \eqnref{PressiometerPressureP}, based on the output quantity *ΣMstage*, the value of the applied Load B in Phase 2 ($LoadB_2$ = 176.5 kPa), the value of the applied Load B in Phase 3 ($LoadB_3$ = 2500 kPa) and a correction factor to account for large deformations:

$$P = \left[Load\,B_2 + \sum Mstage\left(Load\,B_3 - Load\,B_2\right)\right]\frac{r_0}{r_0 + u_{rr}} \qquad Eq.\ [350]$$

where

r_0 = Initial radius (0.022 m)
u_{rr} = Radial deformation of the Node A

Note:

By considering updated mesh analysis, the area E upon which pressure P acts, should be adjusted to the increasing radius, from r_0 to $r_0 + u_{rr}$. Assuming an angle θ of 1 rad, the length of the corresponding arc is $s = r\,\theta$. The area E is equal to the length s times the height of the membrane H (0.08 m). Force equilibrium between the initial state (r_0) and every next step of the calculation ($r_0 + u_{rr}$) results in the correction factor $\frac{r_0}{r_0 + u_{rr}}$. The latter is taken into account in Eq. [350].

The volumetric deformation $\Delta V/V_0$ cannot be directly obtained from PLAXIS and it is calculated by Eq. [351], based on the initial radius r_0 and the lateral expansion u_{rr} of the pressiometer at the Node A:

$$\frac{\Delta V}{V_0} = \frac{(r_0 + u_{rr})^2 - r_0^2}{r_0^2} \qquad \textit{Eq. [351]}$$

Based on Figure 88 (on page 193) it is concluded that the agreement between the numerical results and the experimental data is very good, both for the initial part of the loading curve and for larger volumetric deformations up to 30%. The original set of parameters for the dense sand that were derived from triaxial testing seem to match the pressiometer data quite well.

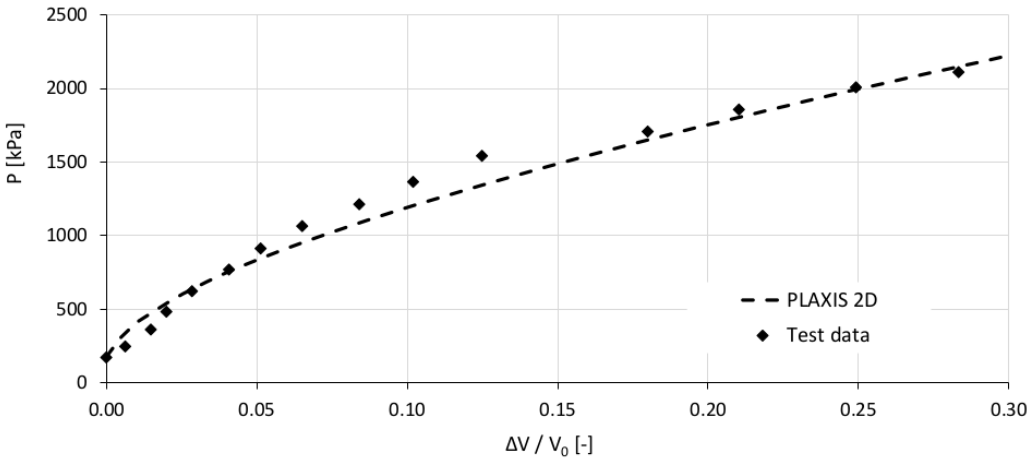


Figure 89: Comparison of numerical results and pressiometer test data

16.2.4 Conclusions of the Application of the Hardening Soil model on real soil tests

The test results indicate that by using the Hardening Soil model it is possible to simulate different laboratory tests with different stress paths. This cannot be obtained with simple models such as the Mohr-Coulomb model without changing input parameters. Hence, the parameters in the Hardening Soil model are consistent and more

or less independent from the particular stress path. This makes the Hardening Soil model a powerful and an accurate model, which can be used in many applications.

16.3 Application of the Hardening Soil model with small-strain stiffness on real soil tests

In this section, the ability of the Hardening Soil model with small-strain stiffness (*HS small model*) to simulate laboratory tests is examined. Both, the laboratory test data and the basic HS parameters are identical to those presented in the previous section. The two additional small strain parameters used in the Hardening Soil model are quantified in Table 13 (on page 194).

Table 13: Additional HSsmall model parameter for loose and dense Hostun sand

Parameter	Loose sand	Dense sand	Unit
G_0^{ref} (p_{ref} = *100* kPa)	70000	112500	[kN/m^2]
$\gamma_{0.7}$	0.0001	0.0002	[-]

Triaxial tests on loose and dense Hostun sand are presented in Figure 89 (on page 195) and Figure 90 (on page 196) respectively. As a reference, the previously obtained results from the Hardening Soil model are plotted as well.

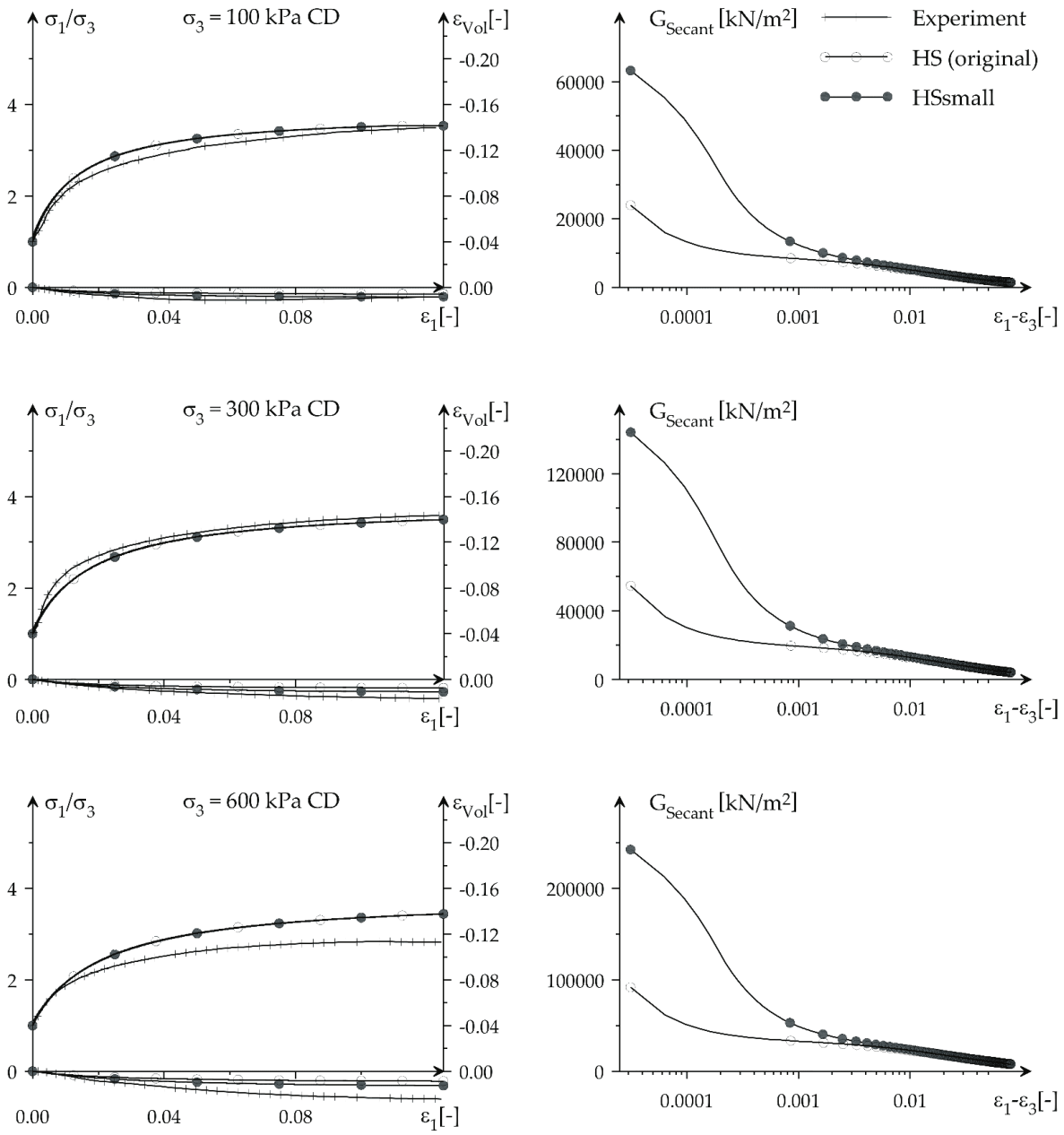


Figure 90: Excavation Drained triaxial tests on loose Hostun sand at confining pressures of 100, 300, and 600 kPa. Left: Stress-strain data. Right: Shear modulus reduction

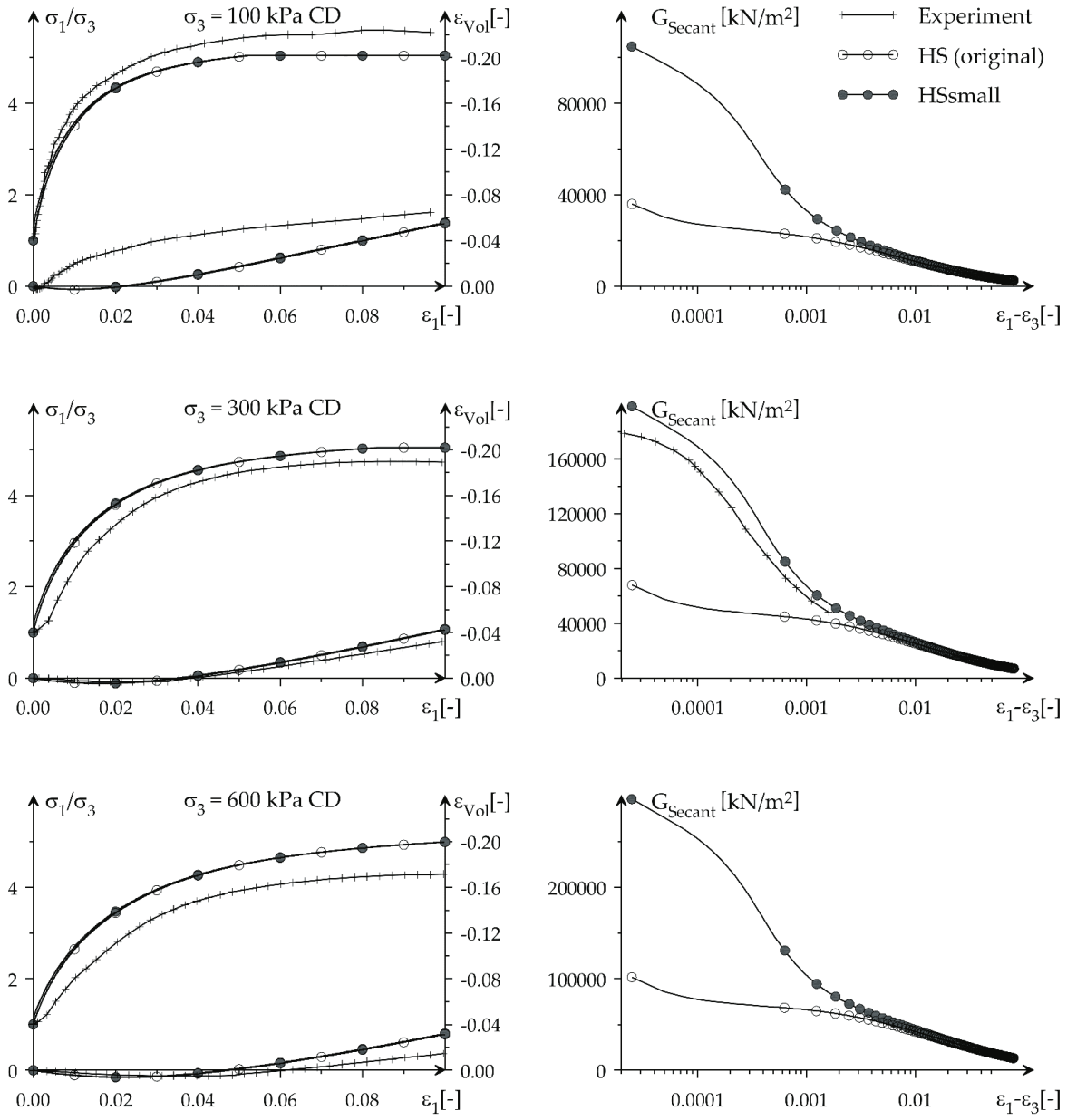


Figure 91: Drained triaxial tests on dense Hostun sand at confining pressures of 100, 300, and 600 kPa. Left: Stress-strain data. Right:Shear modulus reduction

The overall stress-strain data obtained from both models seems almost identical. Only a closer look at the small-strain domain shows a clear difference: The Hardening Soil model with small-strain stiffnessmall follows a S-shaped stiffness reduction curve with much higher initial stiffness than the one of the Hardening Soil model. Generally, both models match the test data at different confining pressures reasonably well.

Figure 91 (on page 197) presents results from a cyclic triaxial test by Rivera & Bard on dense sand. The Hardening Soil model with small-strain stiffnesssmall simulation of the test shows material damping which could not be obtained when simulating the test with the Hardening Soil model. As virgin loading is conducted in

triaxial compression, the unloading sequence in triaxial extension gives some plasticity. Therefore the first unloading / reloading loop is not closed.

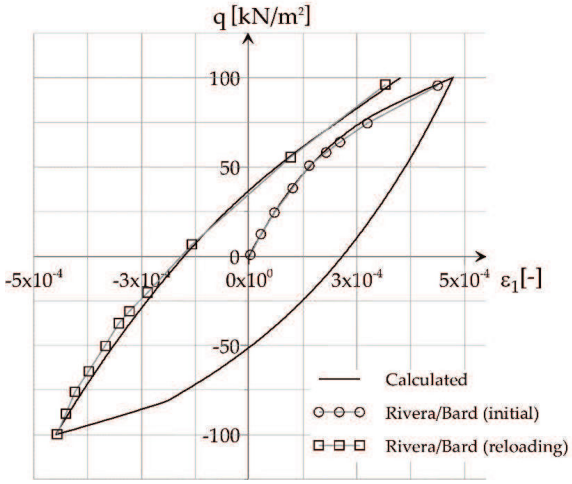


Figure 92: Hysteresis loop in a drained triaxial test on dense Hostun sand. Test data published in Biarez & Hicher (1994).

16.4 Soft Soil Creep model : Undrained triaxial tests at different loading rates

In this section the Soft Soil Creep model (see Soft Soil Creep model (time dependent behaviour) (on page 119)) is utilised for the simulation of clay in an undrained triaxial test, at various strain rates. The model parameters are obtained from test results on Haney Clay and are listed in Table 14 (on page 197) .

The initial isotropic preconsolidation pressure $P_p = 373$ kN/m^2, as reported in the literature, is obtained by specifying a POP of 433 kN/m^2 in the initial conditions.

Table 14: Soft Soil Creep model parameters for Haney clay

Parameter	Symbol	Value	Unit
Modified compression index	λ^*	0.105	-
Modified swelling index	κ^*	0.016	-
Secondary compression index	μ^*	0.004	-
Poisson's ratio	ν_{ur}	0.15	-
Cohesion	c	0.0	[kN/m^2]

Parameter	Symbol	Value	Unit
Friction angle	φ	32	[°]
Dilatancy angle	ψ	0.0	[°]
Coefficient of lateral stress	K_0^{nc}	0.61	[-]
Permeability	k_x , k_y	0.0001	[m/day]
Pre overburden pressure	*POP*	433	[kN/m^2]

Modelling of the triaxial test is as described in Hardening Soil model: Response in drained and undrained triaxial tests (on page 181). However, here, a quarter of the real dimension of the test set-up is simulated (17.5 x 17.5 mm^2). Figure 92 (on page 198) illustrates the model geometry. The specimen surfaces (top and right hand side in Figure 92 (on page 198)) are assumed drained whereas the other boundaries are assumed closed.

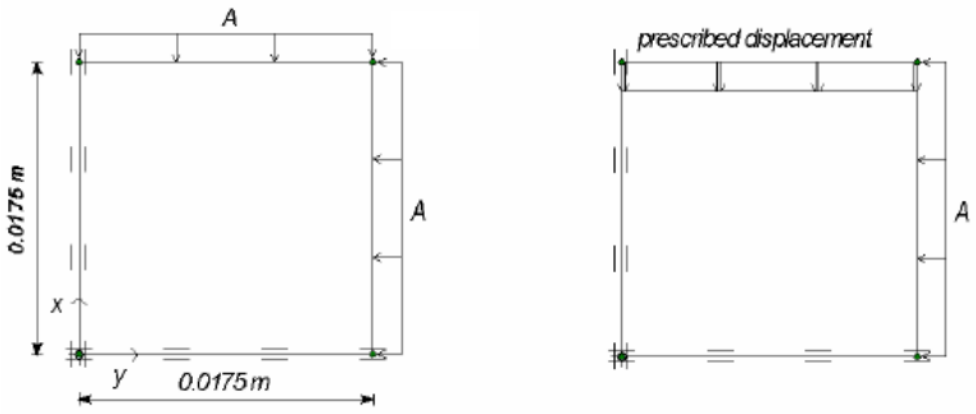


Figure 93: Modelling of triaxial test on Haney clay. Left, Initial configuration. Right, configuration for phases 9 to 11

The *Very coarse* option is selected for the *Element distribution*. To generate the graphs presented further below, mesh points need to be selected. More specifically, a node located at the top model boundary (e.g. with coordinates (0.0175, 0.0175)) is needed to generate Figure 93 (on page 199), while a stress point with coordinates (0.0110, 0.0050) is needed for Figure 94 (on page 199).

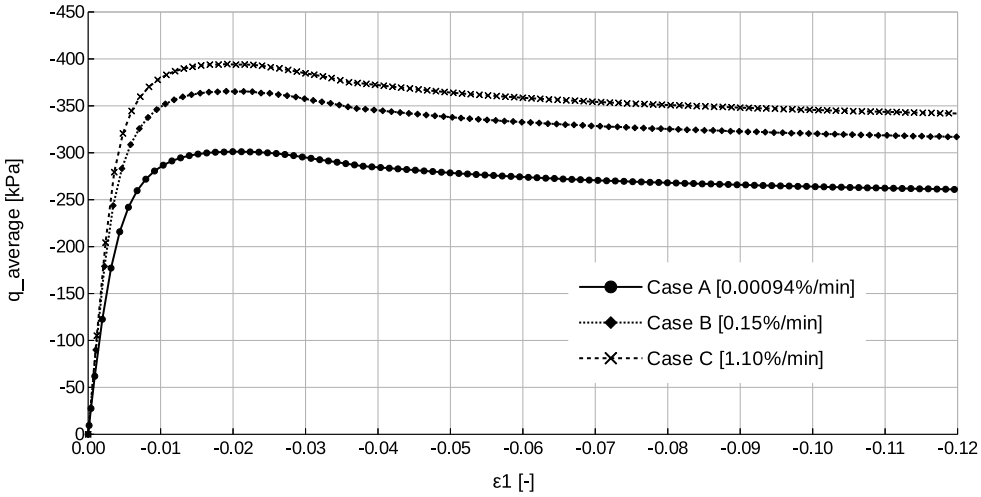


Figure 94: Average deviatoric stress versus axial strain for different strain rates

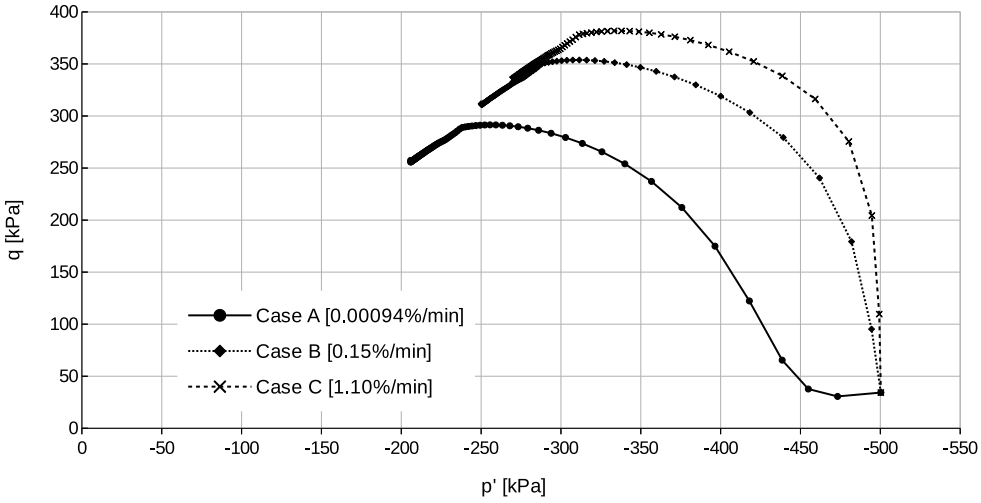


Figure 95: p'- q stress paths for different strain rates for a point at position (0.0110, 0.0050)

In addition to isotropic loading, prescribed displacements are also applied. Both types of loading are simulated using the *Staged construction* option. During isotropic loading, horizontal and vertical loads are applied. The calculation phases for isotropic loading consist of undrained plastic and consolidation analyses.

After the isotropic loading phases, the displacements are reset to zero. The vertical load is deactivated and the prescribed displacement is activated. Rate of loading is simulated by applying prescribed displacements at different velocities. As such, a total of 12% axial strain (2.1 mm, vertical displacement) is applied in 8.865 days (0.00094%/min), 0.0556 days (0.15%/min) and 0.00758 days (1.10%/min) respectively. Each of the prescribed displacement loading phases 9 to 11 starts from the end of the last consolidation phase 8. The calculation scheme is listed in Table 15 (on page 200).

Table 15: Loading scheme for triaxial tests at different loading rates

Phase	Starts from	Calculation type	Top load [kPa]	Side load [kPa]	Displacement [m]	Time interval [day]
1	0	Plastic	-65	-65	Inactive	0.00
2	1	Consolidation	-65	-65	Inactive	0.01
3	2	Plastic	-130	-130	Inactive	0.00
4	3	Consolidation	-130	-130	Inactive	0.01
5	4	Plastic	-260	-260	Inactive	0.00
6	5	Consolidation	-260	-260	Inactive	0.01
7	6	Plastic	-520	-520	Inactive	0.00
8	7	Consolidation	-520	-520	Inactive	0.01
9	8	Plastic	Inactive	-520	0.0021	8.865
10	8	Plastic	Inactive	-520	0.0021	0.0556
11	8	Plastic	Inactive	-520	0.0021	0.00758

The computational results are presented in Figure 93 (on page 199) and Figure 94 (on page 199). Figure 93 (on page 199) illustrates the average deviatoric strain $q_{average}$ versus the principal strain ε_1 for phases 9 to 11. The average deviatoric strain is obtained as:

$$q_{average} = \frac{2F_Y}{R^2} - \sigma_3 \qquad \textit{Eq. [352]}$$

where:

R=0.0175 and σ_3=-520 kN/m^3

In Eq. [352], F_Y is the reaction force against the applied prescribed displacement ($Force_Y$). The principal strain ε_1 is obtained by dividing the vertical displacement u_y of a node located at the top boundary by the height of the model (0.0175 m). The starting point in Figure 93 (on page 199) is deliberately selected to be zero.

Based on Figure 93 (on page 199), it can be seen that the shear strength highly depends on the strain rate; the higher strain rate the higher the shear strength.

Figure 94 (on page 199) shows the p' - q stress paths from the prescribed displacement loading phases. For higher strain rates there is a smaller reduction of the mean effective stress, which allows for larger ultimate deviatoric stress. It should be noted that the stress state is not homogeneous at all, because of the inhomogeneous (excess) pore pressure distribution. This is due to the fact that points close to draining boundaries consolidate faster than points at a larger distance.

In addition to the full tests as described before, the last part of the test can also be done in a simplified way using the **Soil Test** facility. Since the **Soil Test** facility operates on a single stress point, it is not possible to start the

undrained triaxial tests from an inhomogeneous stress state, as considered in the full finite element based model. Instead, we start from an isotropic effective stress of *500* kN/m^2.

Table 16: Input parameters for the Soil Test facility

Input parameter	A(0.00094%/min)	B(0.15%/min)	C(1.10%/min)
Type of test	Triaxial, Undrained	Undrained & Triaxial	Undrained
Direction	Compression	Compression	Compression
Consolidation	Isotropic	Isotropic	Isotropic
Initial effect. stress $\|\sigma_3'\|$	500 kN/m^2	500 kN/m^2	500 kN/m^2
Maximum strain $\|\varepsilon_1\|$	12.0%	12.0%	12.0%
Time Δt	8.865 days	0.0556 days	0.00758 days
Number of steps	200	200	200
|Vert. precons. stress|	433 kN/m^2	433 kN/m^2	433 kN/m^2

16.5 Soft Soil Creep model: Response in one-dimensional compression test

In this section the behaviour of the Soft Soil Creep model is illustrated on the basis of a one-dimensional compression test on clay. Two types of analysis are performed. First, the test is simulated assuming drained conditions in order to demonstrate the logarithmic stress-strain relationship and the logarithmic time-settlement behaviour on the long term (secondary compression). Second, the test is simulated more realistically by including undrained conditions and consolidation. Since the consolidation process depends on the drainage length, it is important to use actual dimensions of the test set-up. In this case an axisymmetric configuration with specimen height of 0.01 m, Figure 95 (on page 202), is used. The material parameters are shown in Table 17 (on page 202). The parameter values are selected arbitrarily, but they are realistic for normally consolidated clay. The vertical preconsolidation stress is fixed at 50 kPa (POP = 50 kPa).

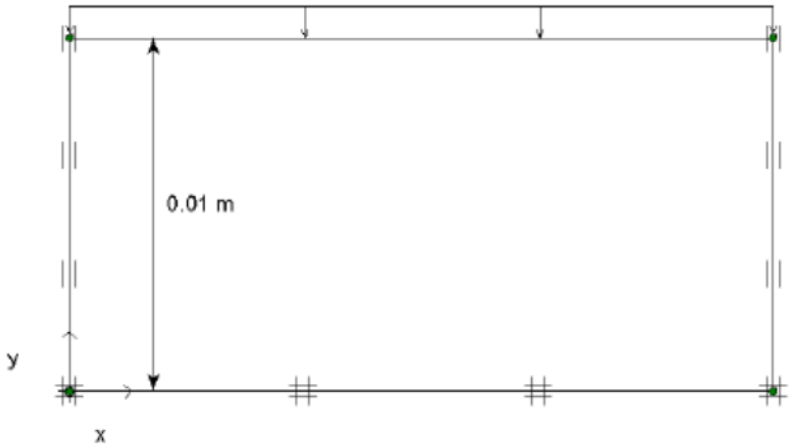


Figure 96: One-dimensional compression test

Table 17: Soft Soil Creep model parameters for one-dimensional compression test

Parameter	Symbol	Value	Unit
Unit Weight	γ	19	kN/m^3
Permeability	k_x, k_y	0.0001	m/day
Modified compression index	λ^*	0.10	-
Modified swelling index	κ^*	0.02	-
Secondary compression index	μ^*	0.005	-
Poisson's ratio	ν_{ur}	0.15	-
Cohesion	c	1.0	kN/m^2
Friction angle	φ	30	°
Dilatancy angle	ψ	0.0	°
Coefficient of lateral stress	K_0^{nc}	0.5	-

16.5.1 *Drained analysis*

In the first analysis successive plastic loading steps are applied using drained conditions. The load is doubled in every step using *Staged construction* with time increments of 1 day. After the last loading step an additional creep period of 100 days is applied. The calculation scheme is listed in Table 18 (on page 203). All calculations are performed with a tolerance of 1%.

Table 18: Calculation scheme for the drained case

Phase	Calculation type	Loading input	Load [kPa]	Time interval [day]	End time [day]
1	Plastic	Staged construction	10	1	1
2	Plastic	Staged construction	20	1	2
3	Plastic	Staged construction	40	1	3
4	Plastic	Staged construction	80	1	4
5	Plastic	Staged construction	160	1	5
6	Plastic	Staged construction	320	1	6
7	Plastic	Staged construction	640	1	7
8	Plastic	Staged construction	640	100	107

16.5.2 *Undrained analysis*

In the second analysis the loading steps are instantaneously applied using undrained conditions. After each loading step a consolidation of 1 day is applied to let the excess pore pressures fully dissipate. After the last loading step, an additional creep period of 100 days is again introduced. The calculation scheme for this analysis is listed in Table 19 (on page 203). All calculations are performed with a reduced tolerance of 1%.

Table 19: Calculation scheme for second analysis

Phase	Calculation type	Loading input	Load [kPa]	Time interval [day]	End time [day]
1	Plastic	Staged construction	10	0	0
2	Consolidation	Staged construction	10	1	1
3	Plastic	Staged construction	20	0	1

Phase	Calculation type	Loading input	Load [kPa]	Time interval [day]	End time [day]
4	Consolidation	Staged construction	20	1	2
5	Plastic	Staged construction	40	0	2
6	Consolidation	Staged construction	40	1	3
7	Plastic	Staged construction	80	0	3
8	Consolidation	Staged construction	80	1	4
9	Plastic	Staged construction	160	0	4
10	Consolidation	Staged construction	160	1	5
11	Plastic	Staged construction	320	0	5
12	Consolidation	Staged construction	320	1	6
13	Plastic	Staged construction	640	0	6
14	Consolidation	Staged construction	640	1	7
15	Consolidation	Staged construction	640	100	107

Figure 96 (on page 205) shows the load-settlement curves of both analyses. It can be seen that, after consolidation, the results of the undrained test match those of the drained test. The influence of the preconsolidation stress can clearly be seen, although the transition between reloading and primary loading is not as sharp as when using the Soft Soil model. In fact, the results presented here are more realistic. The transition is indeed around 50 kPa.

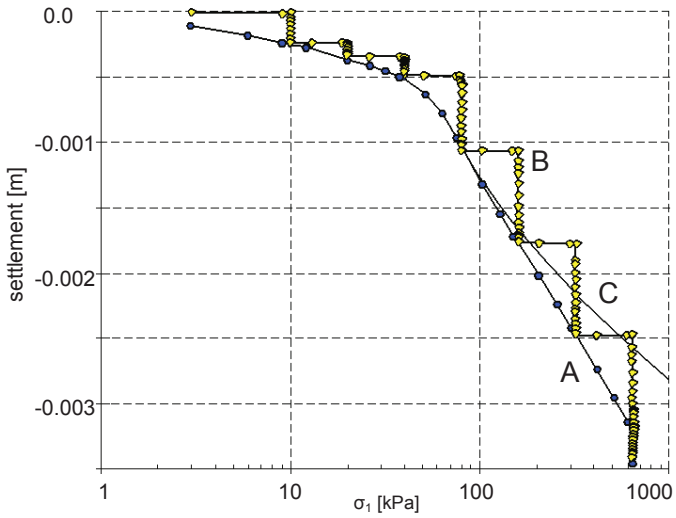


Figure 97: Load-settlement curve of oedometer test with Soft Soil Creep model. A) Transient loading with doubling of loading within one day. B) Instantaneous loading with doubling of load at the beginning of a new day. C) As 'A' using Updated Mesh calculation

From the slope of the primary loading line one can back-calculate the modified compression index $\lambda^* = \Delta \varepsilon_1 / ln(\sigma_1 + \Delta\sigma_1) / \sigma_1 \approx 0.10$. Note that 1 mm settlement corresponds to $\varepsilon_1 = 10\%$. For an axial strain of 30% one would normally use an *Updated mesh* analysis, which has not been done in this simple analysis. If, however, the Soft Soil Creep model would have been used in an *Updated mesh* analysis with axial strains over 15% one would observe a stiffening effect as indicated by line *C* in Figure 96 (on page 205).

Figure 97 (on page 206) shows the time-settlement curves of the drained and the undrained analyses. From the last part of the curve one can back-calculate the secondary compression index $\mu^* = \Delta \varepsilon_1 / ln(\Delta t / t_0) \approx 0.005$ (with $t_0 = 1$ day).

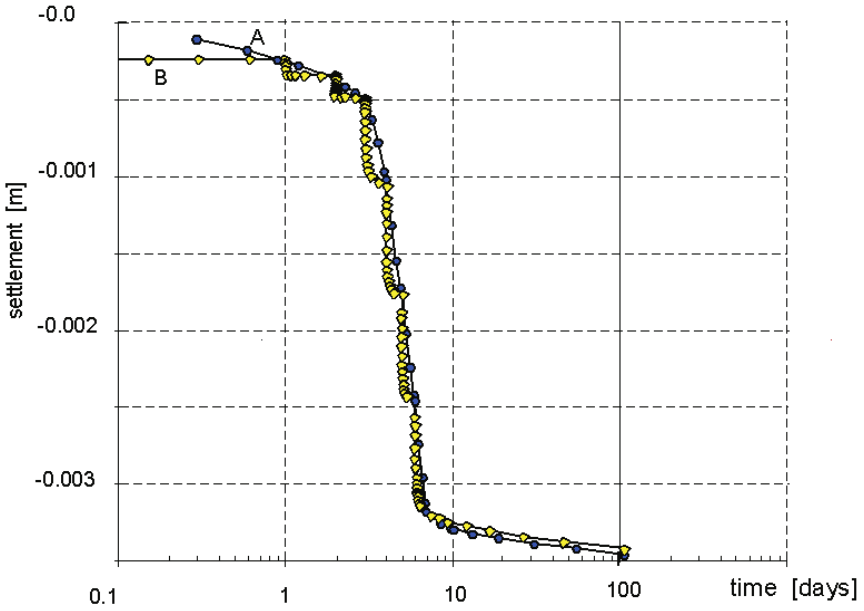


Figure 98: Time-settlement curve of oedometer test with Soft Soil Creep model. A) Transient loading with doubling of loading within one day. B) Instantaneous loading with doubling of load at the beginning of a new day

Another interesting phenomenon is the development of lateral stresses. During primary loading, the lateral stress is determined by K_0^{nc}, appropriate for normally consolidated soil. During unloading, the lateral stress decreases much less than the vertical stress, so that the ratio $\sigma'_{xx} / \sigma'_{yy}$ increases.

To show these effects the calculation is continued after with a new drained unloading phase that starts from phase 7 (see Table 18 (on page 203)) in which the vertical stress is reduced to *-80* kPa.

Figure 98 (on page 206) shows the stress state for two different calculation phases, both at a vertical stress level of 80 kPa. The plot in the left hand side shows the stress state after primary loading. As expected the horizontal stress is found to be approximately *-40* kPa (corresponding to $K_0^{nc} = 0.5$). The plot in the right hand side shows the final situation after unloading down to *-80* kPa. In this case the horizontal stress is decreased from *-320* kPa to approximately *-220* kPa, ($\Delta \sigma'_{xx} = 100$ kPa), i.e, much less than the decrease of the vertical stress ($\Delta\sigma'_{yy} = 560$ kPa). Thus, a situation where σ'_{xx} is larger than σ'_{yy} is obtained.

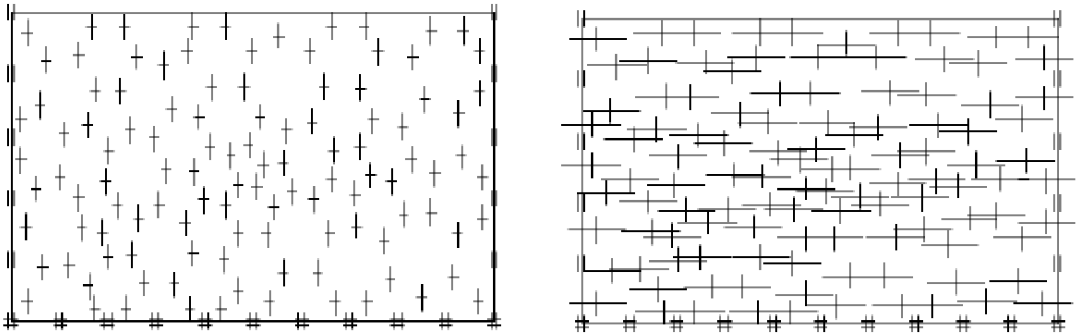


Figure 99: Stress states at vertical stress level of -80 kPa. Left, after primary loading σ 'xx≈ 40 kPa. Right, after unloading from -640 kPa σ 'xx≈ -220 kPaσ '$_{xx}$≈ 40 kPa. Right, after unloading from -640 kPa σ '$_{xx}$≈ -220 kPa

During sudden unloading in a one-dimensional compression test, the behaviour is purely elastic. Hence, the ratio of the horizontal and vertical stress increments can be determined as:

$$\frac{\Delta\sigma'_{xx}}{\Delta\sigma'_{yy}} = \frac{\nu_{ur}}{1 - \nu_{ur}} \qquad \textit{Eq. [353]}$$

It is easy to verify that the results correspond to Poisson's ratio $\nu_{ur} = 0.15$ as listed in Table 13 (on page 194).

16.6 Soft Soil model: Response in isotropic compression test

In this section it will be demonstrated that the Soft Soil model obeys a logarithmic relationship between the volumetric strain and the mean stress in isotropic compression. For this purpose the test set up is simulated as that presented in Figure 73 (on page 182). The vertical load (A) and the horizontal load (B) are simultaneously applied to the same level so that a fully isotropic stress state occurs. The parameters of the Soft Soil model are chosen arbitrarily, but the values are realistic for normally consolidated clay. The parameters are presented in Table 20 (on page 207).

Table 20: Soft Soil model parameters for isotropic compression test

Modified compression index	λ^*	0.1
Modified swelling index	κ^*	0.02
Poisson's ratio	ν_{ur}	0.15
Friction angle	φ	30°
Cohesion	c	1.0 kPa
Normally consolidated K_0	K_0 & K_0^{nc}	0.5

From a stress-free state, the model is isotropically loaded to a mean stress of $p' = 100$ kPa, after which the displacements are reset to zero. As a result, the material becomes 'normally consolidated', i.e., the preconsolidation stress is equivalent to the current state-of-stress. After that, the isotropic pressure is increased to $p' = 1000$ kPa. This loading path is denoted as 'primary loading'. Then, the sample is isotropically ' unloaded' to $p' = 100$ kPa. Finally, the sample is loaded up to $p' = 10000$ kPa. In the last loading path, the maximum preload of 1000 kPa is exceeded. and hence, it consists of two parts: the part of the loading path for which $p' < 1000$ kPa is referred to as 'reloading', and the part of the loading path for $p' > 1000$ kPa consists of further primary loading. The calculation phases are indicated in Table 21 (on page 207).

Table 21: Calculation phases for isotropic compression test on clay

Stage		Initial stress	Final stress
0	Initial situation	-	p^0 = 100 kPa
1	Primary loading	p^0 = 100 kPa	p^1 = 1000 kPa

Stage		Initial stress	Final stress
2	Unloading	p^1 = 1000 kPa	p^2 = 100 kPa
3	Reloading	p^2 = 100 kPa	p^3 = 1000 kPa
4	Primary loading	p^3 = 1000 kPa	p^4 = 10000 kPa

The computational results are presented in Figure 99 (on page 208), which shows the relation between the vertical strain ε_{yy} and the vertical stress σ'_{yy}.

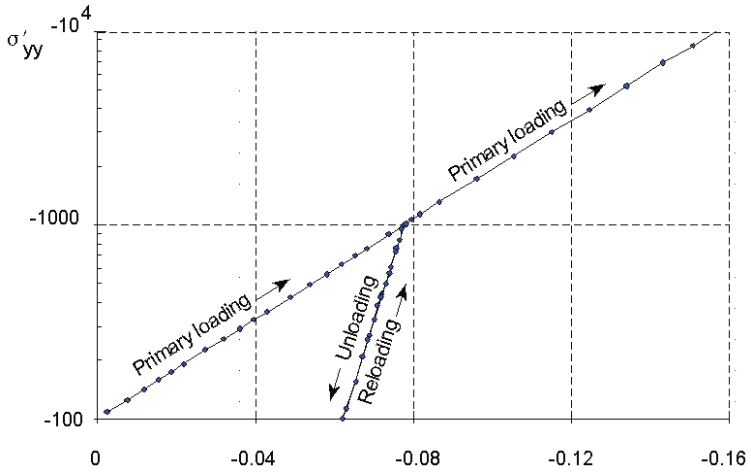


Figure 100: Results of isotropic compression test

The latter quantity is plotted on a logarithmic scale. The plot shows two straight lines, which indicates that there is indeed a logarithmic relation for loading and unloading. The vertical strain is 1/3 of the volumetric strain, ε_v, and the vertical stress is equal to the mean stress, p'. The volumetric strains obtained from the calculation are given in Table 22 (on page 208).

Table 22: Volumetric strains from various calculation phases

Phase	Initial strain	Final strain
0	-	$\varepsilon_v^0 = 0.000$
1	$\varepsilon_v^0 = 0.000$	$\varepsilon_v^1 = -0.235$
2	$\varepsilon_v^1 = -0.235$	$\varepsilon_v^2 = -0.188$
3	$\varepsilon_v^2 = -0.188$	$\varepsilon_v^3 = -0.235$
4	$\varepsilon_v^3 = -0.235$	$\varepsilon_v^4 = -0.471$

From these strains and corresponding stresses, the parameters λ^* and κ^* can be back-calculated using Eq. [229] and Eq. [230].

$$Phase\ 1: \quad \lambda^* = -\frac{\varepsilon_v^1 - \varepsilon_v^0}{ln\left(p^1 / p^0\right)} = \frac{0.235}{ln(1000/100)} = 0.102$$

$$Phase\ 2: \quad \kappa^* = -\frac{\varepsilon_v^2 - \varepsilon_v^1}{ln\left(p^2 / p^1\right)} = \frac{0.188 - 0.235}{ln(100/1000)} = 0.020$$

$$Phase\ 3: \quad \kappa^* = -\frac{\varepsilon_v^3 - \varepsilon_v^2}{ln\left(p^3 / p^2\right)} = \frac{0.235 - 0.188}{ln(1000/100)} = 0.020$$

$$Phase\ 4: \quad \lambda^* = -\frac{\varepsilon_v^4 - \varepsilon_v^3}{ln\left(p^4 / p^3\right)} = \frac{0.471 - 0.235}{ln(10000/1000)} = 0.102$$

The back-calculated values correspond to the input values as given in Table 20 (on page 207).

Note that the Soft Soil model does not include time effects such as in the secondary compression. Such behaviour is included in the Soft Soil Creep model.

16.7 Hardening Soil model and Hardening Soil model with small-strain stiffness: Excavation in Berlin sand

In the previous example, the advantage of the Hardening Soil model's distinct loading and unloading stiffness was highlighted. With those, the calculated excavation heave could be reduced to a more realistic, but in most cases still too high value. In the Berlin excavation example, now the further advantage of considering small-strain stiffness in the analysis is demonstrated.

The working group 1.6 Numerical methods in Geotechnics of the German Geotechnical Society (DGGT) has organised several comparative finite element studies (benchmarks). One of these benchmark examples is the installation of a triple anchored deep excavation wall in Berlin sand. The reference solution by Schweiger (2002) (on page 255) is used here as the starting point for the next validation example: Both, the mesh shown in Figure 100 (on page 210), and the soil parameters given in Table 23 (on page 210) are taken from this reference solution. However, the bottom soil layer 3 defined by Schweiger (2002) (on page 255) is assigned the parameters of layer 2 in the HSsmall analysis. In the reference solution this layer's only purpose is the simulation of small-strain stiffness due to a lack of small-strain stiffness constitutive models back then.

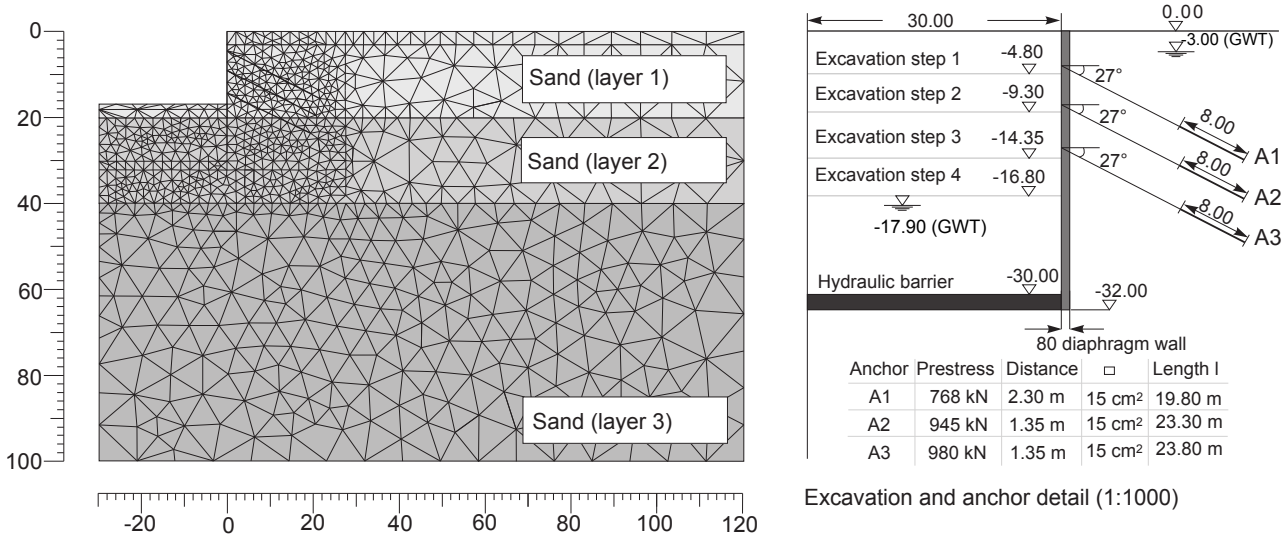


Figure 101: Excavation in Berlin sand: plane strain mesh (left) and geometry detail (right)

Table 23: Hardening Soil model and HS small model parameters for the three sand layers in the excavation project

Parameter	Layer 1	Layer 2	Layer 3	Unit
Unit weight above/ below phreatic level	19 / 20	19 / 20	19 / 20	kN/m^3
E_{50}^{ref} ($p_{ref} = 100$ kPa)	45000	75000	105000	kN/m^2
E_{ur}^{ref} ($p_{ref} = 100$ kPa)	45000	75000	105000	kN/m^2
E_{oed}^{ref} ($p_{ref} = 100$ kPa)	180000	300000	315000	kN/m^2
G_0^{ref} ($p_{ref} = 100$ kPa)	168750	281250	NA	kN/m^2
Shear strain $\mathop{G}_0^{ref}$ ($p_{ref} = 100$ kPa)	0.0002	0.0002	NA	-
Cohesion c	1	1	1	kN/m^2
Friction angle φ	35	38	38	°
Dilatancy angle ψ	5	6	6	°
Poisson's ratio ν_{ur}	0.2	0.2	0.2	-
Power m	0.55	0.55	0.55	-
K_0^{nc}	0.43	0.38	0.38	-

Parameter	Layer 1	Layer 2	Layer 3	Unit
Tensile strength	0	0	0	kN/m^2
Failure ratio	0.9	0.9	0.9	-

Figure 101 (on page 211) shows results from the finite element calculation using the original Hardening Soil model and the Hardening Soil model with small-strain stiffness. The small-strain stiffness formulation in the Hardening Soil model with small-strain stiffness accumulates more settlements right next to the wall, whereas the settlement trough is smaller. The triple anchored retaining wall is deflected less when using the HSsmall model, almost fitting the measured deflection. Calculated excavation heave at the end of excavation is shown in Figure 102 (on page 212) . Compared to the HS results, the heave which is due to elastic unloading, is roughly halved when using the Hardening Soil model with small-strain stiffness.

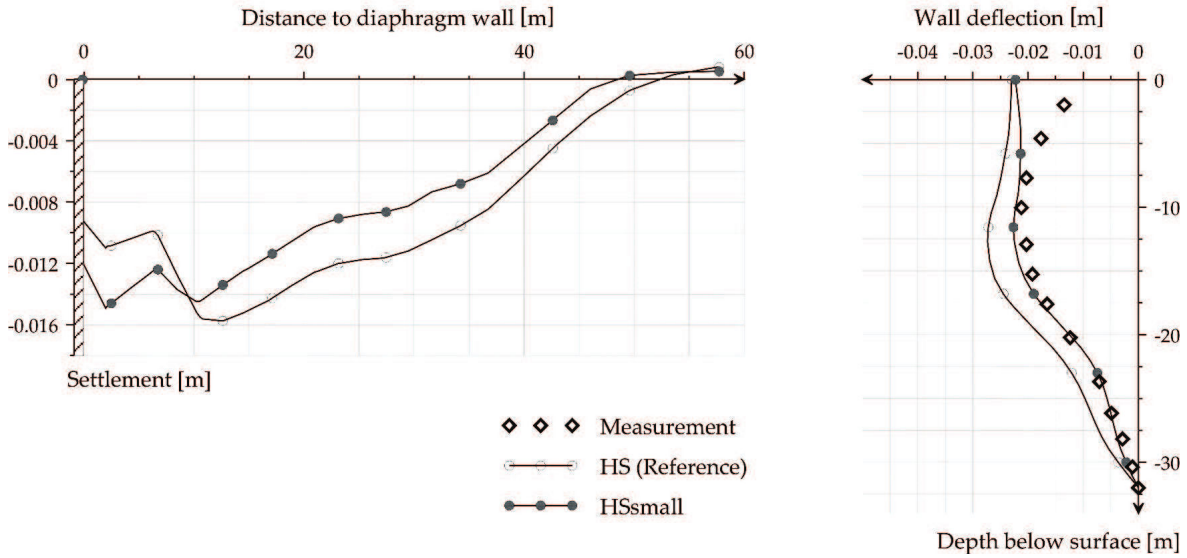


Figure 102: Hardening Soil model and Hardening Soil model with small-strain stiffness predictions versus measured displacements after the final excavation step. Left: Surface settlement trough. Right: Lateral wall deflection.

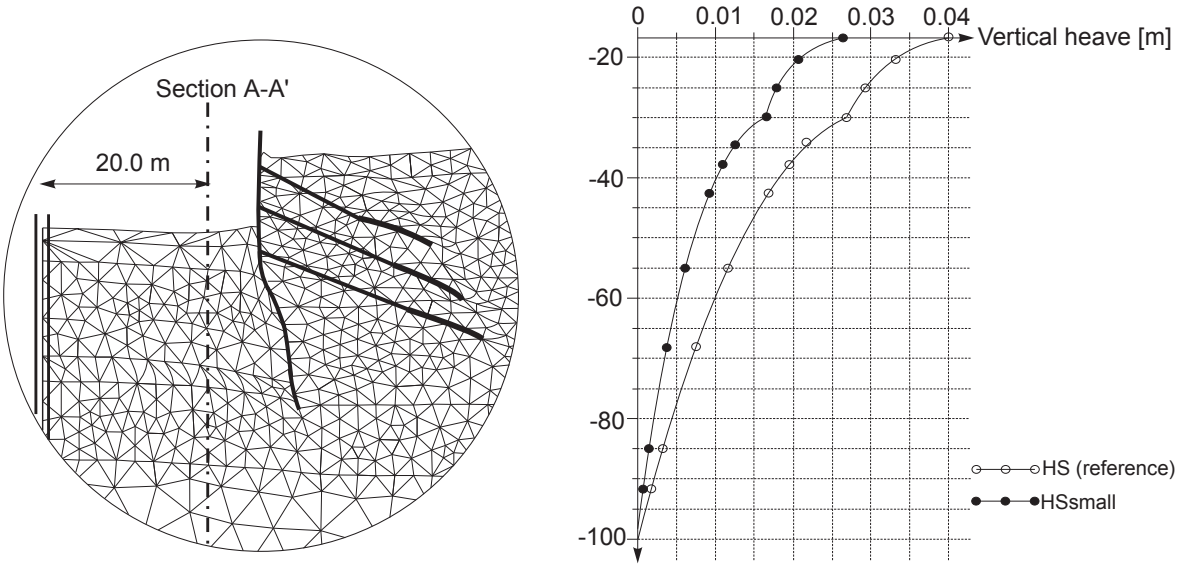


Figure 103: Vertical displacements in the excavation pit at a distance of 10 m from the retaining wall (Section A-A)

17 User-defined soil models

17.1 Introduction

PLAXIS has a facility for user-defined (UD) soil models. This facility allows users to implement a wide range of constitutive soil models (stress-strain-time relationship) in PLAXIS. Such models must be programmed in FORTRAN (or another programming language), then compiled as a Dynamic Link Library (DLL) and then added to the UDSM sub-folder of the PLAXIS program directory.

In principle the user provides information about the current stresses and state variables and PLAXIS provides information about the previous ones and also the strain and time increments. In the material data base of the PLAXIS input program, the required model parameters can be entered in the material data sets.

$\sigma_{ij}^{t+\Delta t}, \kappa^{t+\Delta t}$	Current stresses and state variables.
$\sigma_{ij}^{t}, \kappa^{t}$	Previous stresses and state variables.
$\Delta\varepsilon_{ij}, \Delta t$	strain and time increments

Note:

Please note that the PLAXIS organization cannot be held responsible for any malfunctioning or wrong results due to the implementation and/or use of user-defined soil models.

17.2 Implementation of User Defined (UD) soil Models in calculations program

17.2.1 Main Functionalities UD Models

The PLAXIS calculations program has been designed to allow for UDSM. There are mainly six tasks (functionalities) to be performed in the calculations program:

- *Initialization of state variables*
- *Calculation of constitutive stresses (stresses computed from the material model at certain step)*
- *Return of the state variables*
- *Return of attributes matrix*
- *Creation of effective material stiffness matrix*
- *Creation of elastic material stiffness matrix*

These main tasks (and other tasks) have to be defined by the user in a subroutine called '*User_Mod*'. In this subroutine more than one user-defined soil model can be defined. If a UD soil model is used in an application, the calculation program calls the corresponding task from the subroutine *User_Mod*. To create a UD soil model, the *User_Mod* subroutine must have the following structure:

```
Subroutine      (IDTask, iMod, IsUndr, iStep, iTer, Iel,Int, X, Y, Z, Time0, dTime,
User_mod        Props, Sig0, Swp0, StVar0, dEps, D, Bulk_W, Sig, Swp, StVar, ipl,
                nStat, NonSym, iStrsDep, iTimeDep, iTang, iPrjDir, iPrjLen, iAbort)
```

where

IDTask	=	Identification of the task (1 = Initialise state variables; 2 = Calculate constitutive stresses; 3 = Create effective material stiffness matrix; 4 = Return the number of state variables; 5 = Return matrix attributes (NonSym, iStrsDep, iTimeDep, iTang); 6 = Create elastic material stiffness matrix).
iMod	=	User-defined soil model number (This option allows for more than one UD model, up to 10).
IsUndr	=	Drained condition (IsUndr = 0) or undrained condition (IsUndr = 1). In the latter case, PLAXIS will add a large bulk stiffness for water.
iStep	=	Current calculation step number
iter	=	Current iteration number
Iel	=	Current element number
Int	=	Current local stress point number (1..3 for 6-noded elements, or 1..12 for 15-noded elements)
X,Y,Z	=	Global coordinates of current stress point
Time0	=	Time at the start of the current step
dTime	=	Time increment of current step
Props	=	Array(1..50) with User-defined model parameters for the current stress point
Sig0	=	Array(1..20) with previous (= at the start of the current step) effective stress components of the current stress point and some other variables (σ'^0_{xx}, σ'^0_{yy}, σ'^0_{zz}, σ'^0_{xy}, σ'^0_{yz}, σ'^0_{zx}, p_{steady}, $\Sigma\ Mstage^0$, $\Sigma\ Mstage$, Sat, Sat^0, Suc, Suc^0, $\Sigma\ Msf^0$, $\Sigma\ Msf$, X_i, SatRes, Temp, UnfrozenW, *0*). In 2D calculations σ_{yz} and σ_{zx} should be zero.
Swp0	=	Previous excess pore pressure of the current stress point}
StVar0	=	Array(1..nStat) with previous values of state variables of the current stress point
dEps	=	Array(1..12) with strain increments of the current stress point in the current step ($\Delta\varepsilon_{xx}$, $\Delta\varepsilon_{yy}$, $\Delta\varepsilon_{zz}$, $\Delta\gamma_{xy}$, $\Delta\gamma_{yz}$, $\Delta\gamma_{zx}$, ε_{xx}^0, ε_{yy}^0, ε_{zz}^0, γ_{xy}^0, γ_{yz}^0, γ_{zx}^0). In 2D calculations $\Delta\gamma_{yz}$, $\Delta\gamma_{zx}$, γ_{yz}^0 and γ_{zx}^0 should be zero. In \twod this array may also contain non-local strains. Contact Plaxis for more details.
D	=	Effective material stiffness matrix of the current stress point (1..6, 1..6)

Bulk_W	=	Bulk modulus of water for the current stress point (for undrained calculations and consolidation)
Sig	=	Array (1..6) with resulting constitutive stresses of the current stress point (σ'_{xx}, σ'_{yy}, σ'_{zz}, σ'_{xy}, σ'_{yz}, σ'_{zx})
Swp	=	Resulting excess pore pressure of the current stress point
StVar	=	Array(1..nStat) with resulting values of state variables for the current stress point
ipl	=	Plasticity indicator: 0 = no plasticity, 1 = Mohr-Coulomb (failure) point; 2 = Tension cut-off point, 3 = Cap hardening point, 4 = Cap friction point, 5 = Friction hardening point, 6 = Plotting liquefaction indicators.
nStat	=	Number of state variables (unlimited)
NonSym	=	Parameter indicating whether the material stiffness matrix is non-symmetric (NonSym = 1) or not (NonSym = 0) (required for matrix storage and solution).
iStrsDep	=	Parameter indicating whether the material stiffness matrix is stress-dependent (iStrsDep = 1) or not (iStrsDep = 0).
iTimeDep	=	Parameter indicating whether the material stiffness matrix is time-dependent (iTimeDep = 1) or not (iTimeDep = 0).
iTang	=	Parameter indicating whether the material stiffness matrix is a tangent stiffness matrix, to be used in a full Newton-Raphson iteration process (iTang = 1) or not (iTang = 0).
iPrjDir	=	Project directory (for debugging purposes)
iPrjLen	=	Length of project directory name (for debugging purposes)
iAbort	=	Parameter forcing the calculation to stop (iAbort = 1).

In the above, 'increment' means 'the total contribution within the current step' and *not* per iteration. 'Previous' means 'at the start of the current step', which is equal to the value at the end of the previous step.

In the terminology of the above parameters it is assumed that the standard type of parameters is used, i.e. parameters beginning with the characters A-H and O-Z are double (8-byte) floating point values and the remaining parameters are 4-byte integer values.

The parameters `IDTask` to `dEps` and `iPrjDir` and `iPrjLen` are input parameters; The values of these parameters are provided by PLAXIS and can be used within the subroutine. These input parameters should not be modified (except for `StVar0` in case `IDTask`= 1). The parameters `D` to `iTang` and `iAbort` are output parameters. The values of these parameters are to be determined by the user. In case `IDTask` = 1, `StVar0` becomes output parameter.

The user subroutine should contain program code for listing the tasks and output parameters `IDTask`= 1 to 6). After the declaration of variables, the *User_Mod* subroutine must have the following structure (here specified in pseudo code):

```
Case IDTask of
            1 Begin
                                { Initialise state Variable StVar }
                    End
            2 Begin
                                { Calculate constitutive stresses Sig (and Swp) }
                    End
            3 Begin
                                { Create effective material stiffness matrix D }
                    End
            4 Begin
                                { Return the number of state variables nStat }
```

```
                End
          5 Begin
                                { Return matrix attributes NonSym, iStrsDep, iTimeDep }
                End
          6 Begin
                                { Create elastic material stiffness matrix De }
                End
End Case
```

If more than one UD model is considered, distinction should be made between different models, indicated by the UD model number `iMod`.

Initialise state variables (`IDTask = 1`)

State variables (also called the hardening parameters) are, for example, used in hardening models to indicate the current position of the yield loci. The update of state variables is considered in the calculation of constitutive stresses based on the previous value of the state variables and the new stress state. Hence, it is necessary to know about the initial value of the state variables, i.e. the value at the beginning of the calculation step. Within a continuous calculation phase, state variables are automatically transferred from one calculation step to another. The resulting value of the state variable in the previous step, StVar, is stored in the output files and automatically used as the initial value in the current step, StVar0. When starting a new calculation phase, the initial value of the state variables is read from the output file of the previous calculation step and put in the StVar0 array. In this case it is not necessary to modify the StVar0 array.

However, if the previous calculation step does not contain information on the state variables (for example in the very first calculation step), the StVar0 array would contain zeros. For this case the initial value has to be calculated based on the actual conditions (actual stress state) at the beginning of the step. Consider, for example, the situation where the first state variable is the minimum mean effective stress, p' (considering that compression is negative). If the initial stresses have been generated using the K_0-procedure, then the initial effective stresses are non-zero, but the initial value of the state variable is zero, because the initialization of this user-defined variable is not considered in the K_0-procedure. In this case, part 1 of the user subroutine may look like:

```
1  Begin
    { Initialise stage variables StVar()}
    p = (SIg0[1] + Sig0[2] + Sig0[3]) /3.0
    StVar0[1] = Min(StVar0[1], p)
        End
```

Calculate constitutive stresses (`IDTask = 2`)

This task constitutes the main part of the user subroutine in which the stress integration and correction are performed according to the user-defined soil model formulation. Let us consider a simple example using a linear elastic D-matrix as created under IDTask = 3.

In this case the stress components, Sig, can directly be calculated from the initial stresses, Sig0, the material `stiffness` matrix, D, and the strain increments, dEps: Sig[i]= Sig0[i] + Σ(D[i, j]*dEps[j]). In this case, part 2 of the user subroutine may look like:

```
2  Begin
    {    Calculate constitutive stresses Sig (and Swp)    }
     For    i=1    to    6    do
            Sig[i]    =    Sig0[i]
            For j=1    to    6    do
                        Sig[i]    =    Sig[i]    +    D[i,j]*dEps[j]
```

```
            End    for{j}
     End    for {i}
    End
```

Create effective material stiffness matrix (`IDTask = 3`)

The material stiffness matrix, D, may be a matrix containing only the elastic components of the stress-strain relationship (as it is the case for the existing soil models in PLAXIS), or the full elastoplastic material stiffness matrix (tangent stiffness matrix). Let us consider the very simple example of Hooke's law of isotropic linear elasticity. There are only two model parameters involved: Young's modulus, E, and Poisson's ratio, *v*. These parameters are stored, respectively, in position 1 and 2 of the model parameters array, Props(1..50). In this case, part 3 of the user subroutine may look like:

```
3    Begin
      {    Calculate effective material stiffness matrix D    }
      E    =    Props[1]
      v    =    Props[2]
      G    =    0.5*E/(1.0+v)
      Fac    =    2*G/(1.0-2*v){    make sure that v<0.5!!}
      Term1    =    Fac*(1-v)
      Term2    =    Fac*v
      D[1,1]    =    Term1
      D[1,2]    =    Term2
      D[1,3]    =    Term2
      D[2,1]    =    Term2
      D[2,2]    =    Term1
      D[2,3]    =    Term2
      D[3,1]    =    Term2
      D[3,2]    =    Term2
      D[3,3]    =    Term1
      D[4,4]    =    G
      D[5,5]    =    G
      D[6,6]    =    G
    End
```

(By default, D will be initialised to zero, so the remaining terms are still zero; however, it is a good habit to explicitly define zero terms as well.)

If undrained behaviour is considered (`IsUndr = 1`), then a bulk stiffness for water (`Bulk_W`) must be specified at the end of part 3. After calling the user subroutine with `IDTask = 3` and `IsUndr = 1`, PLAXIS will automatically add the stiffness of the water to the material `stiffness` matrix `D` such that: D[*i*=1..3, *j*=1..3] = D[*i*, *j*]+ Bulk_W. If `Bulk_W` is not specified, PLAXIS will give it a default value of 100*Avg(D[*i*=1..3, *j*=1..3]).

Return the number of state variables (`IDTask = 4`)

This part of the user subroutine returns the parameter `nStat`, i.e. the number of state variables. In the case of just a single state parameter, the user subroutine should look like:

```
4  Begin
  { Return the number of state variables nStat }
  nStat = 1
 End
```

Return matrix attributes (`IDTask = 5`)

The material stiffness matrix may be stress-dependent (such as in the Hardening Soil model) or time-dependent (such as in the Soft Soil Creep model). When using a tangent stiffness matrix, the matrix may even be non-symmetric, for example in the case of non-associated plasticity. The last part of the user subroutine is used to initialize the matrix attributes in order to update and store the global stiffness matrix properly during the calculation process. For the simple example of Hooke's law, as described earlier, the matrix is symmetric and neither stress- nor time-dependent. In this case the user subroutine may be written as:

```
5    Begin
  {    Return the matrix attributes NonSym, IStrsDep,    }
     {    iTimeDep, iTang    }
     NonSym    =    0
     iStrsDep    =    0
        iTimeDep    =    0
        iTang    =    0
    End
```

For `NonSym = 0` only half of the global stiffness matrix is stored using a profile structure, whereas for `Nonsym` = 1 the full matrix profile is stored.

For `iStrsDep` = 1 the global stiffness matrix is created and decomposed at the beginning of each calculation step based on the actual stress state (modified Newton-Raphson procedure).

For `iTimeDep` = 1 the global stiffness matrix is created and decomposed every time when the time step changes.

For `iTang` = 1 the global stiffness matrix is created and decomposed at the beginning of each iteration based on the actual stress state (full Newton-Raphson procedure; to be used in combination with `iStrsDep`=1).

Create elastic material stiffness matrix (IDTask = 6)

The elastic material stiffness matrix, D^e, is the elastic part of the effective material stiffness matrix as described earlier.

In the case that the effective material stiffness matrix was taken to be the elastic stiffness matrix, this matrix may just be adopted here. However in the case that an elastoplastic or tangent matrix was used for the effective stiffness matrix, then the matrix to be created here should only contain the elastic components.

The reason that an elastic material stiffness matrix is required is because PLAXIS calculates the current relative global stiffness of the finite element model as a whole (CSP = Current Stiffness Parameter). The CSP parameter is defined as:

$$CSP = \frac{Total\ work}{Total\ elastic\ work} \qquad Eq.\ [354]$$

The elastic material stiffness matrix is required to calculate the total elastic work in the definition of the CSP. The CSP equals unity if all the material is elastic whereas it gradually reduces to zero when failure is approached.

The CSP parameter is used in the calculation of the global error. The global error is defined as:

$$Global\ error = \frac{|\ unbalance\ force\ |}{|\ currently\ activated\ load\ | + CSP \cdot |\ previously\ activated\ load\ |} \qquad Eq.\ [355]$$

The unbalance force is the difference between the external forces and the internal reactions. The currently activated load is the load that is being activated in the current calculation phase, whereas the previously

activated load is the load that has been activated in previous calculation phases and that is still active in the current phase.

Using the above definition for the global error in combination with a fixed tolerated error results in an improved equilibrium situation when plasticity increases or failure is approached. The idea is that a small out-of-balance is not a problem when a situation is mostly elastic, but in order to accurately calculate failure state, safety factor or bearing capacity, a stricter equilibrium condition must be adopted.

Part 6 of the user subroutine looks very similar to part 3, except that only elastic components are considered here. It should be noted that the same variable D is used to store the elastic material stiffness matrix, whereas in Part 3 this variable is used to store the effective material stiffness matrix.

```
6    Begin
      {    Create elastic material stiffness matrix D    }
      D[1,1]
      D[1,2]
      D[1,3]
      ....
      D[6,6]
  End
```

17.2.2 Using predefined subroutines from the source code

In order to simplify the creation of user subroutines, a number of FORTRAN subroutines and functions for vector and matrix operations are available in the source code (to be included in the file with the user subroutine). The available subroutines may be called by `User_Mod` subroutine to shorten the code. An overview of the available subroutines is given in Modelling of embedded structures (on page 267).

17.2.3 Definition of user-interface functions

In addition to the user-defined model itself it is possible to define functions that will facilitate its use within the PLAXIS user-interface. If available, PLAXIS Input will retrieve information about the model and its parameters using the procedures described hereafter.

```
procedure GetModelCount(var C:longint) ;
```

where

C = number of models (return parameter)

This procedure retrieves the number of models that have been defined in the DLL. PLAXIS assumes that model IDs are successive starting at model ID = 1.

```
procedure GetModelName(var iModel : longint;
                                                    var Name    :    shortstring)    ;
```

where

iModel = User-defined soil model number to retrieve the name for (input parameter)}

Name = Model name (return parameter)

This procedure retrieves the names of the models defined in the DLL.

```
procedure GetParamCount(var iModel    : longint; var C: longint)    ;
```

where

iModel	=	User-defined soil model number (input parameter)
C	=	number of parameters for the specified model (return parameter)

This procedure retrieves the parameter name of a specific model.

```
Procedure GetParamName(var iModel,iParam : longint;
                                                    var Name    :    shortstring);
```

where

iModel	=	User-defined soil model number (input parameter)
iParam	=	Parameter number (input parameter)
Name	=	parameter name (return parameter)

This procedure retrieves the parameter name of a specific parameter.

```
Procedure GetParamUnit(var iModel,iParam : longint;
                                                    var Units : shortstring)
```

where

iModel	=	User-defined soil model number (input parameter)
iParam	=	Parameter number (input parameter)
Units	=	Parameter units (return parameter)

This procedure retrieves the parameter units of a specific parameter. Since the chosen units are dependent on the units of length, force and time chosen by the user the following characters should be used for defining parameter units:

'L' or 'l' for units of length 'F' or 'f' for units of force 'T' or 't' for units of time.

For model names, model parameter names and model parameter units special characters can be used for indicating subscript, superscript or symbol font (for instance for Greek characters).

^	From here characters will be superscript
_	From here characters will be subscript
@	From here characters will be in symbol font
#	Ends the current superscript or subscript.

Pairs of '^..#','_...#' and '@...#' can be nested.

For example:

A UD model parameter uses the oedometer stiffness as parameter. The parameter name can be defined as 'E_oed#' and its units as 'F/L^2#'.

When defining a unit containing one of the letters 'l', 'f' or 't', like ' cal/mol', these letters will be replaced by the unit of length, the unit of force or the unit of time respectively. To avoid this, these letters should be preceded by a backslash. For example 'cal/mol' should be defined as ' ca\l/mo\l' to avoid getting 'cam/mom'.

The state variables to be displayed in the Output program can be defined.

```
procedure GetStateVarCount(var iModel : longint; var C :longint) ;
```

where

iModel	=	User-defined soil model number (input parameter)
C	=	number of state variables for the specified model (return parameter)

This procedure retrieves the number of state variables of a specific model.

```
procedure GetStateVarName(var iModel,iParam : longint;

  var Name : shortstring);
```

where

iModel	=	Used-defined soil model number (input parameter)
iParam	=	Parameter number (input parameter)
Name	=	Parameter name (return parameter)

This procedure retrieves the state parameter name of a specific parameter.

```
Procedure GetStateVArUnit(var iModel,iParam : longint;

  var Units : shortstring) ;
```

where

iModel	=	User-defined soil model number (input parameter)
iParam	=	Parameter number (input parameter)
Units	=	Parameter units (return parameter)

This procedure retrieves the state parameter units of a specific parameter.

All procedures are defined in Pascal but equivalent procedures can be created, for instance in a Fortran programming language. Please make sure that the data format of the parameters in the subroutine headers is identical to those formulated before. For instance, the procedures mentioned above use a “shorstring” type; a“ shortstring” is an array of 256 characters where the first character contains the actual length of the shortstring contents. Some programming languages only have null-terminated strings; in this case it may be necessary to use an array of 256 bytes representing the ASCII values of the characters to return names and units. An example of Fortran subroutines is included in the software package.

17.2.4 Compiling the user subroutine

This is updated. Please check @@ The user subroutine `User_Mod` has to be compiled into a DLL file using an appropriate compiler. Note that the compiler must have the option for compiling DLL files. Below are examples for two different FORTRAN compilers. It is supposed that the user subroutine `User_Mod` is contained in the file USRMOD.FOR.

After creating the user subroutine `User_Mod`, a command must be included to export data to the DLL. 64-bit compiler must be used.

The following statement has to be inserted in the subroutine just after the declaration of variables:

- Using GNU Fortran:
  ```
  !DEC$ATTRIBUTES DLLExport :: User_Mod
  ```
- Using Intel Visual Fortran:
  ```
  !DEC$ ATTRIBUTES DLLExport,StdCall,Reference :: User_Mod
  ```

In order to compile the USRMOD.FOR into a DLL file, the following command must be executed:

- Using GNU Fortran:

```
gfortran USRMOD.FOR -o usermod64.dll -shared -fno-underscoring -static
```

- Using Intel Visual Fortran:

```
ifort /winapp USRMOD.FOR DFUsrLib.lib /dll
```

In all cases USRMOD64.DLL file will be created. It can be renamed to 'any64' .dll. This file should be placed in the **usdm** folder under the PLAXIS program directory, thereafter it can be used together with the existing PLAXIS calculations program (PLASW.EXE in PLAXIS 2D or PLASW3DF.EXE in PLAXIS 3D). Once the User-defined Soil Model is used, PLAXIS will execute the commands as listed in the USRMOD64.DLL file.

17.2.5 Debugging possibilities

When making computer programs, usually some time is spent to 'debug' earlier written source code. In order to be able to effectively debug the user subroutine, there should be a possibility for the user to write any kind of data to a file. Such a 'debug-file' is not automatically available and has to be created in the user subroutine.

After the debug-file is created, data can be written to this file from within the user subroutine. This can be done by using, for example, the availably written subroutines (Fortran subroutines for User-defined soil models (on page 269)).

17.3 Input of UD model parameters via user-interface

Input of the model parameters for user-defined soil models can be done using the PLAXIS material data base. In fact, the procedure is very similar to the input of parameters for the existing PLAXIS models.

When creating a new material data set for soil and interfaces in the material data base, a window appears with six tabsheets: **General**, **Parameters**, **Groundwater**, **Thermal**, **Interfaces**, **Initial** Figure 103 (on page 223). A user-defined model can be selected from the *Material model* combo box in the **General** tabsheet.

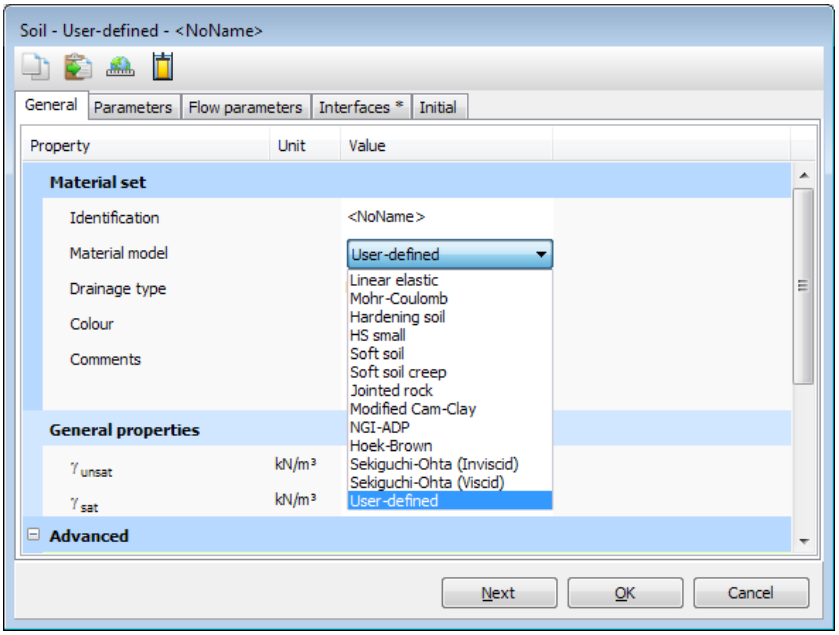


Figure 104: Selection Window. Selection of user-defined soil models

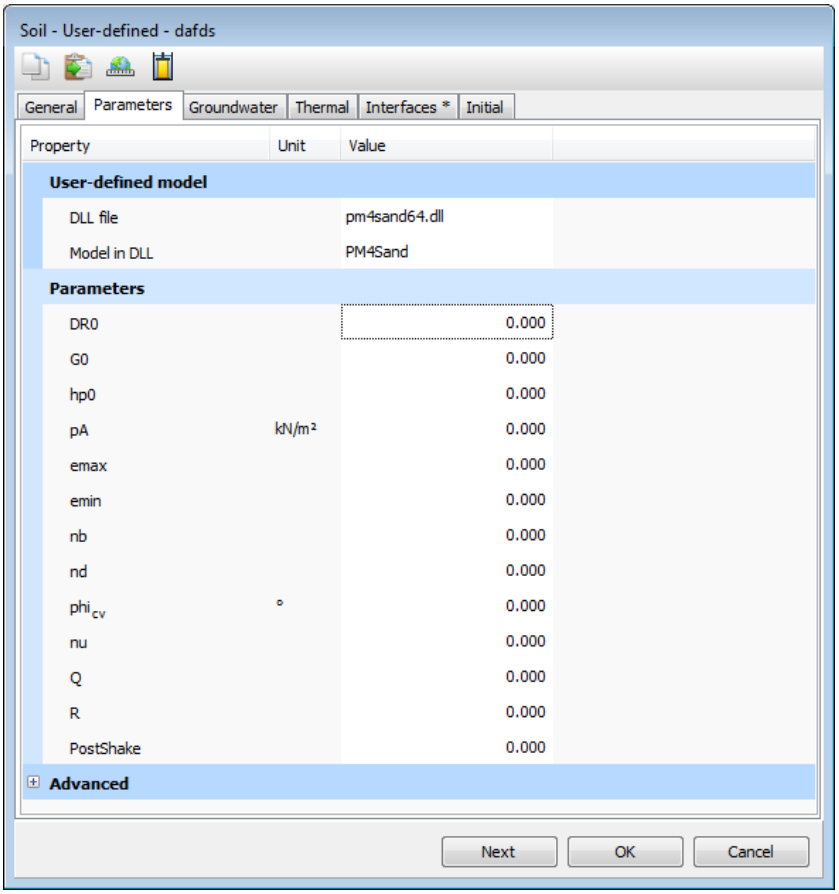


Figure 105: Selection window. Input of parameters

After inputting general properties, the appropriate UD model can be chosen from the available models that have been found by PLAXIS Input.

The **Parameters** tabsheet shows two combo boxes; the top combo box lists all the DLLs that contain valid UD models and the next combo box shows the models defined in the selected DLL. Each UD model has its own set of model parameters, defined in the same DLL that contains the model definition.

When an available model is chosen PLAXIS will automatically read its parameter names and units from the DLL and fill the parameter table below.

17.3.1 Interfaces

The **Interfaces** tabsheet, Figure 105 (on page 224), contains the material data for interfaces.

Normally, this tabsheet contains the R_{inter} parameter. For user-defined soil models the interface tabsheet is slightly different and contains the interface oedometer modulus, E_{oed}^{ref}, and the interface strength parameters c_{inter},φ_{inter} and ψ_{inter}. Hence, the interface shear strength is directly given in strength parameters instead of using a factor relating the interface shear strength to the soil shear strength, as it is the case in PLAXIS models.

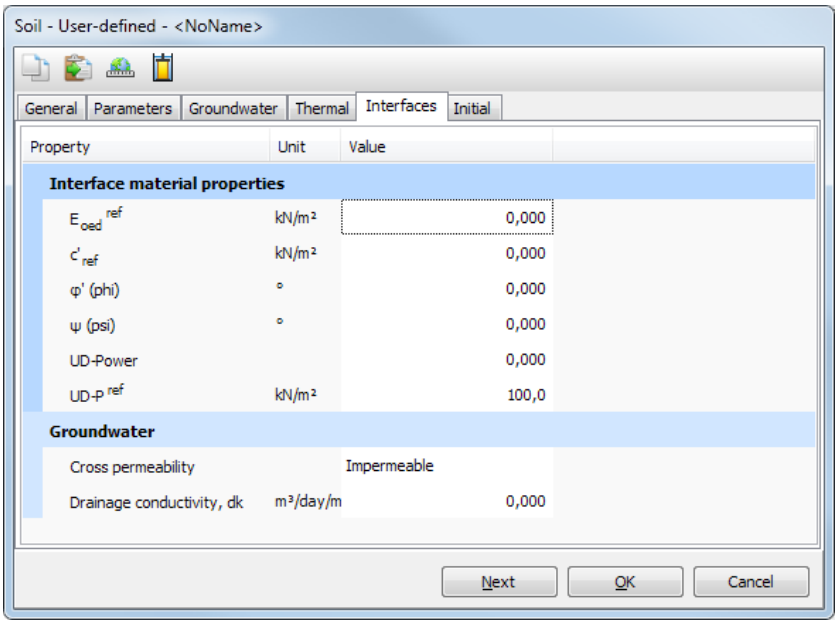


Figure 106: Interface tabsheet

In addition, two parameters are included to enable stress-dependency of the interface stiffness according to a power law formulation:

$$E_{oed}(\sigma_n^{'}) = E_{oed}^{ref}\left(\frac{\sigma_n^{'}}{UD\text{-}P^{ref}}\right)^{UD\text{-}Power} \qquad Eq.\ [356]$$

where

$UD\text{-}Power$	=	Rate of stress dependency of the interface stiffness
$UD\text{-}P^{ref}$	=	Reference stress level (usually 100 kN/m^2)
σ'_n	=	Effective normal stress in the interface stress point.

After having entered values for all parameters, the data sets can be assigned to the corresponding soil clusters, in a similar way as for the existing material models in PLAXIS. The user-defined parameters are transmitted to

the calculation program and appear for the appropriate stress points as Props(1..50) in the `User_Mod` subroutine.

18 Structural Behaviour

18.1 Anchors

The elastic behaviour of an anchor involves only a relationship between axial force N and displacement (elongation) u of the form:

$$N = \frac{EA}{L}U \qquad Eq.\ [357]$$

The anchor stiffness EA is defined by the user based on the material stiffness E and cross section A.

In case of elastoplastic behaviour of the anchor the maximum tension force is bound by $F_{max,tens}$ and the maximum compression force is bound by $F_{max,comp}$.

18.2 3D Beams

The local system of axes of a beam element is such that the first axis corresponds with the axial beam direction. The second and third axis are always perpendicular to the beam axis.

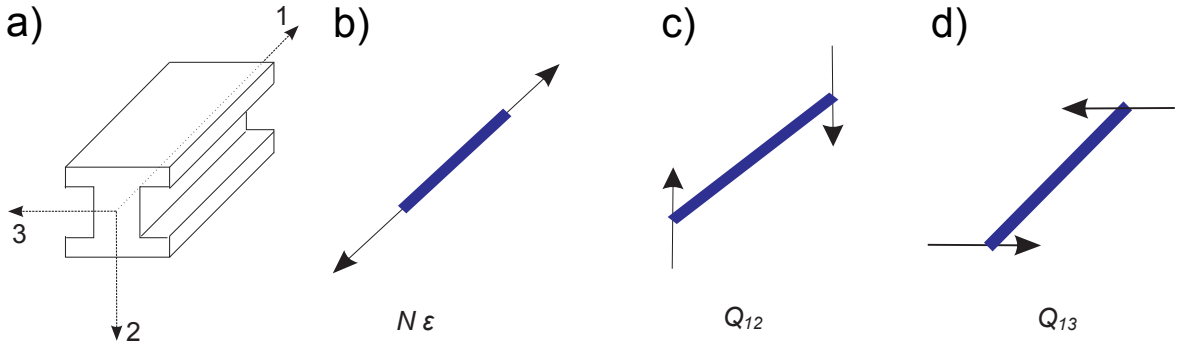


Figure 107: Axial force and shear forces. a- Local axes. b- Axial force N. c- Shear force Q12. d-Shear force Q13Q_{12}. d-Shear force Q_{13}

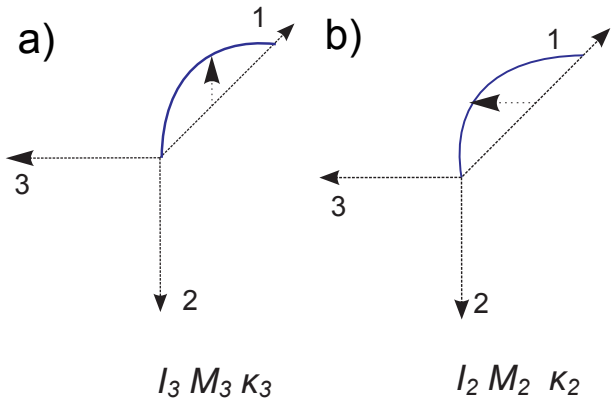


Figure 108: Bending moments. a- Bending moment M_3. b- Bending moment M_2

Elastic behaviour of beam elements is defined by the following parameters:

A	Beam cross section area
E	Young's modulus in axial direction
I_2	Moment of inertia against bending around the second axis
I_3	Moment of inertia against bending around the third axis

The relationships between the different force components and the strain / gradient / curvature components are defined as:

$$\begin{aligned} N &= EA\varepsilon \\ Q_{12} &= kGA\gamma_{12} \\ Q_{13} &= kGA\gamma_{13} \\ M_2 &= EI_2\kappa_2 \\ M_3 &= EI_3\kappa_3 \end{aligned} \qquad \textit{Eq. [358]}$$

In which k is the shear correction factor, which is taken as 5/6. The shear modulus is taken as $G = \frac{1}{2}E$.

When plasticity is considered, the maximum bending moment M_p in the local direction i and the maximum normal force N_p are calculated as:

$$N_{p,eq} = A_{eq}\sigma_{y,eq} \qquad \textit{Eq. [359]}$$

$$M_{p,i,eq} = W_{i,eq}\sigma_{y,eq} \qquad \textit{Eq. [360]}$$

where i is the index number for the selected local direction where plasticity can occur (i.e. *Local direction 2* or *Local direction 3*), $\sigma_{y,eq}$ is the equivalent yield stress, $W_{i,eq}$ is the equivalent plastic section modulus in the i local direction, A_{eq} is the equivalent area.

Based on the input parameters A, I_2, I_3 and σ_y, the equivalent properties are calculated:

$$h_{i,eq} = \sqrt{12\frac{I_i}{A}} \qquad \textit{Eq. [361]}$$

$$A_{eq} = h_{2,eq} h_{3,eq} \qquad \textit{Eq. [362]}$$

$$W_{i,eq} = \frac{\sqrt{3}}{6} A_{eq} h_{i,eq} \qquad \textit{Eq. [363]}$$

The maximum bending moments are given in units of force times length. The maximum axial force is computed in units of force. By default the maximum moment is set to $1 \cdot 10^{15}$ units if the material type is set to elastic (the default setting).

Bending moments and axial forces are calculated at the stress points of the beam elements. When the yield function is violated, stresses are redistributed according to the theory of plasticity, so that the maxima are complied with. This will result in irreversible deformations. Output of bending moments and axial forces is given in the nodes, which requires extrapolation of the values at the stress points. Nodal forces are not checked against the maximum forces.

18.3 2D Geogrids

The PLAXIS program allows for orthotropic behaviour of geogrid elements, which is defined by the parameters EA_1 and EA_2. The stiffnesses are defined by the user and are based on the material tension stiffnesses (E_1, E_2) and the cross section areas (A_1, A_2) corresponding to the local axes of the geogrid. Geogrid elements cannot sustain compression forces.

The relationship between the force and the strain in axisymmetric models is defined as:

$$\begin{bmatrix} N \\ H \end{bmatrix} = \begin{bmatrix} EA_1 & 0 \\ 0 & EA_2 \end{bmatrix} \begin{bmatrix} \varepsilon \\ \varepsilon_H \end{bmatrix} \qquad \textit{Eq. [364]}$$

where H is the hoop force and ε_H is the hoop strain. For plane strain model H = 0.

When plasticity is considered, the maximum tensile forces can be defined:

$N_{p,1}$	The maximum force in 1-direction (in-plane).
$N_{p,2}$	The maximum force in 2-direction (out-of-plane, anisotropic behaviour).

A non-linear N- ε diagram may be specified in case of elastoplasticity:

N_1- eps_1	The N - ε diagram in 1-direction (in-plane).
N_2- eps_2	The N - ε diagram in 2-direction (out-of-plane, anisotropic behaviour).

A *Visco-elastic (time-dependent)* behaviour may be specified based on a visco-elastic perfectly-plastic Kelvin-Voigt model in each direction. Parameters which are required for time-dependent visco-elasticity are:

$EA_{1,short}$	Elastic stiffness during initial(instantaneous) strain increment in 1-direction (in-plane).
$EA_{2,short}$	Elastic stiffness during initial(instantaneous) strain increment in 2-direction (out-of-plane, anisotropic behaviour).
$EA_{1,long}$	Elastic stiffness during (infinitely) long strain increment in 1-direction (in-plane).

$EA_{2,long}$	Elastic stiffness during (infinitely) long strain increment in 1-direction (out-of-plane, anisotropic behaviour).
$N_{p,1}$	Maximum force in 1-direction (in-plane).
$N_{p,2}$	The maximum force in 2-direction (out-of-plane, anisotropic behaviour).
Retardation time	The time where a linear extrapolation of the initial creep rate intersects the long-term displacement line.

For more information about the determination of the parameters see the Reference Manual - Chapter 6 - *Material data sets for geogrids*.

18.4 3D Geogrids

The PLAXIS 3D program allows for orthotropic as well as anisotropic material behaviour in geogrid elements, which is defined by the following parameters:

$$\begin{aligned} N_1 &= EA_1\varepsilon_1 \\ N_2 &= EA_2\varepsilon_2 \\ Q_{12} &= GA_{Y12} \end{aligned} \qquad Eq.\ [365]$$

In the case of orthotropic behaviour $EA_1 = EA_2$ and $GA = \frac{1}{2}EA_1$ in the general three dimensional case.

When plasticity is considered, the maximum tensile forces can be defined:

$N_{p,1}$	Maximum tensile force in 1-direction.
$N_{p,2}$	Maximum tensile force in 2-direction.

A non-linear N- ε diagram may be specified in case of elastoplasticity:

N_1- eps_1	The N - ε diagram in 1-direction.
N_2- eps_2	The N - ε diagram in 2-direction.

Axial forces are calculated at the stress points of the geogrid elements. If N_p is exceeded, stresses are redistributed according to the theory of plasticity, so that the maximum forces are complied with. This will result in irreversible deformations. Output of axial forces is given in the nodes, which requires extrapolation of the values at the stress points. Nodal forces are not checked against the maximum forces. Hence, it is possible that the nodal values of the axial force may slightly exceed N_p.

A *Visco-elastic (time-dependent)* behaviour may be specified based on a visco-elastic perfectly-plastic Kelvin-Voigt model in each direction. Parameters which are required for time-dependent visco-elasticity are:

$EA_{1,short}$	Elastic stiffness during initial(instantaneous) strain increment in 1-direction.

$EA_{2,short}$	Elastic stiffness during initial(instantaneous) strain increment in 2-direction.
$EA_{1,long}$	Elastic stiffness during (infinitely) long strain increment in 1-direction.
$EA_{2,long}$	Elastic stiffness during (infinitely) long strain increment in 1-direction.
$N_{p,1}$	Maximum force in 1-direction (in-plane).
$N_{p,2}$	The maximum force in 2-direction.
Retardation time	The time where a linear extrapolation of the initial creep rate intersects the long-term displacement line.

For more information about the determination of the parameters see the Reference Manual - Chapter 6 - *Material data sets for geogrids*.

18.5 2D plates

The PLAXIS 2D program allows for orthotropic elasto-plastic material behaviour in plate elements. The elastic behaviour is defined by the following parameters:

EA_1	Axial stiffness.
EA_2	Stiffness in the out-of-plane direction.
EI	Bending stiffness
ν	Poisson's ratio

The material behaviour in plate elements is defined by the following relationship between strains and stresses.

$$\begin{bmatrix} \sigma_N \\ \Sigma_2 \\ \tau \end{bmatrix} = \begin{bmatrix} \frac{2G}{1-\nu} & \frac{2G\nu}{1-\nu} & 0 \\ \frac{2G}{1-\nu} & \frac{2G}{1-\nu} & 0 \\ 0 & 0 & kG \end{bmatrix} \begin{bmatrix} \varepsilon_N \\ \varepsilon_2 \\ \gamma \end{bmatrix} \qquad Eq.\ [366]$$

In which k is the shear correction factor, which is taken as $5/6$. For isotropic material:

$$G = \frac{E_1}{2(1+\nu)} \qquad Eq.\ [367]$$

For anisotropic plates, the following relationship between strains and stresses is used:

$$\begin{bmatrix} \sigma_N \\ \Sigma_2 \\ \tau \end{bmatrix} = \begin{bmatrix} E_1 & 0 & 0 \\ 0 & E_2 & 0 \\ 0 & 0 & kG \end{bmatrix} \begin{bmatrix} \varepsilon_N \\ \varepsilon_2 \\ \gamma \end{bmatrix} \qquad Eq.\ [368]$$

where $E_1=EA_1/d$ and $E_2=EA_2/d$. Note that the Poisson's ratio (ν) is assumed to be zero in anisotropic case.

The material behaviour in plate elements is defined by the following relationship between structural forces and strains:

$$N = EA_1\varepsilon \qquad Eq.\ [369]$$

$$H = EA_2\varepsilon_H \qquad Eq.\ [370]$$

$$Q = \frac{kEA}{2(1+\nu)}\gamma^* \qquad Eq.\ [371]$$

$$M = EI\kappa \qquad Eq.\ [372]$$

The modified shear strain γ^* takes into account the shear strain γ and some additional terms in order to give a more accurate approximation of the problem. k is the shear correction factor, which is taken as $5/6$. This implies that the shear stiffness is determined from the assumption that the plate has a rectangular cross section. In the case of modelling a solid wall, this will give the correct shear deformation. However, in the case of steel profile elements, like sheet-pile walls, the computed shear deformation may be too large. You can check this by judging the value of d_{eq}, which can be computed as $\sqrt{12EI / EA}$. For steel profile elements, d_{eq} should be at least of the order of a factor 10 times smaller than the length of the plate to ensure negligible shear deformations.

When plasticity is considered, the maximum bending moment and maximum normal force can be defined:

M_p	Maximum bending moment .
N_p	Maximum normal force.

The maximum bending moment is given in units of force times length per unit width. The maximum axial force, N_p, is specified in units of force per unit of width. When the combination of a bending moment and an axial force occurs in a plate, then the actual bending moment or axial force at which plasticity occurs is lower than respectively M_p or N_p. The relationship between M_p and N_p is visualised in Figure 108 (on page 232). The diamond shape represents the ultimate combination of forces for which plasticity will occur. Force combinations inside the diamond will result in elastic deformations only.

By default the maximum moment is set to $1 \cdot 10^{15}$ units if the material type is set to elastic (the default setting).

Bending moments and axial forces are calculated at the stress points of the beam elements. When yield function is violated, stresses are redistributed according to the theory of plasticity, so that the maxima are complied with. This will result in irreversible deformations. Output of bending moments and axial forces is given in the nodes, which requires extrapolation of the values at the stress points. Nodal forces are not checked against the maximum forces.

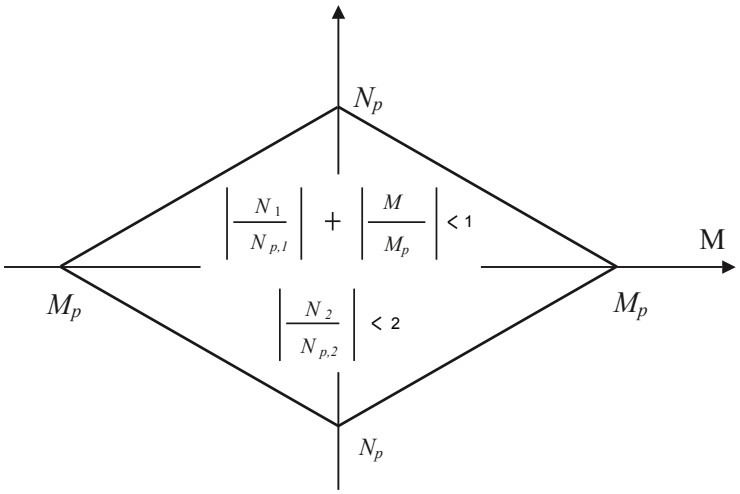


Figure 109: Combinations of maximum bending moment and axial force

When plasticity is defined employing an user-defined moment-curvature (M-κ) diagram, the bending behaviour of the plate is governed by the defined moment-curvature. The curvature, κ, is specified in the unit of length and the moment, M, in the unit of force times length per unit of width in the out-of-plane direction. The M-κ diagram is assumed to govern the plate's behaviour in both positive and negative loading directions.

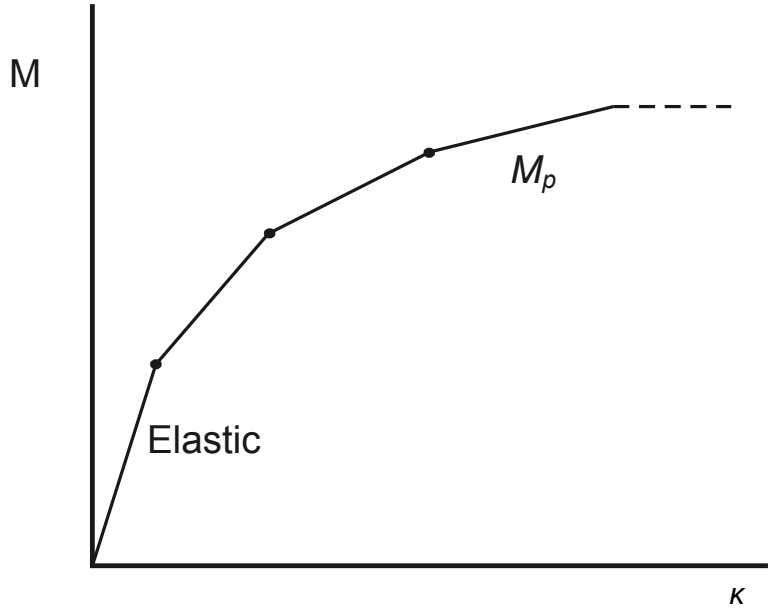


Figure 110: M-κ diagramκ diagram

The first segment in the M-κ diagram determines the plate's elastic bending stiffness EI:

$$EI = M(1) / \kappa(1) \qquad Eq.\ [373]$$

Additional segments in the M-κ diagram define the plate's non-linear elastoplastic behaviour. The last defined M-value is assumed to be the maximum bending moment, M_p, at which the plate fails. Elastic bending strains are calculated from the aforementioned EI value, whereas additional bending (following the defined M-κ diagram) is assumed to be plastic, as long as the loading is in the same direction. Upon unloading from an elastoplastic state, the behaviour is initially elastic, but after significant unloading it may again generate plastic strains.

In the elastoplastic (M-κ) plates, the axial force N is considered elastic and independent from the bending moment M. The axial force influences the stresses and displacements of the element but without affecting the bending moment. In the elastoplastic (M-κ) plates, the M-κ diagram is assumed to be the only one governing the plate's flexural behaviour.

18.6 3D Plates

The PLAXIS 3D program allows for orthotropic material behaviour in plate elements, which is defined by the following parameters:

E_1	Young's modulus in first axial direction.
E_2	Young's modulus in second axial direction.
G_{12}	In-plane shear modulus.
G_{13}	Out-of-plane shear modulus related to shear deformation over first direction.
G_{23}	Out-of-plane shear modulus related to shear deformation over second direction.
ν_{12}	Poisson's ratio ($\nu < \sqrt{E_1 / E_2}$).

The material behaviour in plate elements is defined by the following relationship between strains and stresses, which is based on the general three-dimensional continuum mechanics theory and the assumption that $\sigma_{33}=0$.

$$\begin{bmatrix} \varepsilon_{11} \\ \varepsilon_{22} \\ \gamma_{12} \\ \gamma_{13} \\ \gamma_{23} \end{bmatrix} = \begin{bmatrix} 1/E_1 & -\nu_1 2/E_1 & 0 & 0 & 0 \\ -\nu_{12}/E_1 & 1/E_2 & 0 & 0 & 0 \\ 0 & 0 & 1/G_{12} & 0 & 0 \\ 0 & 0 & 0 & 1/kG_{13} & 0 \\ 0 & 0 & 0 & 0 & 1/kG_{23} \end{bmatrix} \begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{12} \\ \sigma_{13} \\ \sigma_{23} \end{bmatrix} \qquad \textit{Eq. [374]}$$

In which k is the shear correction factor, which is taken as $5/6$. Inverting this relationship and ignoring the higher order terms in ν gives the following stress-strain relationship:

$$\begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{12} \\ \sigma_{13} \\ \sigma_{23} \end{bmatrix} = \begin{bmatrix} E_1 & \nu_{12}E_2 & 0 & 0 & 0 \\ \nu_{12}E_2 & E_2 & 0 & 0 & 0 \\ 0 & 0 & G_{12} & 0 & 0 \\ 0 & 0 & 0 & kG_{13} & 0 \\ 0 & 0 & 0 & 0 & kG_{23} \end{bmatrix} \begin{bmatrix} \varepsilon_{11} \\ \varepsilon_{22} \\ \gamma_{12} \\ \gamma_{13} \\ \gamma_{23} \end{bmatrix} \qquad \textit{Eq. [375]}$$

This approximation holds as long as the Poisson's ratio is small. These stress-strain relationships can be transformed into relationships for structural forces:

$$\begin{bmatrix} N_1 \\ N_2 \end{bmatrix} = \begin{bmatrix} E_1 d & \nu_{12} E_2 d \\ \nu_{12} E_2 d & E_2 d \end{bmatrix} \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \end{bmatrix} \qquad \textit{Eq. [376]}$$

$$\begin{bmatrix} Q_{12} \\ Q_{13} \\ Q_{23} \end{bmatrix} = \begin{bmatrix} G_{12} d & 0 & 0 \\ 0 & k G_{13} d & 0 \\ 0 & 0 & k G_{23} d \end{bmatrix} \begin{bmatrix} \gamma_{12} \\ \gamma_{13}^{*} \\ \gamma_{23}^{*} \end{bmatrix} \qquad \textit{Eq. [377]}$$

$$\begin{bmatrix} M_{11} \\ M_{22} \\ M_{12} \end{bmatrix} = \begin{bmatrix} \frac{E_1 d^3}{12} & \frac{\nu_{12} E_2 d^3}{12} & 0 \\ \frac{\nu_{12} E_2 d^3}{12} & \frac{E_2 d^3}{12} & 0 \\ 0 & 0 & \frac{G_{12} d^3}{12} \end{bmatrix} \begin{bmatrix} \kappa_{11} \\ \kappa_{22} \\ \kappa_{12} \end{bmatrix} \qquad \textit{Eq. [378]}$$

In which d is the thickness of the plate, which also determines the distributed weight of the plate together with the unit weight of the plate material: $\gamma \cdot d$. The modified shear strain γ^* takes into account the shear strain γ and some additional terms in order to give a more accurate approximation of the problem.

The local system of axes in a plate element is such that the first and the second local axis lie in the plane of the plate whereas the third axis is perpendicular to the plane of the plate (Figure 110 (on page 235)).

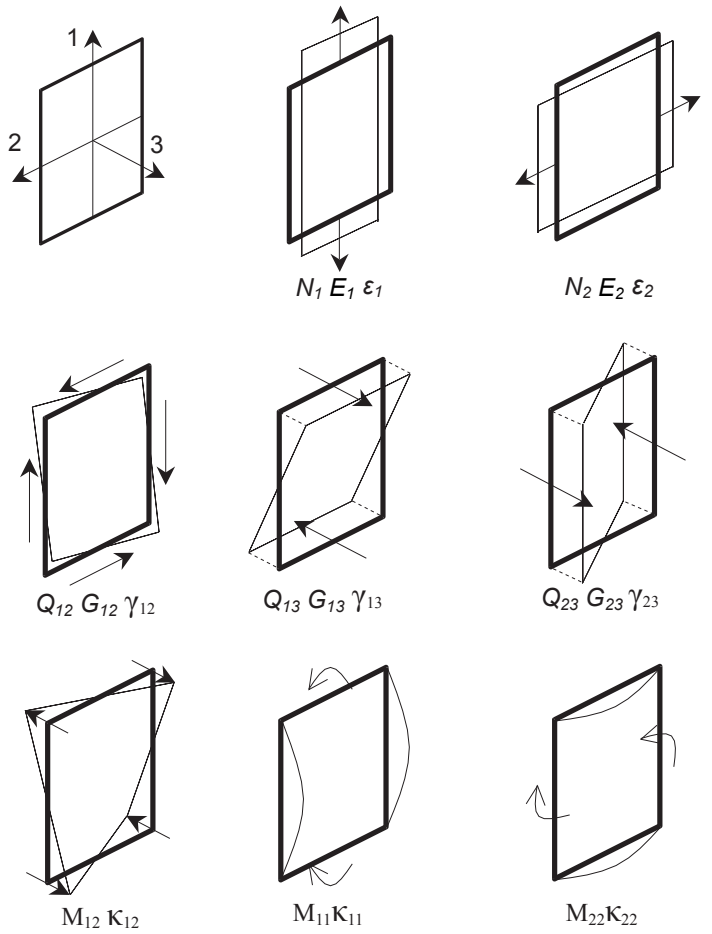


Figure 111: Definition of positive axial forces (N), shear forces (Q) and bending moments (M) for a plate based on local system of axes

When geometric orthotropy is considered rather than material orthotropy, the following relationships for structural forces apply:

$$\begin{bmatrix} N_1 \\ N_2 \end{bmatrix} = \begin{bmatrix} EA_1/(1-\nu^2) & \nu EA_1/(1-\nu^2) \\ \nu EA_1/(1-\nu^2) & EA_2/(1-\nu^2) \end{bmatrix} \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \end{bmatrix} \approx \begin{bmatrix} EA_1 & \nu EA_1 \\ \nu EA_1 & EA_2 \end{bmatrix} \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \end{bmatrix} \qquad \textit{Eq. [379]}$$

$$\begin{bmatrix} Q_{12} \\ Q_{13} \\ Q_{23} \end{bmatrix} = \begin{bmatrix} \frac{EA_{12}}{2(1+\nu)} & 0 & 0 \\ 0 & \frac{EA_{13}}{2(1+\nu)} & 0 \\ 0 & 0 & \frac{EA_{23}}{2(1+\nu)} \end{bmatrix} \begin{bmatrix} \gamma_{12} \\ \gamma^*_{13} \\ \gamma^*_{23} \end{bmatrix} \qquad \textit{Eq. [380]}$$

where the approximations hold for a small Poisson's ratio. In these relations the following alternative parameters are used:

A_1	Effective material cross section area for axial forces in the first direction.

A_2	Effective material cross section area for axial forces in the second direction.
A_{12}	Effective material cross section area for shear forces Q_{12}.
A_{13}	Effective material cross section area for shear forces Q_{13}.
A_{23}	Effective material cross section area for shear forces Q_{23}.
I_1	Moment of inertia against bending over the first axis.
I_2	Moment of inertia against bending over the second axis.
I_{12}	Moment of inertia against torsion.

In order to use the available plate elements for geometric orthotropy, the basic material parameters should be chosen in such a way that the resulting axial stiffness E_1A is equal to the axial stiffness EA_1 of the plate. Here E_1 is the input value for the Young's modulus in the first direction, A is the internally calculated area of the plate, E is the actual Young's modulus of the material and A_1 is the cross sectional area of the element to be modelled. Similar parameter choices should be made for the other axial stiffness, bending stiffness and shear stiffnesses. However, for a given choice of the equivalent plate thickness d it will not be possible to match all stiffness components exactly. The thickness d is the equivalent plate thickness such that the average distributed weight of the plate corresponds to $\gamma \cdot d$.

When bending is considered as the most important type of deformation, the following choices are recommended:

$$E_1 = 12EI_1 / d^3 \quad E_2 = 12EI_2 / d^3$$

$$G_{12} = \frac{6EI_{12}}{(1+\nu)d^3} \quad G_{13} = \frac{EA_{13}}{2(1+\nu)d} \quad G_{23} = \frac{EA_{23}}{2(1+\nu)d} \qquad \textit{Eq. [381]}$$

$$\nu_{12} = \nu$$

In this case the resulting bending stiffness $E_1d^3/12$ and $E_2d^3/12$ and shear stiffnesses $G_{13}d$ and $G_{23}d$ prove to be independent of the chosen value for equivalent plate thickness. Only the axial stiffnesses E_1A and E_2A and shear stiffness $G_{12}d$ are not independent of the chosen value of the equivalent plate thickness, and a suitable selection for d has to be made. What is the most suitable selection for d depends on the construction that is to be modelled. Two examples are given below.

When plasticity is considered, the maximum bending moment M_p and the maximum axial force N_p are calculated in the two axial directions (*1* and *2*) as:

$$N_{p,1,eq} = d \quad \sigma_{y,11,eq} \qquad \textit{Eq. [382]}$$

$$N_{p,2,eq} = d \quad \sigma_{y,22,eq} \qquad \textit{Eq. [383]}$$

$$M_{p,11} = W_{11} \quad \sigma_{y,11} \qquad \textit{Eq. [384]}$$

$$M_{p,22} = W_{22} \quad \sigma_{y,22} \qquad \textit{Eq. [385]}$$

where

$\sigma_{y,11,eq}$, $\sigma_{y,22,eq}$	=	Yield stresses.
W_{11},W_{22}	=	Plastic section moduli.
d	=	(Equivalent) Thickness.

In order to obtain the plastic axial forces $N_p$the equivalent stresses are calculated:

$$\sigma_{y,11,eq} = \sigma_{y,11}/\sqrt{3} \qquad Eq.\ [358]$$

$$\sigma_{y,22,eq} = \sigma_{y,22}/\sqrt{3}$$

The maximum bending moments are given in units of force times length per unit width. The maximum axial forces are computed in units of force per unit width. The yield surfaces are a diamond shape in the N_1 - M_{11} plane and in the N_2 - M_{22} plane. The two directions are treated separately. Force combinations inside the diamonds will result in elastic deformations only.

By default the maximum moment is set to $1 \cdot 10^{15}$ units if the material type is set to elastic (the default setting).

Bending moments and axial forces are calculated at the stress points of the beam elements. When yield function is violated, stresses are redistributed according to the theory of plasticity, so that the maxima are complied with. This will result in irreversible deformations. Output of bending moments and axial forces is given in the nodes, which requires extrapolation of the values at the stress points. Nodal forces are not checked against the maximum forces.

18.6.1 Engineering example:

In the following, two types of applications are given that frequently occur in the engineering practice. The first example is a sheet-pile wall, as depicted in Figure 111 (on page 237). From the sheet-pile manufacturer, the following properties are known: t (wall thickness), h (total height), A (per m wall width), I_1, E_{steel} and γ_{steel}.

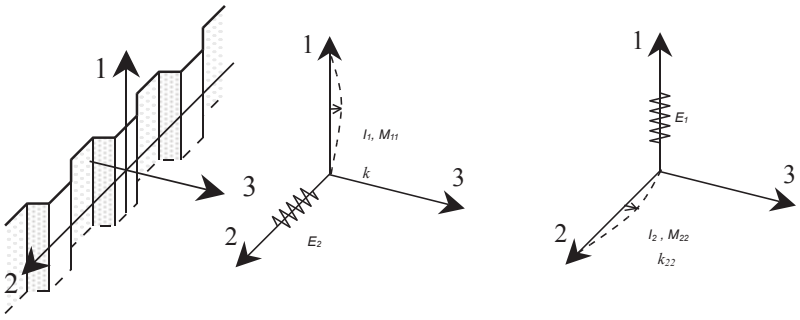


Figure 112: Example of sheet-pile wall with its major quantities

The structure is geometrically orthotropic with significant different stiffnesses in horizontal and vertical direction. It is known that the axial stiffness in vertical direction is larger than the effective stiffness in horizontal direction ($E_1 > E_2$). Moreover, the stiffness against bending over the vertical direction, I_1, is much larger than the stiffness against bending over the horizontal direction, I_2, ($I_1 >> I_2$ say $I_1 \approx 20\ I_2$ and $I_1 >> I_{12}$ say $I_1 \approx 10 I_{12}$). [3]

Furthermore, it is assumed that the cross section area that is effective against shear deformation over the vertical direction is about 1/3 of the total cross section area, whereas the area that is effective against shear deformation over the horizontal direction is about 1/10 of the total cross section area. Finally, the Poisson's ratio's for sheet pile walls can be assumed zero. With these assumptions, the situation could be modelled by selecting the model parameters in the following way:

$$d = h$$

[3] A factor of 20 is used here to move the bending stiffness over the first direction sufficiently small compared to the bending stiffness over the second direction, whilst the matrix condition is still OK. Note that in reality bending stiffness differences in order of 1000 may exist.

$$E_1 = 12E_{steel}I_1 / d^3$$

$$E_2 = 12E_{steel}{}^{I_2}/_{d^3} \approx {}^{I_2}/_{I_1}\mathrm{E}_1 \approx E_1 / 20$$

$$G_{12} = \frac{6E_{steel}I_{12}}{(1+\nu_{steel})d^3} \approx 6E_{steel}{}^{I_1}/_{10d^3}$$

$$G_{13} = \frac{E_{steel}A_{13}}{2(1+\nu_{steel})d} \approx E_{steel}(A/3) / 2d \approx E_{steel}A / 6d$$

$$G_{23} = \frac{E_{steel}A_{23}}{2(1+\nu_{steel})d} \approx E_{steel}(A/10) / 2d \approx E_{steel}A / 20d$$

$$\nu_{12} \approx 0$$

$$\gamma = A\gamma_{steel} / d$$

The second example is a concrete T-shaped floor profile, as depicted in Figure 111 (on page 237). In addition to the precise geometry dimensions, the following properties are known:

$E_{concrete}$, $\nu_{concrete}$

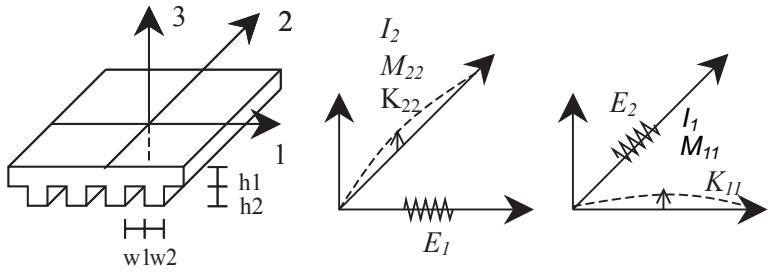


Figure 113: Example of concrete floor profile with its major quantities

The structure is again geometrically orthotropic with significant different stiffnesses in the two major floor directions. The flexural rigidity against bending over the second direction, I_2, is larger than the stiffness against bending over the first direction, I_1, ($I_2 > I_1$), since I_2 is dominated by $h_1 + h_2$ whereas I_1 only depends on h_1. Furthermore, the cross section area (per unit of width) that is effective against shear deformation over the second direction (G_{23}) is equal to the total cross section area A, whereas the area that is effective against shear deformation over the first direction (G_{13}) is equal to h_1. With these assumptions, the situation could be modelled by selecting the model parameters in the following way:

$$d = \frac{h_1 w_1 + (h_1 + h_2)w_2}{w_1 + w_2}$$

$$E_1 = 12E_{concrete}I_1 / d^3 = 12E_{concrete}\frac{1}{12}h_1^3 / d^3 = E_{concrete}h_1^3 / d^3$$

$$E_2 = 12E_{concrete}I_2 / d^3;\ where\ I_2 = \frac{\frac{1}{12}h_1^3 w_1 + \frac{1}{12}(h_1 + h_2)^3 w_2}{w_1 + w_2}$$

$$G_{12} = \frac{6E_{concrete}I_{12}}{(1+\nu_{concrete})d^3} where\ I_{12} \approx I_1 = \frac{1}{12}h_1^3$$

$$G_{13} = \frac{E_{concrete}A_{13}}{2(1+\nu_{concrete})d} = \frac{E_{concrete}h_1}{2(1+\nu_{concrete})d}$$

$$G_{23} = \frac{E_{concrete}A_{23}}{2(1+\nu_{concrete})d} = \frac{E_{concrete}d}{2(1+\nu_{concrete})d} = \frac{E_{concrete}}{2(1+\nu_{concrete})}$$

$$\nu_{12} = \nu_{concrete}$$

18.7 2D Embedded beam row

An embedded beam in PLAXIS 2Dconsists of plate elements with embedded interface elements to describe the interaction with the soil at the pile skin and at the pile foot (bearing capacity). The material parameters of the embedded beam distinguish between the parameters of the pile and the parameters of the skin resistance and foot resistance. The plate elements can have an elastic or an elastoplastic behaviour. In case plasticity can occur, the plate elements behave accordingly to a 2D plate (Figure 110 (on page 235)).

The elastic behaviour is defined by the following parameters:

E	Young's modulus in axial direction.
A	Pile cross section area.
I	Moment of inertia against bending around the pile axis.

The material behaviour in plate elements is defined by the following relationship between strains and stresses.

$$\begin{bmatrix}\sigma_N \\ \tau\end{bmatrix} = \begin{bmatrix}E & 0 \\ 0 & kG\end{bmatrix}\begin{bmatrix}\varepsilon_N \\ \gamma\end{bmatrix} \qquad Eq.\ [386]$$

where

σ_N = Normal stress
τ = Shear stress
G = Shear modulus $G = \frac{E}{2(1+\nu)}$
κ = Shear correction factor taken as *5/6*
ε_N = Normal strain

The material behaviour in plate elements is defined by the following relationship between structural forces and strains:

$$N = EA_1\varepsilon_N \qquad Eq.\ [387]$$

$$Q = \frac{kEA}{2(1+\nu)}\gamma^* \qquad Eq.\ [388]$$

$$M = EI\kappa \qquad Eq.\ [389]$$

The modified shear strain γ^* takes into account the shear strain γ and some additional terms in order to give a more accurate approximation of the problem.

The interaction of the pile with the soil at the skin of the pile is described by linear elastic behaviour with a finite strength and is defined by the following parameter:

T_{max}	Maximum traction allowed at the skin of the embedded beam (can vary along the pile)

Maximum traction allowed at the skin of the embedded beam (can vary along the pile)

The constitutive equation at the skin of the pile is defined by (see Figure 113 (on page 240)):

$$\begin{bmatrix} t_s \\ tm \end{bmatrix} = \begin{bmatrix} K_s & 0 \\ 0 & K_n \end{bmatrix} \begin{bmatrix} u_s^p - u_s^s \\ u_s^p - u_n^s \end{bmatrix} \qquad Eq.\ [390]$$

where

u^p = Displacement of the pile
u^s = Displacement of the soil
K_s = The elastic shear stiffness (against longitudinal (axial) displacement differences) of the embedded interface elements and K_n denotes the elastic axial stiffness (against transverse (lateral) displacement differences) of the embedded interface elements.

These values are calculated using the interface stiffness factors and the pile spacing defined by the user:

$$K_s = ISF_{RS} \frac{G_{soil}}{L_{spacing}}$$
$$K_n = ISF_{RN} \frac{G_{soil}}{L_{spacing}} \qquad Eq.\ [391]$$

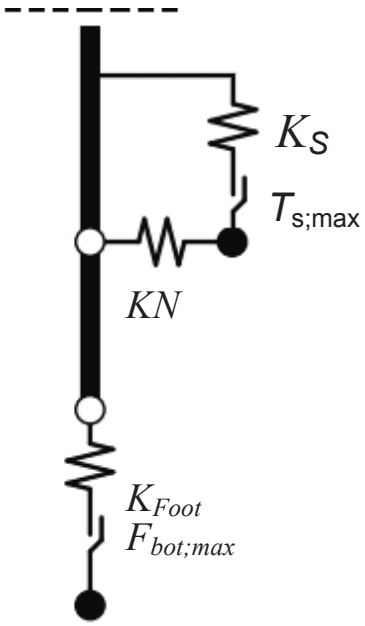


Figure 114: Stiffness of the embedded interface elements for piles

Default interface stiffness factors are calculated based on the pile spacing (Lspacing) in relation to the pile diameter (D_{eq}):

$$ISF_{RS} = 2.5\left(\frac{L_{spacing}}{D_{eq}}\right)^{-0.75} \qquad Eq.\ [392]$$

$$ISF_{RN} = 2.5\left(\frac{L_{spacing}}{D_{eq}}\right)^{-0.75} \qquad Eq.\ [393]$$

$$ISF_{KF} = 25\left(\frac{L_{spacing}}{D_{eq}}\right)^{-0.75} \qquad Eq.\ [394]$$

The normal stress t_n remains elastic if the *Lateral resistance* option is set to *Unlimited*. An elastoplastic behaviour is possible setting the *Lateral resistance* to *Linear* or *Multi-linear*.

For the shear stress in axial direction t_s to remain elastic it is given by:

$$|t_s| < T_{max} \qquad Eq.\ [395]$$

For plastic behaviour the shear force t_s is given by:

$$|t_s| = T_{max} \qquad Eq.\ [396]$$

The interaction of the pile with the soil at the foot of the pile is described by a linear elastic perfectly plastic interface element. The strength of the base is described by the following parameter:

F_{max}	Maximum force allowed at the foot of the embedded beam.

In addition, no tension forces are allowed. In order to ensure that a realistic pile bearing capacity as specified can actually be reached, a zone in the soil surrounding the pile foot is identified where any kind of soil plasticity is excluded (elastic zone; Figure 114 (on page 241)). The size of this zone is determined by the embedded beam's equivalent radius R_{eq} (Reference Manual).

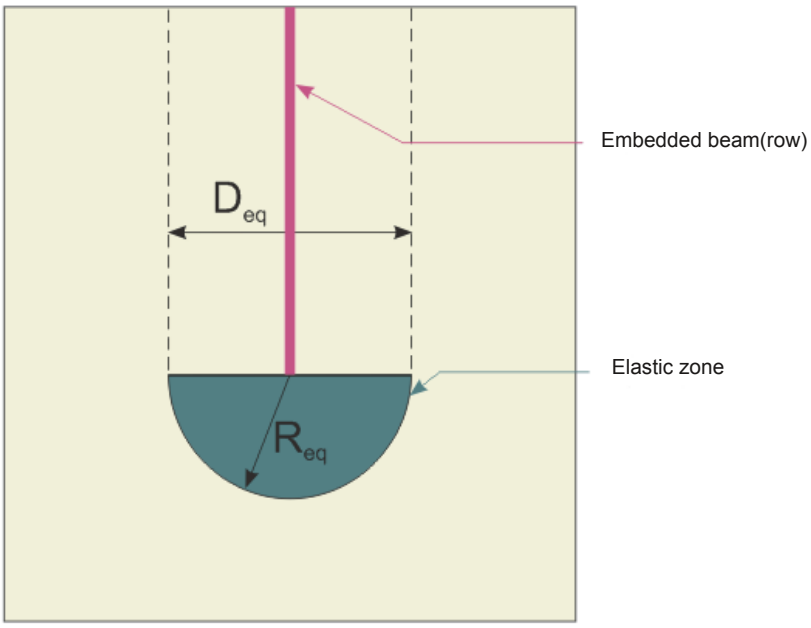


Figure 115: Elastic zone surrounding the bottom of the pile (after Sluis, 2012)

The constitutive relationship at the foot of the pile and its failure criterion are defined by:

$$F_{foot} = K_{foot}\left(u^{p}_{foot} - u^{s}_{foot}\right) < F_{max} \qquad Eq.\ [397]$$

where

K_{foot} = Stiffness of the spring which is defined in the same way as the stiffness of the embedded interface elements:

$$K_{foot} = ISF_{KF}\frac{G_{soil}R_{eq}}{L_{s}} \qquad Eq.\ [398]$$

In case of plastic behaviour, the foot force F_{foot} is given by:

$$F_{foot} = F_{max} \qquad Eq.\ [399]$$

18.8 3D Embedded beam (PLAXIS 3D)

An embedded beam in PLAXIS 3D consists of beam elements with embedded interface elements to describe the interaction with the soil at the pile skin and at the pile foot (bearing capacity). The material parameters of the embedded beam distinguish between the parameters of the beam and the parameters of the skin resistance and foot resistance. The beam elements can be linear elastic or elastoplastic. Their behaviour and material parameters are defined as a regular 3D beam element (3D Beams (on page 226)).

The interaction of the pile with the soil at the skin of the pile is described by linear elastic behaviour with a finite strength and is defined by the following parameter:

***T**max* Maximum traction allowed at the skin of the embedded beam (can vary along the pile)

The constitutive equation at the skin of the pile is defined by (see Figure 115 (on page 243)):

$$\begin{bmatrix} t_s \\ t_n \\ t_t \end{bmatrix} = \begin{bmatrix} K_s & 0 & 0 \\ 0 & K_n & 0 \\ 0 & 0 & K_t \end{bmatrix} \begin{bmatrix} u_s^{p} - u_s^{s} \\ u_s^{p} - u_n^{s} \\ u_s^{p} - u_t^{s} \end{bmatrix} \qquad Eq.\ [400]$$

where

u^p = Displacement of the pile
u^s = Displacement of the soil
K_s = The elastic shear stiffness (against parallel displacement differences) of the embedded interface elements
K_t = Elastic normal stiffness (against perpendicular displacement differences) of the embedded interface elements.

By default these values are defined such that the stiffness of the embedded interface elements does not influence the total elastic stiffness of the pile-soil structure:

$$K_s >> G_{soil}$$
$$K_n = K_t = \frac{2(1-\nu)}{1-2\nu}K_s \qquad Eq.\ [401]$$

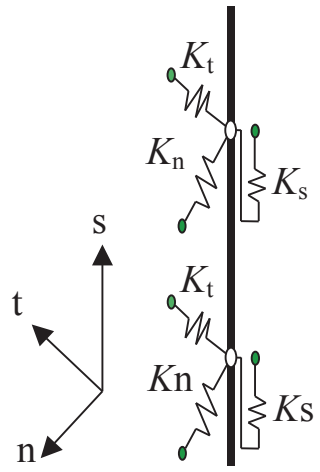


Figure 116: Stiffness of the embedded interface elements at the skin of the pile

The normal stresses t_n and t_t always remain elastic. The transverse forces are not limited in the special interface element that connects the pile with the soil but, in general, they are limited due to failure conditions in the surrounding soil itself outside the elastic zone.

For the shear stress in axial direction t_s, to remain elastic, it is given by:

$$|t_s| < T_{max} \qquad \textit{Eq. [402]}$$

For plastic behaviour the shear force t_s is given by:

$$|t_s| = T_{max} \qquad \textit{Eq. [403]}$$

In case of defining a layer dependent skin resistance the shear force t_s will remain elastic as long as:

$$|t_s| < \left(\sigma_n^{avg} \tan\varphi_i + c_i\right)\pi D_{eq} \quad \textit{and} \quad |t_s| < T_{max} \qquad \textit{Eq. [404]}$$

where

D_{eq} = Diameter or the equivalent diameter (in the case alternative beam properties have been specified) of the embedded beam($D_{eq} = 2\max\{\sqrt{(A/\pi)}, \sqrt{(2I_{avg}/A)}\}$) with $I_{avg} = (I_2+I_3)/2$)

σ_n^{avg} = Average lateral (perpendicular) stress of the soil around the pile:

$$\sigma_n^{avg} = \tfrac{1}{2}(\sigma_{xx} + \sigma_{yy}) \qquad \textit{Eq. [405]}$$

The parameters φ_i and c_i are the friction angle and cohesion of the embedded interface. The strength properties of embedded interfaces with layer dependent skin resistance are linked to the strength properties of a soil layer. Each data set has an associated strength reduction factor for interfaces R_{inter}. The embedded interface properties are calculated from the soil properties in the associated data set and the strength reduction factor by applying the following rules:

$$\tan\varphi_i = R_{inter}\tan\varphi_{soil}$$
$$c_i = R_{inter}c_{soil} \qquad \textit{Eq. [406]}$$

In the case of a layer dependent skin resistance where the actual bearing capacity is not known, T_{max} can be used as an ultimate cut-off value. The interaction of the pile with the soil at the foot of the pile is described by a linear elastic perfectly plastic interface element. The strength of the base is described by the following parameter:

For plastic behaviour t_s is given by:

$$|t_s| = \left(\sigma_n^{avg} \tan\varphi_i + c_i\right)\pi D \;;\; \textit{provided that } \left(\sigma_n^{avg} \tan\varphi_i + c_i\right)\pi D \le T_{max} \qquad \textit{Eq. [407]}$$

In the case of a layer dependent skin resistance where the actual bearing capacity is not known, T_{max} can be used as an ultimate cut-off value. The interaction of the pile with the soil at the foot of the pile is described by a linear elastic perfectly plastic interface element. The strength of the base is described by the following parameter:

F_{max}	Maximum force allowed at the foot of the embedded beam.

In addition, no tension forces are allowed. The constitutive relationship at the foot of the pile and its failure criterion are defined by (see Figure 115 (on page 243)):

$$F_{foot} = K_{foot}\left(u_{foot}^{p} - u_{foot}^{s}\right) < F_{max} \qquad \textit{Eq. [408]}$$

where

K_{foot} = Stiffness of the spring which is defined in the same way as the stiffness of the embedded interface elements:

$$K_{foot} > > G_{soil}$$

In case of plastic behaviour, the foot force F_{foot} is given by:

$$F_{foot} = F_{max} \qquad \textit{Eq. [409]}$$

In order to ensure that a realistic pile bearing capacity as specified can actually be reached, a zone in the soil volume elements surrounding the beam is identified where any kind of soil plasticity is excluded (elastic zone Figure 114 (on page 241)). The size of this zone is determined by the embedded beam's equivalent radius $R_{eq} = \max\left\{\sqrt{(A/\pi)},\ \sqrt{(2I_{avg}/A)}\right\}$ with $I_{avg} = (I_2+I_3)/2$. The elastic zone makes the embedded beam almost behave like a volume pile. However, installation effects of piles are not taken into account and the pile-soil interaction is modelled at the centre rather than at the circumference.

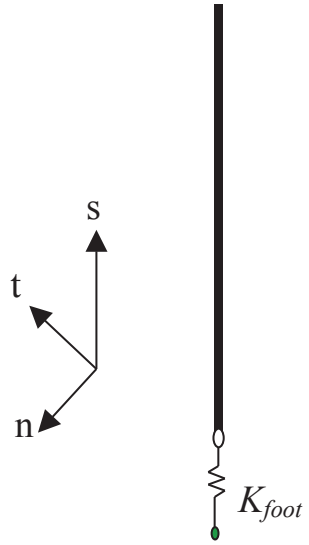


Figure 117: Stiffness of the embedded interface element at the foot of the pile

19 Hydraulic Models

19.1 Van Genuchten model

A Soil Water Characteristic Curve (SWCC) is introduced to describe hydraulic parameters of the groundwater flow in unsaturated zones (usually above the phreatic surface). The SWCC describes the capacity of the soil to keep water at different stresses. There are many models which describe the hydraulic behaviour of unsaturated soils. The most common in the groundwater literature is the model proposed by van Genuchten (1980) (on page 255), which is used in PLAXIS. The Van Genuchten function is a three-parameter equation and relates the saturation to the pressure head ψ:

$$S(\psi) = S_{res} + (S_{sat} - S_{res})\left[1 + (g_a |\psi|)^{g_n}\right]^{gc} \qquad \textit{Eq. [410]}$$

where

ψ = $\Psi = -\frac{p_w}{\gamma_w}$

p_w = Suction pore stress.

γ_w = Unit weight of the pore fluid.

S_{res} = A residual saturation which describes a part of the fluid that remains in the pores even at high suction heads.

S_{sat} = In general at saturated conditions the pores will not be completely filled with water as air can get trapped and the saturation in this situation, S_{sat}, will be less than one. However, the default is $S_{sat} = 1.0$

g_a = A fitting parameter which is related to the air entry value of the soil and has to be measured for a specific material. It is in the unit of *1/L* and is a positive value.

g_n = A fitting parameter which is a function of the rate of water extraction from the soil once the air entry value has been exceeded. This parameter has to be measured for a specific material.

g_c = A fitting parameter which is used in the general Van Genuchten equation. In PLAXIS the following assumption is made to convert the Van Genuchten to a two-parameter equation (Eq. [411]).

$$g_c = \left(\frac{1 - g_n}{g_n}\right) \qquad \textit{Eq. [411]}$$

The Van Genuchten relationship provides reasonable results for low and intermediate suctions. For very high suction values, saturation remains at the residual saturation.

Figure 117 (on page 246) and Figure 118 (on page 246) show the effect of the parameters g_a and g_n on the shape of the SWCC.

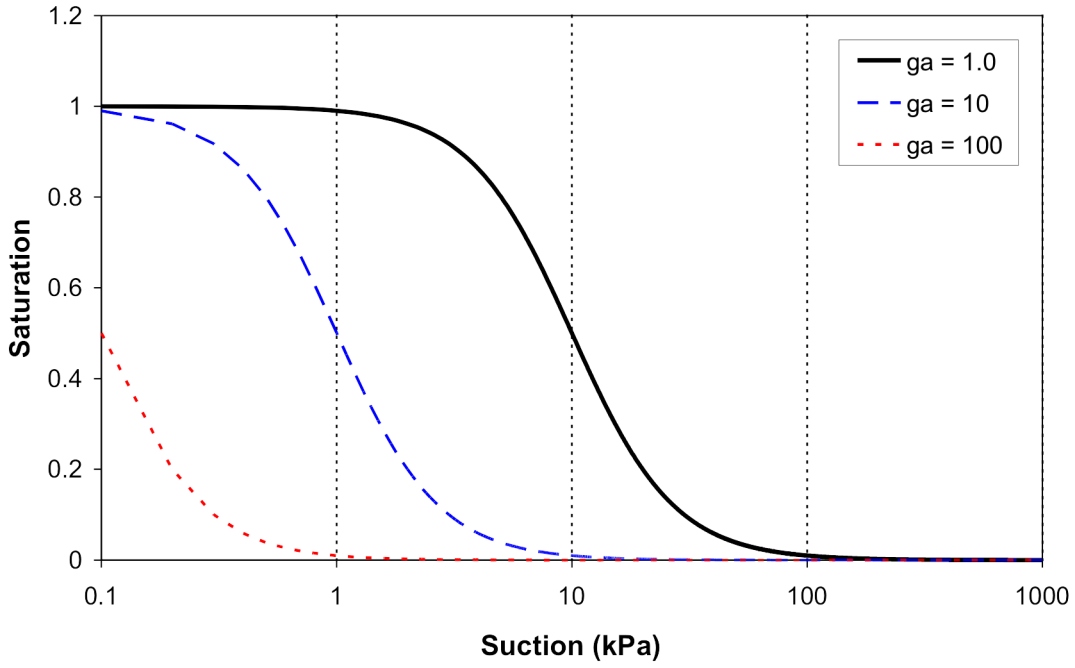


Figure 118: Effect of the parameter ga on the SWCCg_a on the SWCC

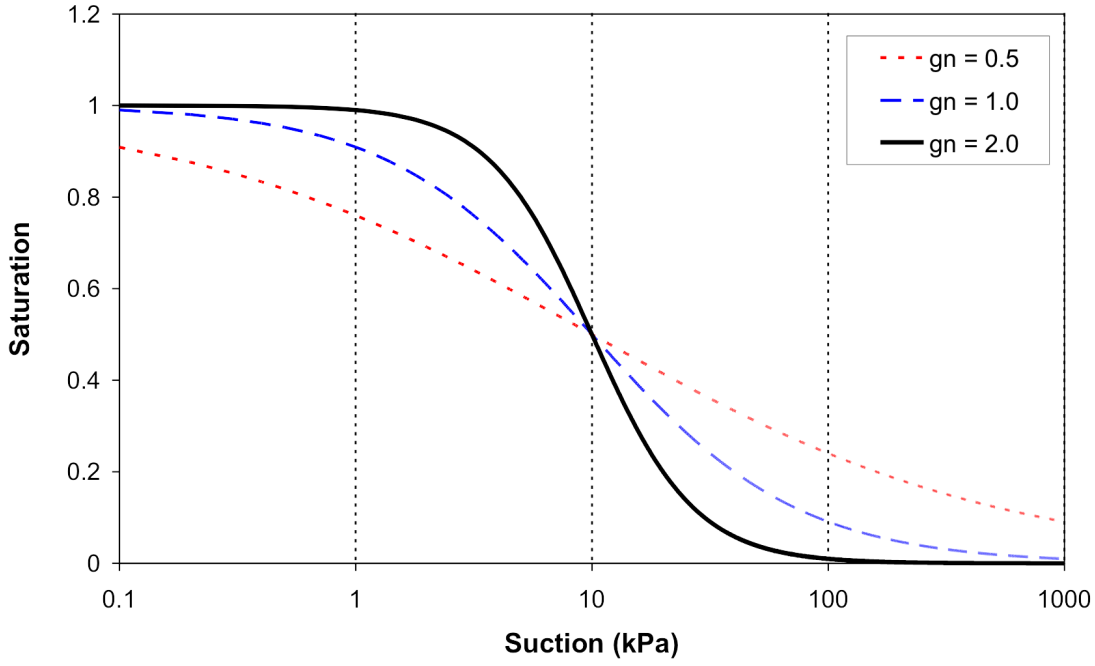


Figure 119: Effect of the parameter gn on the SWCCg_n on the SWCC

Relative permeability is related to the saturation via the effective saturation. The effective saturation S_{eff} is expressed as:

$$S_{eff} = \frac{S - S_{res}}{S_{sat} - S_{res}} \qquad Eq.\ [412]$$

The relative permeability according to Van Genuchten now reads:

$$k_{rel}(S) = max\left[(S_{eff})^{g_l} \left(1 - \left[1 - S_{eff}^{\left(\frac{g_n}{g_n - 1} \right)} \right]^{\left(\frac{g_n - 1}{g_n} \right)} \right)^2 , 10^{-4} \right] \qquad Eq.\ [413]$$

g_l is a fitting parameter and has to be measured for a specific material. Note that using the above expressions, the relative permeability can be related to the suction pore pressure directly.

The derivative of the degree of saturation with respect to the suction pore pressure reads:

$$\frac{\partial S(p_w)}{\partial p_w} = (S_{sat} - S_{res}) \left[\frac{1 - g_n}{g_n} \right] \left[g_n \left(\frac{g_a}{\gamma_w} \right)^{g_n} \cdot p_w^{(g_n - 1)} \right] \left[1 + \left(g_a \cdot \frac{p_w}{\gamma_w} \right)^{g_n} \right]^{\left(\frac{1 - 2g_n}{g_n} \right)} \qquad Eq.\ [414]$$

Figure 119 (on page 247) and Figure 120 (on page 248)present the Van Genuchten relations for a sandy material with parameters S_{sat}= *1.0*, S_{res} = *0.027*, g_a = *2.24*~m^{-1}, g_l = *0.0* and g_n = *2.286* graphically.

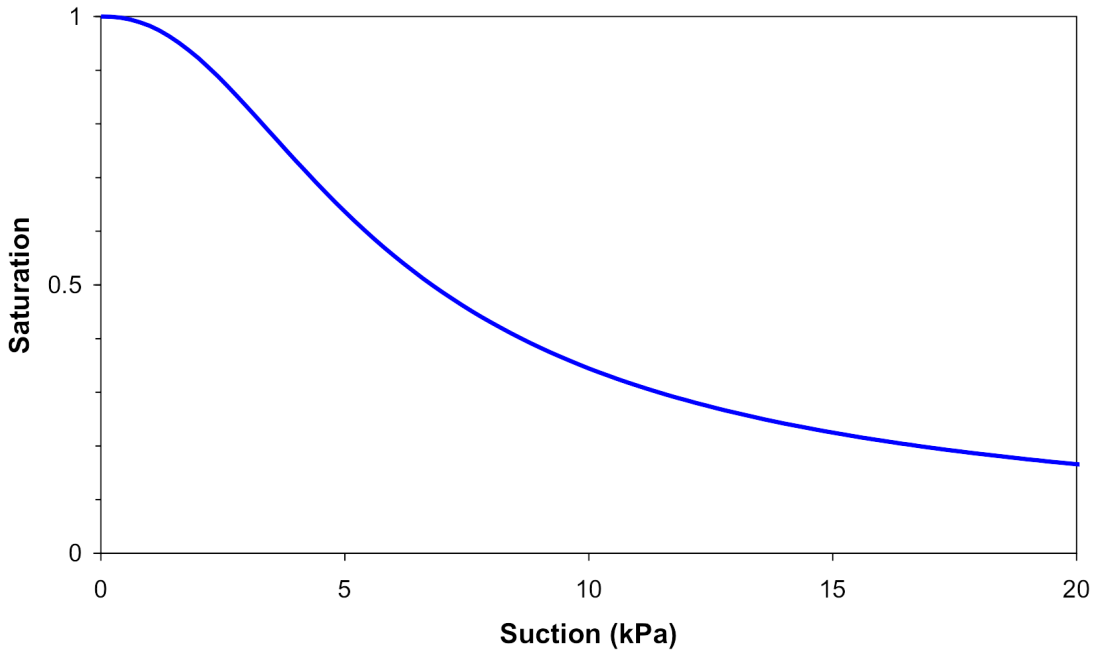


Figure 120: Van Genuchten pressure-relative permeability

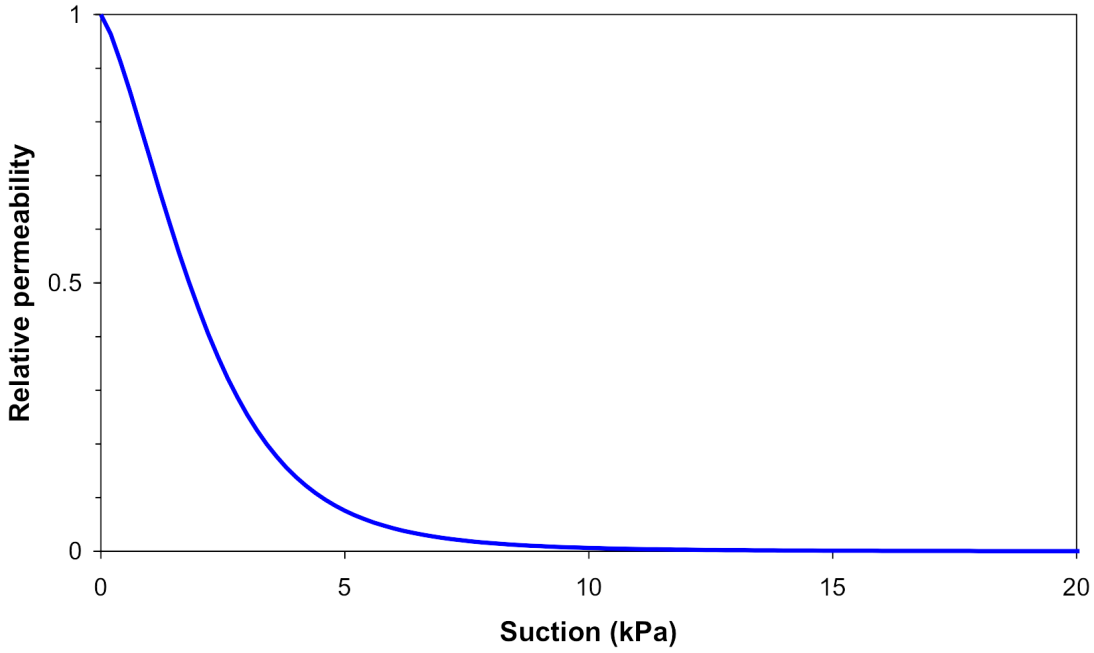


Figure 121: Approximate Van Genuchten pressure-relative permeability

19.2 Approximate Van Genuchten model

As an alternative, the PlaxFlow program supports a linearised Van Genuchten model for which the approximate Van Genuchten parameters can be derived. According to this concept saturation relates to the pore pressure head as:

$$S(\psi) = \begin{cases} 1 & if\ \psi \geq 0 \\ 1 + \dfrac{\psi}{|\psi_k|} & if\ \psi_k < \psi < 0 \\ 0 & if\ \psi \leq \psi_k \end{cases} \qquad Eq.\ [415]$$

The variable ψ_k is a material dependent pressure head which specifies the extent of the unsaturated zone under hydrostatic conditions. Below this threshold value the saturation is assumed to be zero. For saturated conditions the degree of saturation equals one. The relation between relative permeability and pressure head is written as:

$$K_{rel(\psi)} = \begin{cases} 1 & if\ \psi \geq 0 \\ 10^{\dfrac{4\psi}{|\psi_s|}} & if\ \psi_s < \psi < 0 \\ 10^{-4} & if\ \psi \leq \psi_s \end{cases} \qquad Eq.\ [416]$$

According to this formulation the permeability in the transition zone is described as a log-linear relation of pressure head where ψ_s is the pressure head at which the relative permeability is reduced to 10^{-4}. The permeability remains constant for higher values of the pressure head. Under saturated conditions the relative

permeability equals one and the effective permeability is equal to the saturated permeability which is assumed to be constant.

The input parameters of the "approximate Van Genuchten model'' are derived from the classical Van Genuchten model. These parameters are translated into approximately equivalent process parameters for the numerically more robust linearised model. For ψ_k the translation is as follows:

$$\Psi_k = \frac{1}{S_{\psi=-1.0\ \mathrm{m}} - S_{sat}} \qquad \textit{Eq. [417]}$$

The parameter ψ_s is set equal to the pressure head at which the relative permeability according to Van Genuchten is 10^{-2}, with a lower limit of -0.5~m. Figure 121 (on page 249) presents the functional relation between pressure and saturation according to the approximate Van Genuchten model using $\psi_k = 1.48$ m. The corresponding pressure-relative saturation relation $\psi_s = 1.15$ m is given in Figure 120 (on page 248).

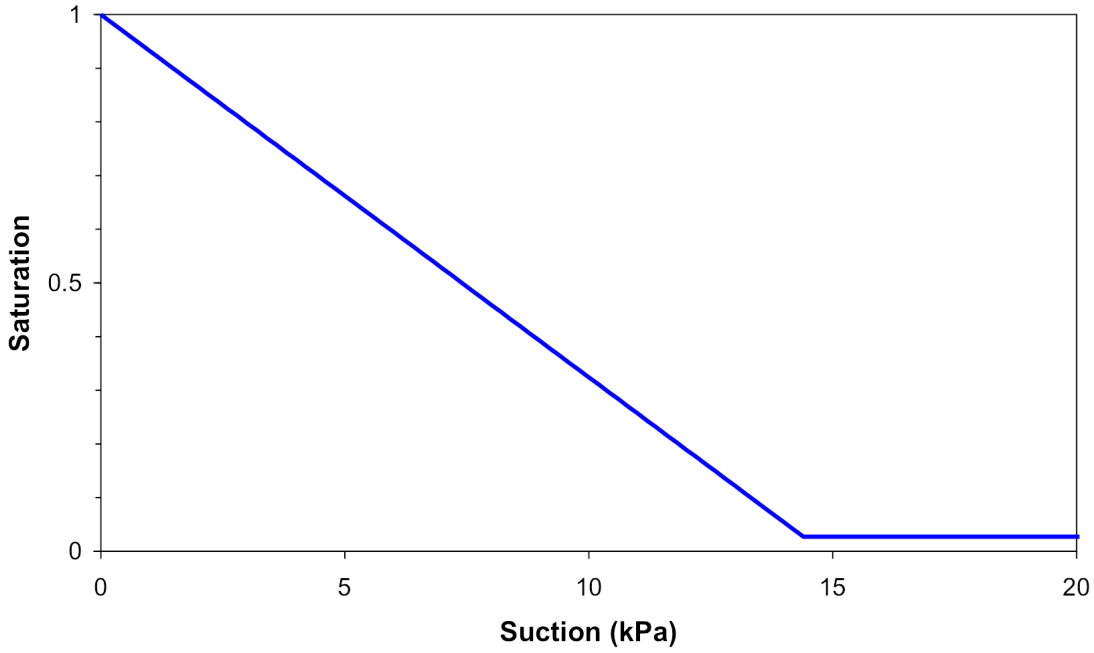


Figure 122: Approximate Van Genuchten pressure-saturation

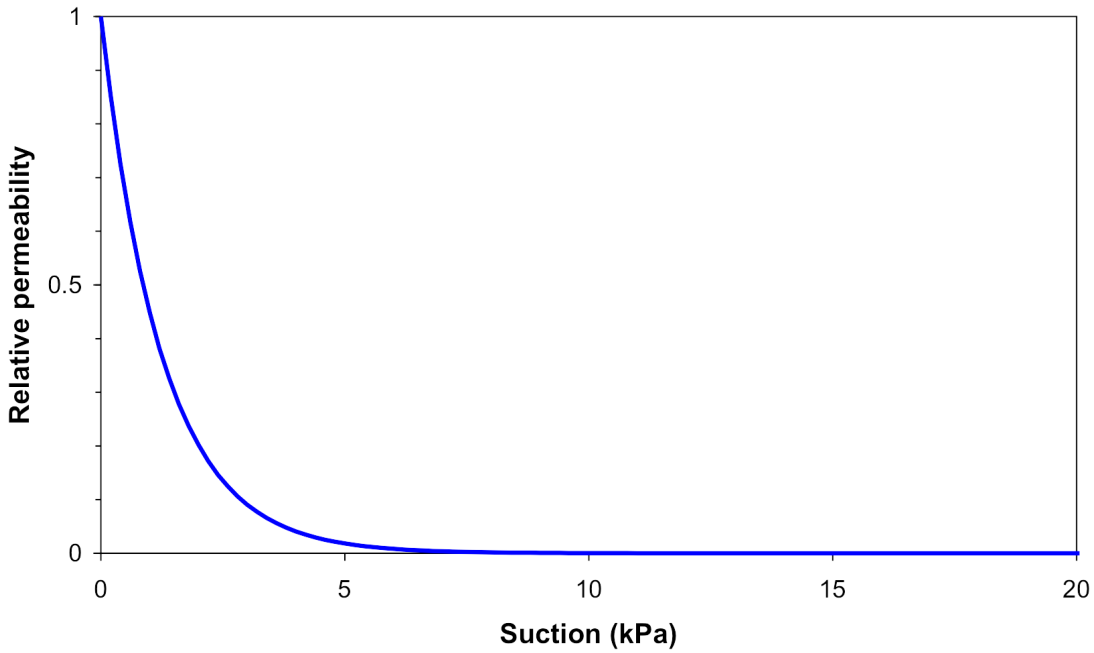


Figure 123: Approximate Van Genuchten pressure-relative permeability

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Appendices

A Symbols

General Symbols	Name
A	Cross section area
c	Cohesion
csp	Current stiffness parameter
C	Correction factor for SPT value
C_α	Creep index for secondary compression
C_c	Compression index
C_r	Ricompression index
C_s	Swelling index
C_u , S_u	Undrained shear-strength
d	Thickness
D	Disturbance factor
$\mathbf{D}^e$	Elastic material matrix representing Hooke's law
e	Void ratio
E	Young's modulus
E_{oed}	Oedometer modulus
f	Yield function
f_{dens}	Densification factor
f_{Epost}	Post-liquefaction factor
g	Plastic potential function

Symbols

General Symbols	Name
G	Shear modulus
GSI	Geological Strength Index
G_{ur}	Unloading/reloading shear modulus
I	Moment of inertia
$k^{*e}{}_B$	Elastic bulk modulus factor
$k^{*e}{}_G$	Elastic shear modulus factor
$k^{*p}{}_G$	Plastic shear modulus factor
$k^{*p}{}_{G,secondary}$	Secondary plastic shear modulus factor
K	Bulk modulus
K_0	Coefficient of lateral earth pressure (initial stress state)
K_0^{nc}	Coefficient of lateral earth pressure for a normally consolidated stress state
me	Power in stress-dependent relation for elastic bulk modulus
m_i	Intact rock parameter
ne	Power in stress-dependent relation for elastic shear modulus
np	Power in stress-dependent relation for plastic shear modulus
M	Slope of critical state line in p'-q space
M	Bending moment
n_{rev}	Number of shear stress reversals
N	Normal force
$N_{1,60}$	Corrected SPT value
OCR	overconsolidation ratio
p	Isotropic stress or mean stress, negative for pressure; positive for tension
p_w	Pore pressure
p_p	Isotropic pre-consolidation stress, negative for pressure
POP	Pre overburden pressure, positive for (over)pressure

Symbols

General Symbols	Name
q	Equivalent shear stress or deviatoric stress
Q	Shear force
R_f	Failure ratio
$r_{u,\sigma'v}$	Excess pore pressure ratio in terms of vertical effective stresses
$r_{u,p'}$	Excess pore pressure ratio in terms of mean effective stresses
RD	Relative density
$s^a{}_u$	Undrained active shear strength
$s^{c,TX}{}_u$	Undrained triaxial compressive shear strength
$s^{DSS}{}_u$	Undrained direct simple shear strength
$s^p{}_u$	Undrained passive shear strength
t	Time
$\underline{u}$	Vector with displacement components
γ	Unit weight
γ	Various types of shear strain
α_1	dip angle
α_2	dip direction
Δ	Increment
$\underline{\varepsilon}$	Vector with Cartesian strain components, normal components positive for extension; negative for compression
ε_q	Deviatoric strain (invariant)
ε_v	Volumetric strain, negative for compression; positive for extension
κ	Cam-Clay swelling index
κ^*	Modified swelling index
λ	Plastic multiplier
λ	Cam-Clay compression index
λ^*	Modified compression index

Symbols

General Symbols	Name
μ^*	Modified creep index
ν	Poisson's ratio
$\underline{\sigma}$	Vector with Cartesian stress components, normal components positive for tension; negative for pressure
σ_ψ	Confining pressure at which $\psi = 0$
σ_{ci}	Uni-axial compressive strength
σ_p	Vertical pre-consolidation stress, negative for pressure
φ	Friction angle
φ_{cv}	Costant volume friction angle
φ_{mob}	Mobilised friction angle
φ_p	Peak friction angle
ψ	Dilatancy angle
ψ_m	Mobilised dilatancy angle
ψ_{max}	Maximum dilatancy angle
$\times^c$	Denotes creep component
$\times^e$	Denotes elastic component
$\times^p$	Denotes plastic component
$\times^{ref}$	Denotes reference value (related to a reference stress)
$\times_u$	Denotes undrained
$\times_{ur}$	Denotes unloading and reloading
$\times_m$	Denotes mobilised

Concrete model symbols	Name
a	Increase of ε_{cp} with increase of p
f	Yield stress
f_{xxn}	Normalised strength
F	Yield function

Symbols

Concrete model symbols	Name
G	Fracture energy
H	Normalised hardening/softening
J	Shotcrete strength class
k_σ	Degree of concrete utilisation in compression
L_{eq}	Characteristic length of the finite element
s	Power in time-dependent strength/stiffness relations
t_{hydr}	Time of full curing
γ_{fx}	Safety factor for strength
φ_{cr}	Creep factor
φ_{max}	Maximum friction angle
ψ	Dilatancy angle
$\times^{cr}$	denotes creep
$\times^{shr}$	denotes shrinkage
$\times_{\infty}$	Denotes a time $t = \infty$
$\times_{28}$	Denotes a value of cured concrete
$\times_{50}$	Denotes a time t when 50% of the phenomenon has occurred
$\times_{cp}$	Denotes peak in uniaxial compression
$\times_{xf}$	Denotes a uniaxial failure value

B

Applicability of the material model

In this appendix, an overview of the applicability of the material models is given.

Considering different materials:

Model	Concrete	Rock	Gravel	Sand	Silt	OC clay	NC clay	Peat(org)
Linear Elastic Model	C	C						
Mohr-Coulomb model	B	B	C	C	C	C	C	C
Hardening soil model			B	B	B	B	B	
HS small model			A	A	A	A	B	
UBC3D-PLM model			B*	B*	B*			
Soft Soil creep model							A*	A*
Soft soil model							A*	A*
Jointed rock model		A**						
Modified Cam-Clay model							C	C
NGI-ADP model						A*	A*	A*

Applicability of the material model

Model	Concrete	Rock	Gravel	Sand	Silt	OC clay	NC clay	Peat(org)
UDCAM-S model						A*	A*	A*
Hoek-Brown model		A**						
Concrete model	A							

A : The best standard model in PLAXIS for this application

B : Reasonable modelling

C : First order (crude) approximation

* : Soft Soil Creep model in case time-dependent behaviour is important; UBC3D-PLM model for dynamic analysis of sandy soils involving liquefaction

* : NGI-ADP model for short-term analysis and UDCAM-S model for cyclic analysis, in case only undrained strength is known

** : Jointed Rock model in case of anisotropy and stratification; Hoek-Brown model for rock in general

Considering different types of applications(consider also type of soil!)

Model	Foundation	Excavation	Tunnel	Embankment	Slope	Dam	Offshore	Other
Linear Elastic model	C		C					
Mohr-Coulomb model	C	C	C	C	C	C	C	C
Hardening Soil model	B	B	B	B	B	B	B	B
HS small model	A	A	A	A	A	A	A	A
UBC3D-PLM model*	B	B	B	B	B	B	B	B

Applicability of the material model

Model	Foundation	Excavation	Tunnel	Embankment	Slope	Dam	Offshore	Other
Soft Soil Creep model	B	B	B	A	A	B	B	B
Soft Soil model	B	B	B	A	A	B	B	B
Jointed Rock model	B	B	B	B	B	B	B	B
Modified Cam-Clay model	C	C	C	C	C	C	C	C
NGI-ADP model	B	B	B	A	A	B	A	B
UDCAM-S model*							A	
Hoek-Brown model	B	B	B	B	B	B	B	B
Concrete model	A	A	A	A	A	A	A	A

A : The best standard model in PLAXIS for this application

B : Reasonable modelling

C : First order (crude) approximation

* : UDCAM-S model for cyclic analysis, in case only undrained strength is known; UBC3D-PLM model for dynamic analysis of sandy soils involving undrained cyclic loading

* : As an alternative PM4Sand is available as a user-defined soil model under GSE

Considering different types of loading and soils (consider also type of soil!):

Applicability of the material model

Model	Primary compression	Unloading / Reloading	Shear / Deviatoric loading	Undrained loading	Cyclic	Compression + Shear	Extension + Shear
Linear Elastic model	C	C					
Mohr-Coulomb model	C	B	C	C		C	C
Hardening Soil model	A	B	B	B	C	A	A
HS small model	A	A	A	B	B	A	A
UBC3D-PLM model*	B	B	B	B	B	B	B
Soft Soil Creep model	A	B	B	B	C	A	B
Soft Soil model	A	B	B	B	C	A	B
Jointed Rock model	B	B	B			B	B
Modified Cam-Clay model	C	C	C	C	C	C	C
NGI_ADP model	B	B	B	A	C	B	B
UDCAM-S model*	B	B	B	A	A*	A	B
Hoek-Brown model	B	B	B			B	B
Concrete model**	A	A	A		C	A	A
A : The best standard model in PLAXIS for this application							
B : Reasonable modelling							

Applicability of the material model

Model	Primary compression	Unloading / Reloading	Shear / Deviatoric loading	Undrained loading	Cyclic	Compression + Shear	Extension + Shear
C : First order (crude) approximation							
* : UDCAM-S model for cyclic analysis, in case only undrained strength is known; UBC3D-PLM model for dynamic analysis of sandy soils involving undrained cyclic loading							
* : As an alternative PM4Sand is available as a user-defined soil model upon request							

C

Modelling of embedded structures

In this appendix, an overview of the applicability of the different modelling techniques for embedded structures is given. In addition to displacement differences and shear forces in axial direction, the embedded structures can undergo transverse forces due to lateral displacements. The lateral displacements can be induced by a transverse force applied at the top of the pile (*Pile head loading*) or as a consequence of the transverse distributed load induced by the lateral displacement field of the surrounding soil (*Horizontal soil displacement*).

PLAXIS 2D	**Axial behaviour**			**Lateral behaviour Pile head loading**		**Lateral behaviour Lateral soil movement**	
Approach	**Wall behaviour**	**Pile row**	**Single pile**	**Pile row**	**Single pile**	**Pile row**	**Single Pile**
Volume elements	B	C	-	-	-	-	-
Plate	A	C	-	B	-	C	-
Node to node anchor	-	C	-	-	-	-	-
Embedded beam row	-	B	C	B	-	B	-

PLAXIS 3D	**Axial behaviour**			**Lateral behaviour Pile head loading**		**Lateral behaviour Lateral soil movement**	
Approach	**Wall behaviour**	**Pile row**	**Single pile**	**Pile row**	**Single pile**	**Pile row**	**Single Pile**
Volume elements	A	A	A	A	A	A	A
Plate	A	C	-	-	-	-	-
Node to node anchor	-	C	-	-	-	-	-
Embedded beam	-	B	C	C	C	B	B

A : The best modelling choice for the correspondent application

B : Reasonable modelling

C : First order (crude) approximation

- : Not recommended

D

Fortran subroutines for User-defined soil models

D.1 Subroutines

In this appendix, a listing is given of the subroutines and functions which are provided by PLAXIS in libraries and source code in the User-defined soil model directory. These can be called by the `User_Mod` subroutine:

Subroutine	Description
`MZeroR( R , K )`	To initialize `K` terms of double array `R` to zero.
`MZeroI( I, K )`	To initialize `K` terms of integer array `I` to zero.
`SetRVal( R, K, V )`	To initialize `K` terms of double array `R` to `V`.
`SetIVal( I, K, IV )`	To initialize `K` terms of integer array `I` to `IV`.
`CopyIVec( I1, I2, K )`	To copy `K` values from integer array `I1` to `I2`.
`CopyRVec( R1, R2, K )`	To copy `K` values from double array `R1` to `R2`.
`MulVec( V, F, n )`	To multiply a vector `V` by a factor `F, n` values.
`MatVec( xMat, im, Vec, n, VecR )`	• Matrix (`xMat`)-vector(`Vec`) operation. • First dimension of matrix is `im`; resulting vector is `VecR`.
`AddVec( Vec1, Vec2, R1, R2, n, VecR )`	To add n terms of two vectors; result in `VecR` • `VecRi` = `R1 · Vec1i + R2 · Vec2i`
`MatMat( xMat1, id1, xMat2, id2, nR1,nC2, nC1, xMatR, idR)`	• Matrix multiplication xMatRij = $\texttt{xMat1}_{ik} \cdot \texttt{xMat2}_{kj}$ • `id1`,`id2`, `idR`: first dimension of matrices • `nR1` number of rows in `xMat1` and resulting `xMatR` • `nC2` number of column in `xMat2` and resulting xMatR • `nC1` number of columns in `xMat2` =rows in `xMat2`

Subroutine	Description
`MatMatSq( n, xMat1, xMat2, xMatR )`	• Matrix multiplication xMatRij = $\texttt{xMat1}_{ik} \cdot \texttt{xMat2}_{kj}$ • Fully filled square matrices with dimensions `n`
`MatInvPiv( AOrig, B, n )`	Matrix inversion of square matrices `AOrig` and `B` with dimensions n. • `AOrig` is NOT destroyed, `B` contains inverse matrix of `AOrig.` • Row-pivoting is used.
`WriVal( io, C, V )`	To write a double value `V` to file unit `io` (when `io` > 0). • The value is preceded by the character string `C`.
`WriIVl( io, C, I )`	• As `WriVal` but for integer value `I`.
`WriVec( io, C, V, n )`	• As `WriVal` but for `n` values of double array `V`.
`WriIVc( io, C, iV, n )`	• As `WriVal` but for n values of integer array `iV`
`WriMat( io, C, V, nd, nr, nc )`	• As `WriVal` but for double matrix `V`. nd is first dimension of `V`, `nr` and `nc` are the number of rows and columns to print respectively.
`PrnSig( iOpt, S, xN1, xN2, xN3, S1, S2, S3, P, Q )`	To determine principal stresses and (for `iOpt`=1) principal directions. • `iOpt` = 0 to obtain principal stresses without directions. • `iOpt` = 1 to obtain principal stresses and directions. • `S` array containing 6 stress components (XX, YY, ZZ, XY, YZ, ZX). • `xN1`, xN2, xN3 array containing 3 values of principal normalised directions only when iOpt=1. • S1, S2, S3 sorted principal stresses ($S1 \leq S2 \leq S3$) • `P` isotropic stress (negative for compression). • `Q` deviatoric stress.
`CarSig( S1, S2, S3, xN1, xN2, xN3, SNew )`	To calculate Cartesian stresses from principal stresses and principal directions. • `S1`, `S2`, `S3` principal stresses. • `xN1`, `xN2`, `xN3` arrays containing principal directions (from `PrnSig`). • `SNew` contains 6 stress components (XX, YY, ZZ, XY, YZ, ZX).
`CrossProd( xN1, xN2, xN3 )`	Cross product of vectors `xN1` and `xN2`

Subroutine	Description
`SetVecLen( xN, n, xL )`	To multiply the `n` components of vector `xN` such that the length of `xN` becomes `xL` (for example to normalize vector `xN` to unit length).

D.2 Functions

Functions	Description
`Logical Function LEqual( A, B, Eps )`	Returns TRUE when two values A and B are almost equal, FALSE otherwise. • `LEqual` = $\mid A - B \mid < Eps * (\mid A \mid + \mid B \mid + Eps) / 2$
`Logical Function Is0Arr( A, n )`	Returns TRUE when all `n` values of real (double) array `A` are zero, FALSE otherwise.
`Logical Function Is0IArr( IArr, n )`	Returns TRUE when all `n` values of integer array `IArr` are zero, FALSE otherwise.
`Double Precision Function DInProd( A, B, n )`	Returns the dot product of two vectors with length `n`